



ESA-MOST China Dragon 4 Cooperation

→ ADVANCED TRAINING COURSE IN OCEAN AND COASTAL REMOTE SENSING

12 to 17 November 2018 | Shenzhen University | P.R. China

Principles of SAR altimetry & The ESA GPOD SARvatore on-line and on-demand processing service for the advanced exploitation of Sentinel-3 and CryoSat-2



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Principles of SAR altimetry



Limits of LRM Altimetry



• Conventional altimeters discussed so far use returns from the pulse limited footprint (forming the leading edge) to estimate the minimum radar range at nadir.

- A radar altimeter is pulse limited when the tx signal duration is short enough that the entire target within the antenna beam is not simultaneously illuminated.
- The mean return pulse is mainly the convolution of the radar system point target response (PTR), the sea surface height distribution (typically Gaussian) and the antenna pattern.
- By looking at the **trailing edge**, it is clear that echoes from scatterers located outside the pulse limited footprint appear at a relative greater delay.

 Therefore, a significant amount of power is wasted in receiving echoes that cannot be used for range estimation.
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Limits of LRM Altimetry (1)



As an example, (Raney, 1998) indicated that for GEOSAT the pulse limited footprint (from which the leading edge is created) was less than 1/10 of the antenna pattern when a quasi-flat surface was considered.

 Another disadvantage of LRM altimetry is the increase in footprint dimension as the surface become rougher (SWH>>) leading to a degraded estimation of range and SWH.





Limits of LRM Altimetry (2)





Why SAR Altimetry?



Starting from these limitations, the Delay/Doppler processing (*Raney*, *1998*) aims at:

1) Better exploiting the transmitted energy by <u>using the entire beam-</u> <u>limited along-track signal history</u> instead of only the small pulse limited footprint.

2) Using the Doppler selectivity to decrease the extension of the footprint in <u>along-track</u> limiting also the influence of an increasing SWH.

A Doppler shift f in the frequency of the received signal is present anytime the sensor and the scatterer are moving with respect to each other:

$$f = \frac{2|\vec{v}|\cos\theta_n}{\lambda}$$

where \vec{V} is the velocity vector, λ is the wavelength and θ_n is the angle between the the sensor and the surface scatterer. The Doppler shift is null when the scatterer is observed at nadir as no relative movement exists





Transmission Scheme



• To be performed, this processing requires a different transmission scheme in comparison to LRM altimeters:



• No single pulses but **bursts of pulses are transmitted** guaranteeing, through a higher PRF (~18*Khz*), the **coherent correlation** among pulses of each burst (the transmitted *pulses* of a *coherent* radar have all *defined* phase angles to a reference). The **coherency** is needed to support the **along-track FFT** discussed in the next slides.

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Transmission Scheme (2)



- Old Design: Sentinel-3 LRM radar cycle transmitting pattern (left) and SAR radar cycle transmitting pattern (right).
- The LRM mode was dismissed.
- SAR radar cycles contain four bursts
- Each burst has a sequence of 1 C -64 Ku -1 C pulses.



(Figure credit: Thales Alenia Spazio)

How to perform Doppler Processing?



• The altimeter is said to operate in the <u>time domain</u> in <u>along-track</u> and in the <u>range</u>, or <u>Delay</u>, <u>domain</u> in <u>across-track</u>.

• A **Fast Fourier Transform (FFT)** is applied to signals received from each burst **to transform the time domain** into the **Doppler domain**. Here a comparison between Delay-Time and Delay-Doppler Domain:



scatterer.

How to perform Doppler Processing? (1)

Following the application of the FFT in along-track, the relative delay becomes function of Doppler frequency $(\delta_r(f))$.

The **Delay/Doppler relation** is **now single-valued** and the relative delay $\delta_r(f)$ can be eliminated from all signals simultaneously (Raney, 1998).

The new domain can be geometrically interpreted as it includes by mathematical construction a 1:1 correspondence between the observed Doppler frequency f (relative to zero) and the individual scatterer's position in along-track.







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How to perform Doppler Processing? (2)

The processing continues by eliminating the curvature of the range delay (unwanted extra delay with respect to the nadir direction for which the Doppler frequency f = 0) by the application of multiplicative phase shifts and partitioning the data in Doppler frequency bins.







How to perform Doppler Processing? (3)

During the overfly of the scatterer, the height estimate spans the Doppler range from the highest Doppler bin to the lowest until the scatterer is no more illuminated.

In other words, height estimates are sorted by the Doppler frequency as if the beam-limited antenna pattern would be split into many narrower Doppler beams (looks) looking at the same scatterer from different angles during the overfly.

After the compensation, the scatterer appears at its minimum nadir distance over all its delay history and all the area illuminated by the antenna pattern is exploited.





How to perform Doppler Processing? (4)

- The process is repeated over subsequent bursts.
- Several bursts are transmitted during the overfly of each surface point and each burst provides one single look to a surface point.





Stacking



• Afterwards, data collected in each Doppler bin are inverse Fourier transformed by applying an IFFT (Inverse Fast Fourier Transform) and power detected (losing the phase information, no more needed after that the range delay has been compensated using phase shifters).

 Data are accumulated to form stacks of many "looks" at specific surface positions.

Formation of 3 stacks on predetermined surface locations. <u>Each burst provides one single look to a surface point</u> (Credit: isardSAT).

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Incoherent Averaging



The final height estimate (retracking) is made on the L1b waveform resulting from the **incoherent averaging of waveforms (looks)**, composing the stack, that point a specific surface location (e.g. 6 looks from 6 different bursts are reported in the figure).

If Doppler bins cover the entire along-track antenna beam-width, all data acquired contribute to the height estimate (up to ~230 looks can be averaged).

The possibility of using a reduced number of looks will be discussed later.





Incoherent Averaging



The resulting waveform is named "L1b echo waveform" and shall be retracked either by using empirical retrackers or physical retrackers **specifically developed** for SAR (Delay/Doppler) waveforms.







Footprint reduction in Along-Track



The incoherent averaging (multilooking) of the individual echoes in the stack leads to a different result, if compared to the incoherent averaging made on LRM altimeters.

Footprint reduction in along-track up to 300 m (fixed value!).

The SAR L1b waveform is peakier than the LRM one (S/N increases) and the footprint dimension is no more dependent on surface roughness (SWH).







Following the Walsh bound (*Walsh, 1982*), the transmitted pulses (PRF = 17Khz for CryoSat-2 in Delay/Doppler SAR mode) are **coherent within the burst** and **incoherent from burst to burst**.

The **coherency** is needed to support the **along-track FFT** leading to the 2D Delay/Doppler domain, whereas the burst period separating the transmission of two consecutive bursts is set both to map overlapping surface locations in successive bursts and to **guarantee that in the multi-looking incoherent returns are averaged to reduce the speckle** as in conventional LRM altimeters.



Important considerations (2)



Surface along-track locations are derived from satellite burst locations projected on ground.

The burst repetition frequency is typically ~80Hz leading to an on-ground cell spacing of 80m with each grid cell co-located with the burst center.

However, standard SAR L1b 20 Hz products are formed by averaging four consecutive 80 Hz SAR waveforms resulting in an increase of cell size to ~300 m (no dependent on SWH!).





Important considerations (2)



Altimetric geophysical parameters from 80 Hz data can be also used (see option in SARvatore)





Important considerations (3)



Although the SAR altimeter design curtails the along-track footprint, the across-track footprint remains large.

Researchers (see CRUCIAL project later) are now moving towards working with Level-1BS data (stack data before multi-looking), tailoring the processing to optimise signal retrieval from the desired target.





Important considerations (4)



L1b products contain L1b waveforms (records) from each 20 Hz surface location.



Appended to each record is the **number of looks** used in the averaging and the correspondent Doppler angles identifying the displacement of the looks. **They are needed to support the retracking phase** (only analytical retracking). Empirical retrackers do not need any additional information (not an advantage in case of mispointing).

A detailed description of the processing can be found in (Raney, 1998).



Fully-Focused SAR



The recent developed Fully-Focused SAR processing (*Egido and Smith, 2017*) is currently capable of reducing the along-track resolution down to the theoretical limit equal to half the antenna length (**0.5 m for typical SAR altimeters**).

This is accomplished thanks to **an enhanced multi-looking** capability leading both to a significant **increase in the effective number of looks (ENL)** with respect to the delay/Doppler altimetry and to a **peakier multi-looked waveform (S/N>>)**





Fully-Focused SAR (2)

N 12



0.2 0.4 0.6 0.8 0.0 1.0 Normalized Power 0.0 0.2 0.4 0.8 1.0 0.6 Normalized Power

Delay/Doppler response (left) and FF-SAR response (right) of a 40 x 40 m irrigation pond

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Altimetry Missions (1973-2017)



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The ESA GPOD SARvatore on-line and on-demand processing service for the advanced exploitation of Sentinel-3 and CryoSat-2







- Introduction to the ESA/ESRIN GPOD Platform
- The SARvatore Service for Cryosat-2 and Sentinel-3
- Radar Altimetry Tools
- Recent & Future Updates
- Users Contribution to GPOD
- Different Methodologies to Process L1A Data up to L2 in SAR Mode
- SARvatore Data in Projects & Peer-Reviewed Papers



Introduction to the ESA/ESRIN GPOD Platform



The **ESA Grid Processing on Demand (**G-POD**)** system is a generic GRID-based operational computing environment providing users with a <u>fast computational facility without</u> <u>the need to handle bulky data</u>.

The G-POD system hosts high-speed connectivity, distributed processing resources and large volumes of data to provide scientific and industrial partners with a shared data processing platform fostering the development, validation and operations of new Earth Observation applications.



SARSCE CSA





In particular, the G-POD environment consists of:

Over 600 CPUs in about 90 Working Nodes

Over **400 TB** of **local on-line Storage** + flexible capacity of EO data accessed directly from the PACs Access to Cloud processing and data resources on demand **Internal dedicated 1 Gbit LAN** at ESRIN and at UK-PAC archives & 1 Gbps external connection **Software Resources on-line**: IDL, MATLAB, BEAT, BEAM, BEST, CQFD, NEST, **BRAT**, Python, Gamma System: GRID Globus on Linux

EO Data available to G-POD services come from both ESA and non-ESA missions.



G-POD Web Portal



The G-POD web portal is a flexible, secure, generic and distributed web platform.

From the creation of a new task to the output/publication, passing through the data selection and the job monitoring, the user goes trough a friendly and intuitive user interface accessible from everywhere.

More info on the G-POD Web Portal are available here: http://wiki.services.eoportal.org/tikiindex.php?page=GPOD+User+Manual#Annex











G-POD Services Portfolio



AARDVARC aeromeris algal1 AMORGOS Antarctica ASARP BEAMARITHM BeamReproject **BIOMASAR-II** BRAT download ESCATSM FAIRE2 GEOFIT

GlobTemperature GMESCOC GUT Imager INSAR JLOEP JURASSIC **KLIMA** LandsatIPF MCFS MGVLIRC2 **MGVIRegional** MIOPS MKI 3 MOSAICOM

MSGBaroncini MSGTimeseries NEST PHAVEOS RAIES **RIVFRI AKF2** SAROTECnFLO SARvatore for CryoSat-2 SARINvatore for CryoSat-2 SARvatore for Sentinel-3 SMOSL1 SMOSL2OS SMOSL2SM SOIL MAPPER SSEGridFAPAR VASD vomit WACMOS





The ESA G-POD Service, SARvatore (**SAR V**ersatile **A**Itimetric **T**oolkit for **O**cean **R**esearch & **E**xploitation) for Sentinel-3 & CryoSat-2 is an Earth-Observation application that provides the capability to process <u>remotely and on demand</u> **Sentinel-3** SAR and **CryoSat-2** SAR/SARin data, from L1A (FBR) data products to SAR/SARin L2 geophysical data products.







• The service is based on the SAR Processor Prototype that was developed by the ESRIN R&D Altimetry Team for CryoSat-2 validation purposes and preparation for Sentinel-3 mission.

System features:

- SAR/SARin L1b Processor Prototype (Standard Delay-Doppler Processing).
- SAR/SARin L2 Retracker Prototype (with SAMOSA Analytical Model and LEVMAR Least Square Estimator).
- Input: CryoSat-2 SAR/SARIN FBR Data or Sentinel-3 L1A Data.
- Output L1b → Radar Echogram.
- Output L2 \rightarrow SSH, SLA (W/O SSB), SWH, sigma0, wind speed.







• ESRIN R&D ALT team compiled the processor's MATLAB source code into a 64-bit <u>Linux binary</u> and delivered to ESA G-POD team the executables, <u>the input archive (FBR/L1A data)</u> and <u>satellite footprints</u> (ASCII tracks). The toolkit has been fully integrated in the GPOD System for grid on-demand computing.

The objectives of the service integration in GPOD are:

- to experiment <u>in-house research</u> themes that will be further exploited in the ESA-funded R&D projects.
- to validate CryoSat-2 & Sentinel-3 and support the exploitation of the data.
- to provide scientists with the access to SAR/SARin processing to get acquainted with the novelties and specificities of SAR/SARin Altimetry and to build their own customized products.


DATA Catalogues in G-POD



• The current GPOD service offers SAR (SARvatore) and SARin (SARinvatore) services to process **Cryosat-2** data.

• **439,184 SAR** passes and **367,592 SARin** passes have been stored in the service catalogue.

• An amount of **190.1 TB** of **CryoSat-2 FBR data** has been archived into the G-POD storage*.

 Data obtained from the ESRIN R&D ALT Team (historical) and CryoSat-2 FTP servers (current).

*Partial historical archive (<2012/05) were provided by NOAA/RADS and ESA/ESTEC.



DATA Catalogues in G-POD (2)

- The current GPOD service also offers a SAR (SARvatore) service to process Sentinel-3 data.
- **39,001 SAR** passes have been stored in the service catalogue.
- An amount of 82.4 TB of Sentinel-3 L1A data have been archived into the G-POD storage.





CANASCE CESA



Users in last 4 years:

97 SARvatore for CS-2 94 SARI Nvatore for CS-2 52 SARvatore for Sentinel-3

375.280 CPU hours (that's 42.8 years);

190.1 TB of CryoSat-2 data storage & 82.4 TB of Sentinel-3 data storage.

Number of processing tasks submitted for SARvatore / SARINvatore for CryoSat-2 : **21393** / **3179** Number of processing tasks submitted for SentineI-3: **11838** Input processed by SARvatore / SARINvatore tasks: **106.7 TB** / **28.8 TB** Input processed by SentineI-3 tasks: **182.5 TB**



Service Registration and Access

- The service is open, free of charge and accessible online from everywhere.
- In order to be granted the access to the service, you need to have an EO-SSO (Earth Observation Single Sign-On) **ID**.
- For the EO-SSO registration, go https://earth.esa.int/web/guest/general-registration.
- Afterwards, you need to send an e-mail to the G-POD team (to eo-gpod@esa.int), requesting the activation of the SARvatore service for your EO-SSO user account.





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- Service Registration and Access (2)
- After the registration to EO-SSO, users can freely access the services at:

https://gpod.eo.esa.int/services/CRYOSAT_SAR/ https://gpod.eo.esa.int/services/CRYOSAT_SARIN/ https://gpod.eo.esa.int/services/SENTINEL3_SAR

 These services are listed under the Marine Theme and can be found through the search bar.







The SARvatore Service for CryoSat-2 and Sentinel-3













Main Parameters

Publish Server	Portal		
Compression			
○ None ○	Single File 🤇	Unique Package	
	10 mm	2	

Pick Profile:



The Service Graphical User Interface



By default, the start date is the launch date of CryoSat-2 and Sentinel-3, respectively.

The GUI embeds standard buttons for image browsing (panning, zoom-in zoom-out, centering, undo, redo, reset, etc.).



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Data Selection



After the temporal/spatial selection, by clicking on the "**QUERY**" button, the service <u>lists all passes matching</u> <u>the temporal/spatial requirements</u>.

Sentinel-3 (or CryoSat-2) tracks, crossing the area of interest, are then overlaid on the world map.

The graphical interface lists up to 250 FBR products per page and informs users on the total number of passes found.

The user can select products by: clicking on specific passes. A 'Select All' option is available.









Geographical selection bn bat A of Select Date start date 2016-06-15T00:00: 2018-06-07T11:45: 500 km 2000 mi 2018-06-15T00:00: 2018-06-07T11:45: 500 km 2000 mi	
Received new 250 entries (12.202 sec)	
File Name	🔷 Start 🌩 End
S3A_SR_1_SRA_A_20180306T092447_20180306T101517_20180331T230538_3029_028_307	LN3_O_NT_003 2018-03-06T09:24:47.000Z 2018-03-06T10:15:17.
SIA_SR_1_SRA_A_20180307T085836_20180307T094906_20180401T214707_3029_028_321	LN3_O_NT_003 2018-03-07T08:58:36.000Z 2018-03-07T09:49:06.
S3A_SK_1_SKA_A_201803071195501_201803071204527_201804011214843_3025_028_327	N3_O_N1_003 2018-03-07119:55:01.0002 2018-03-07120:45:27.
S3A_SR_1_SRA_A_20180309T094713_20180309T103743_20180403T213331_3029_028_350	LN3_O_NT_003 2018-03-09T09:47:13.0002 2018-03-09T10:37:43,
S3A_SR_1_SRA_A_20180309T204338_20180309T213407_20180403T213319_3028_028_356	LN3_O_NT_003 2018-03-09T20:43:38.000Z 2018-03-09T21:34:07.
S3A_SR_1_SRA_A_201803101092102_201803101101132_20180404T214059_3029_028_364	N3_O_NT_003 2018-03-10109:21:02.0002 2018-03-10110:11:32.
T 53A_5K_1_5K4_A_201603101201727_201603101210756_201804041213056_3029_028_370	
Chawing 1 to 350 of 350 ontring	
Select All Delete Query Results from 1 to 250 out of 2276 (12.202 sec)	

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On the top right, a main parameters panel allows users to set the:

- Name of the current task.
- FTP Server to publish results (portal or personal).
- Data compression format (.tgz, none).
- Grid Computing Resources.
- Task Priority.

the right hand side of the map.	Main Parameters
Geograp Judi Selection ban dat a 3 3 con lat con lat	Task Caption SARvatore for S3 Publish Server Portal Compression None Single File Unique Package Computing Element ESRIN CE 01 SL6 64bits Optimised for S3 Priority Normal





The last step, before the task submission, is to set the list of processing options.

The processor prototype is **versatile** in the sense that the users can customize and adapt the processing, according their specific requirements, by setting the list of configurable options.

In the G-POD interface, users can easily set processing options via a series of drop-down menus.

The configurable options are divided according to the processing level they refer to (L1b and L2).





Processing Parameters

Pick Profile:

Here you can choose some pre-defined processing configuration: by selecting one of the available items in the drop-down menu below, the processing options (recommended for the specific thematic application) will be automatically selected and then you can go directly to the processing clicking on the "Process it!" button.

-

Select the processing configuration you want to use: -- Custom --

Here you find a list of processing options that you can select according to the processing level For a wiki user manual of the service, go here: wiki For a hands-on presentation, go here: slides

L1B Processor

Select the data type NT/ST you want to process	
lag to process only ST (Short Time Critical) or only NT (Non Time Critical) or both data types	only NT
Data Posting Rate	
lag to set the data posting rate: 20 Hz (canonic posting rate) or 80 Hz (finer posting rate)	20 Hz 🔻
Hamming Weighting Window	
lag to set the application of the Hamming Weighting Window on the burst data (section 4.4 in REF1)	Apply only in coasta
Exact Beam-Forming	
lag to set the application of exact or approximated Doppler Beam Steering (section 4.4 in REF1)	Approximated 💌
FFT Zero-Padding	
Tag to operate the Zero-Padding prior to the range FFT (section 4.8 in REF1). Zero-Padding is indicated or coastal zone analysis	Yes, apply Zero-Pa
Radar Receiving Window Size	
lag to select the size of the radar receiving window: 128 range bins (standard) or 256 range bins extended). Extended window is indicated for coastal zone analysis	128 range bins 💌
Antenna Pattern Compensation	
ag to activate the antenna pattern compensation on the Stack Data	No
Dump SAR Stack Data in output	
Tag to dump the SAR Stack Data in the output package. Be aware that SAR Stack Data are bulky data products (around 1 GB for single pass); do not process them massively but limit yourself at around 10/20 passes at the time	No

Processing Parameters

Pick Profile:

Here you can choose some pre-defined processing configuration menu below, the processing options (recommended for the spec then you can go directly to the processing clicking on the "Proce

Select the processing configuration you want to use: -- Custom --

	Custom	
Here you find a list of processing options t	Ice Sheets	t ace
For a wiki user manual of the service, go h	Sea Ice	
For a hands-on presentation, go here: slide	Open Ocean	
L1B Processor:	Coastal Zone	
- Select the data type NT/ST you want to pr	Inland Water	
Flag to process only ST (Short Time Critical) or only NT	Inland Water (HPR)	both
- Data Posting Rate	Official S3	
Flag to set the data posting rate: 20 Hz (canonic postir	ng rate) or 80 Hz (fin	er pos



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• Restrict the re-tracking on specific surfaces	
Flag to limit the processing on open sea or on water (open sea, coastal zone and inland process the full pass	water) or to Process only water
• PTR width alphap parameter	
Use a LUT (Look-Up Table) or a constant for PTR (Point Tartet Response) alphap parame	eter LUT 🔽
SAMOSA Model Generation	
Flag to select the generation of the SAMOSA model to use in the re-tracking. SAMOSA3 version (only zero order term) of SAMOSA2 (REF2), SAMOSA+ is the SAMOSA2 model to inland water, sea ice and coastal zone domain	is a truncated ailored for Use SAMOSA2 🔽
· Dump RIP in output	
Flag to append Range Integrated Power (RIP) in the output netCDF data product	No
Dump SAR Echo Waveforms in output	
Flag to append the SAR Echo Waveforms in the output netCDF data product	No
Single-look or Multi-look Model	
Flag to set the application of the Model Multilooking (Single-Look or Multi-Look). Single- indicated for quick look operations while Multi-Look is the most accurate	Look option is Multi-look 🔹
REF1: Guidelines for the SAR (Delay-Doppler) L1b Processing REF2: SAR Altimeter Backscattered Waveform Model (SAMOSA Model Paper), IEEE-TGARSS, Geoscience and Remote Sensing, IEEE Transactions on (Volume:53, Issu	Je: 2)
For any question, bugs and support, please contact us at: altimetry.info@esa.int For G-POD specific questions, please contact eo-good@esa.int	



Task Submission

Once the user has operated the selection of the tracks & processing options, the user has to click on the "PROCESS IT" button to submit the task to G-POD Computing Elements.

Geographical selection in lat 36 21 48 A01 Select Date start date 2016-06-15T00:00: 2018-06-07T11:45: 200 m SENTINEL3 SRA L1A operations products Query Received new 250 entries (43.431 sec)			13.57, 44.8
File Name	\$	Start	÷ .
S3A_SR_1_SRA_A_20180227T090607_20180227T095637_20180324T213045_3029_028_207LN3	_O_NT_00:	8 2018-02-27T09:06	:07.000Z 2018
→ S3A_SR_1_SRA_A_20180301T095444_20180301T104514_20180326T231003_3029_028_236	O_NT_00	2018-03-01709:54	:44.0002 2018
* 53A_SR_1_SRA_A_20180301T095444_20180301T104514_20180326T231303_3029_028_236LN3	_O_NT_00	3 2018-03-01T09:54	:44.000Z 2018
S3A_SR_1_SRA_A201803071092833_201803021101903_201803271213615_3029_028_2501N3	_O_NT_00	2018-03-02109:28	:33.0002 2018
♣ S3A_SR_1_SRA_A_20180302T202458_20180302T211527_20180327T225817_3029_028_256LN3	0 MT 00	2018-03-02720-24	E9 0007 2010
	_O_N1_00.	1 2010 05 02120.24	.38.0002 2016
S3A_SR_1_SKA_A_20180303T090221_20180303T095251_20180328T214405_3029_028_264LN3	_O_NT_00.	2018-03-03109:02	:21.0002 2018

Processing Parameters

Pick Profile:

Here you can choose some pre-defined processing configuration: by selecting one of the available items in the drop-down menu below, the processing options (recommended for the specific thematic application) will be automatically selected and then you can go directly to the processing clicking on the "Process it!" button. Select the processing configuration you want to use $\left\| - Outpow - I \right\|$

Here you find a list of processing options that you can select according to the processing level For a wiki user manual of the service, go here: wiki For a hands-on presentation, go here: slides

L1B Processor

LB Processor:		
elect the data type NT/ST you want to process		
	only NT	
Data Posting Rate		
ig to set the data posting rate: 20 Hz (canonic posting rate) or 80 Hz (finer posting rate)	20 Hz	
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ig to operate the Zero-Padding prior to the range FFT (section 4.8 in REF1). Zero-Padding is indicated r coastal zone analysis	Yes, apply Zero	Pa
tadar Receiving Window Size		
ig to select the size of the radar receiving window: 128 range bins (standard) or 256 range bins xtended). Extended window is indicated for coastal zone analysis	128 range bins	
Interna Pattern Compensation		
	No	
oump SAR Stack Data in output		
ng to cump the SAR Stack Data in the output package. Be aware that SAR Stack Data are bulky data oducts (around 1 Golf or ingle pass); do not process them massively but limit yourself at around //20 passes; at the time	No	•
2 Processor:		
Restrict the re-tracking on specific surfaces		
ag to limit the processing on open sea or on water (open sea, coastal zone and inland water) or to ocess the full pass	Process only wat	ter 💌
TR width alphap parameter		
se a LUT (Look-Up Table) or a constant for PTR (Point Tartet Response) alphap parameter	LUT	•
ag to select the generation of the SAMOSA model to use in the re-tracking. SAMOSA3 is a truncated rsion (only zero order term) of SAMOSA2 (REF2), SAMOSA+ is the SAMOSA2 model tailored for land water, sea ice and coastal zone domain	Use SAMOSA2	•
Dump RIP in output		
	No	
Dump SAR Echo Waveforms in output		
	No	•
Single-look or Multi-look Model		
ag to set the application of the Model Multilooking (Single-Look or Multi-Look). Single-Look option is dicated for quick look operations while Multi-Look is the most accurate	Multi-look	•
F1: Guidelines for the SAR (Delay-Doppler) L1b Processing F2: SAR Altimeter Backscattered Waveform Model (SAMOSA Model Paper), EE-TGARSS, Geoscience and Remote Sensing, IEEE Transactions on (Volume:53, Issue: 2)		

For any question, bugs and support, please contact us at: altimetry.info@esa.in For G-POD specific questions, please contact eo-gpod@esa.int

→ ADVANCED TRAINING COURSE IN OCEAN AND COASTAL REMOTE SENSING

Hosted by

Task Viewer / Workspace



esa	Home	Services	Workspace	Catalogue	Produc	ts Sche	dulers	My profile	Admin	Docu	mentation		
	Works	pace						Search Showing 20	0 of the 21	results	20 T	Name: Marco Restano Credits: 3 Logout	g-pod
	All	Prepare	d Created	l Pending	Active	Paused I	Failed	Completed	Incomple	ete C	Deleted		
		Capt	tion	Servio	ce	(Computi	ng Resource	St	atus	Creation time	Submission time	Completion time
		SARvator	re for S3	SARvatore for	SENTINEL3	ESRIN CE	01 SL6	64bits Optimis S3	sed for Com	pleted	2018-04-06 11:55:30 (UTC)	2018-04-06 11:55:30 (UTC)	2018-04-06 21:13:17 (UTC)
		SARvator	e for S3	SARvatore for	SENTINEL3	ESRIN CE	01 SL6	64bits Optimis S3	sed for Com	pleted	2018-04-05 12:39:53 (UTC)	2018-04-05 12:39:53 (UTC)	2018-04-05 14:40:49 (UTC)

After the submission of the job, users are directed to the workspace page where they can **check in real time the status of the run**. The color code is:

> Orange → run under processing Green → run completed Red → run failed

Further, **clicking on the task**, the user can have more information on the processing task:

Task Id
 Processing Id

Grid Working Node Id Task Creation Time

– Task Progress (data retrieving, data processing, data publishing)

SEN UNIL





SARvatore for S3

 Task ID: a0b93042-bfcd-4779-9047-062c8ec7bf03

 Service: SARvatore for SENTINEL3

 Status: Completed (refrsh)Cost: 3

 Progress:

 Progress:

 Submission Time: 2018-04-06711:55:30 (UTC)

 Completion Time: 2018-04-06711:55:30 (UTC)

 Processing ID: S_152301575489641496483921792829

 CE: ESRIN CE 01 SL6 64bts Optimised for S3



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Showing 1 to 1 of 1 entries						
Task Operations						
Caption						
SARVatore for 53						
			Cop	oy Clone Rec	reate Resubmit Requery Input Data	Delete
Jobs Information						





L18 Details input Parameters Processing Hodes Image: Parameters [21,17,1] Last notification: (2018-04-06718-72.23 (UTC)) Image: Parameters [21,207] Last notification: (2018-04-06718-37.19 (UTC)) Image: Parameters Processing Hodes	Jobs Information	
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	[26488] [2/1] wnode23	Last notification: [2018-04-06T21:12:21 (UTC)] Publishing results to gsiftp://gpodeoportal@giserver2.esrin.esa.int:2811//data/operational/ftproot/a0b93042-bfcd-4779-9d77-062c8ec7bf03/ 26488.stdout 26488.stdour =.log
Resubmit	Resubmit	
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Task Viewer / Workspace

After run completion, clicking on the button "Jobs Information", the user can inspect:

- The GPOD log file (.stdout or .stderr) where eventual errors on data retrieving or data storing are reported.
- The prototype **configuration file** (L1b_CONFIG_FILE.log and L2_CONFIG_FILE.log) where all the **processing options** are reported.
- The prototype **log files** (L1b_start.log and L2_start.log) where **eventual prototype processing errors** are reported.
- Users can also decide to **change one or more processing options** and then **re-submit the task**.

obs Infe	ormat	ion		
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SYSTEM PATHS

L1B			
Details	Input	Parameters	Processing Nodes
		[21171] [7/7] wnode26	Last notification: [2018-04-06T19:47:23 (UTC)] <u>21171.stdout</u> <u>21171.stderr</u> <u>L1b CONFIG FILE.log</u> <u>L1b start.log</u>
		[21207] [7/7] wnode23	Last notification: [2018-04-06T18:37:19 (UTC)] <u>21207.stdout</u> <u>21207.stdout</u> Lib CONSTC FUE log

You don't need to care about it (if everything goes ok) **********************************

NORTH_LAT=-3 SOUTH_LAT=-13 EAST_LON=-32 WEST_LON=-38



Example of Log File (L1b)

SAR vatore Processor Prototype SAR Versatile Altimetry Toolkit for OLIVV (Ocean-Land-Inland Water) Research and Exploitation

Current Run: CryoSat-2 SAR Mode L1b Processor Current Version: 1.52

Found 3 Passes to Process

Processing the Pass: CS_OFFL_SIR1SAR_FR_20140619T042952_20140619T043016_B001.DBL

Pass with 537 Records to Process

obs Inf	ormat	ion	
L1B			
Details	Input	Parameters	Processing Nodes
		[21171] [7/7] wnode26	Last notification: [2018-04-06T19:47:23 (UTC)] 2 <u>1171.stdout</u> 2 <u>1171.stderr L1b CONFIG FILE.log</u> L1b start.log
		[21207] [7/7] wnode23	Last notification: [2018-04-06T18:37:19 (UTC)] <u>21207.stdout</u> <u>21207.stderr</u> 116.CONETC ET E Loc

You don't need to care about it (if everything goes ok)

 $\begin{array}{l} \mathsf{BLOCK}\;\mathsf{START:}\,1 \longrightarrow 200\\ \mathsf{Scenario}\;\mathsf{Recovery}\,1 \longrightarrow 200\\ \mathsf{Gain}\;\mathsf{and}\;\mathsf{Calibration}\;\mathsf{Correction};\,1 \longrightarrow 200\\ \mathsf{Beam}\;\mathsf{Pointing}\;(1 \rightarrow 200\\ \mathsf{Beam}\;\mathsf{Forming}\;(Approximated);\,1 \longrightarrow 200\\ \mathsf{Beam}\;\mathsf{Stacking};\,1 \rightarrow 200\\ \mathsf{Scenario}\;\mathsf{Recovery}\;1 \longrightarrow 200\\ \mathsf{Alignment}\;\mathsf{and}\;\mathsf{Range}\;\mathsf{Compression};\,1 \longrightarrow 200\\ \mathsf{Elapsed}\;\mathsf{tim}\;\mathsf{e}\;\mathsf{is}\;\mathsf{SS447266}\;\mathsf{seconds}.\\ \mathsf{BLOCK}\;\mathsf{END};\,1 \longrightarrow 200\\ \end{array}$

 $\begin{array}{l} \mathsf{BLOCK} \mathsf{START} \colon 201 \longrightarrow 400\\ \mathsf{Scenario} \,\mathsf{Recovery} \,201 \longrightarrow 400\\ \mathsf{Gain} \,\mathsf{and} \,\mathsf{Cailbration} \,\mathsf{Correction} \colon 201 \longrightarrow 400\\ \mathsf{Beam} \,\mathsf{Pointing} \,\,(201 \to 400\\ \mathsf{Beam} \,\mathsf{Stacting} \,\,201 \to 400\\ \mathsf{Beam} \,\mathsf{Stacting} \,\,201 \to 400\\ \mathsf{Scenario} \,\mathsf{Recovery} \,\,201 \to 400\\ \mathsf{Scenario} \,\mathsf{Recovery} \,\,201 \to 400\\ \mathsf{Alignment} \,\,\mathsf{and} \,\,\mathsf{Range} \,\,\mathsf{Compression} \,\,201 \to 400\\ \mathsf{Elapsed time} \,\mathsf{is} \,\,277\,35071\,\,\mathsf{seconds}.\\ \mathsf{BLOCK} \,\,\mathsf{END} \,\,201 \to 400\\ \mathsf{Stacting} \,\,201 \to 400\\ \mathsf{Stacting} \,\,\mathsf{Stacting} \,\,\mathsf{Stacting$

BLOCK START: 401 --> 537 Scenario Recovery: 401 --> 537 Gain and Calibration Correction: 401 --> 537 Beam Pointing: 401 -> 537 Beam Forming (Approximated): 401 --> 537 Beam Stacking: 401 --> 537 Scenario Recovery: 401 --> 537 Alignment and Range Compression: 401 -> 537 Extrapolation going on with more than 4 samples Elapsed time is 14.332029 seconds. BLOCK END: 401 -> 537

Generating Output in kml, png and mat format

Output Generated -> Moving to Next Pass ...

Completed L1b Processing for the Pass CS_OFFL_SIR1SAR_FR_20140619T042952_20140619T043016_B001.DBL

Processing the Pass: CS_OFFL_SIR1SAR_FR_20140619T042952_20140619T043016_B001.HDR

No CryoSat-2 L1b File for: CS_OFFL_SIR1SAR_FR_20140619T042952_20140619T043016_B001.HDR -> File Skipped





Output Package Publishing

 In case of successful run completion green status), the portal will provide the user with a http link from where to download the output package on own local drive.

• The user can order to post the package directly on his **own personal ftp server** once the ftp server credentials have been inserted (through my "publish servers" submenu). This is the recommended option







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→ ADVANCED TRAINING COURSE IN OCEAN AND COASTAL REMOTE SENSING





SARvatore for S3 **♣** ? € € € **€ ∩** ∩ Task ID: a0b93042-bfcd-4779-9d77-062c8ec7bf03 Service: SARvatore for SENTINEL3 Status: Completed (refresh)Cost: 3 100% Progress: Creation Time: 2018-04-06T11:55:30 (UTC) Submission Time: 2018-04-06T11:55:30 (UTC) Completion Time: 2018-04-06T21:13:17 (UTC) Processing ID: S_152301575489641496483921792829 CE: ESRIN CE 01 SL6 64bits Optimised for S3 1000 m **Result Identifier** Start Time End Time ŧ Files: /tasks/download/?url=http://qpod.eo.esa.int/results/a0b93042-bfcd-4779-9d77-062c8ec7bf03/results.tgz Quicklook: Showing 1 to 1 of 1 entries Task Operations Caption SARvatore for S3 Clone Recreate Resubmit Requery Input Data Delete



Output Package Content





The output package consists of :

- Pass Ground-Track in .kml format.
- Radar Echogram Picture in PNG format.
- L2 data product in NetCDF format with all the scientific results.

The NetCDF format is self-explanatory with all the data field significance described in the attributes.



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For massive processing (years of data in large area of interest), it is recommended to request an off line processing: the GPOD team is available to process the data for you in an off line configuration and post the output L2 data in a personal ftp repository.

To request an order of processing, please write your order description (time of interest, region of interest, processing baseline) at:

eo-gpod@esa.int

altimetry.info@esa.int





Recent & Future Updates



Google Earth Map Layer



• New Map Layer (Google Earth Map) to support coastal and inland water communities.

• Use the Base Layer menu to switch between the Google Hybrid and the Base Map layer.







Chittage

89.83, 22.05

91.48 23.04 88.54 21.35 AOI -- 7 Select Date start date stop date del Nord 2016-06-15700:00: 2018-05-06T12:53 1.1 Corea + del Sud 91.48 23.04 88.54 21.35 Cina A01 -- 7 lest nultan start date stop date Pakistan 2018-06-06T12:53: 2016-06-15T00:00: Bhutan Emirati Arabi Unit Bangladesh wan India Myanmar (Burma) Oman Laos Tailandia Mar Cinese Meridionale Vietnam COULTR Cambogia Filippine SENTINEL3 SRA L1A operations products V Query Negros Mindanao Sri Lanka Basilan Malesia Google SENTINEL3 SRA L1A operations products V Query



New Models and Options



Recently made available in the products:

- CNES-CLS MSS 2015
- CLS Jason-2 Sea State Bias Solution
- ECMWF SWH and Wind Speed
- NSIDC Sea Ice Concentration
- NSIDC Sea Ice Age
- NCEP Sea Surface Temperature
- NCEP Precipitable Water

Soon to come:

- UPorto GPD Wet Tropo Solutions
- LEGOS FES14b Tide Model
- TPX09 Tide Model
- SAMOSA++
- STACK PHASE
- RETRACKER EPOCH





-SARvatore for Sentinel-3 allows to process L1A Short Time Critical (STC) Data (48h latency).

-The latest available Geophysical Corrections and Models are ingested daily in the GPOD system and appended to the GPOD Sentinel-3 STC products.

- System ready to process S3-B data when they will be made available to users



J/S Forum: users can get here the last

Joins & Share SARvatore Forum

updates & releases and report issues, ask questions, share & discuss results:

> https://wiki.services.eoportal.org/tikiview_forum.php?forumId=105



NRSCC



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Data Repository



Data Repository: The **SARvatore Data Repository** is now online. Datasets processed for the users are available to the Altimetry Community at:

https://wiki.services.eoportal.org/tikiindex.php?page=SARvatore+Data+Repository&highlight=repository

• A .kmz file can be downloaded to visualize in Google Earth the processed regions and compare, for example, to the CS-2 geographical mode mask.

SARVATORE DATA REPOSITORY

This page is a repository of Data processed in G-POD with SARvatore service. Data are available for download.

USER	SERVICE	PROFILE	REGION	COORDINATES	START-STOP TIME	PURPOSE OF THE PROCESSING	DATA
S. Dinardo	SARvatore for S3	Custom	Atlantic - North East	60N 35N 12W 16E	15/06/2016 09/05/2018		0001
SCOOP Team	SARvatore for CS-2	Sentinel-3	Pacific - West	17.1N ON 137E 150E	01/10/2012 31/12/2013	Support to the SCOOP project	0002
SCOOP Team	SARvatore for CS-2	Sentinel-3	Pacific - Central	25.2N 15N 180W 167W	01/10/2012 31/12/2013	Support to the SCOOP project	0003
SCOOP Team	SARvatore for CS-2	Sentinel-3	Pacific - East	4.6S 25S 140W 85W	01/10/2012 31/12/2013	Support to the SCOOP project	0004
SCOOP Team	SARvatore for CS-2	Sentinel-3	Atlantic - North East	70.3N 32.9N 20.1W 0.5E	01/10/2012 31/12/2013	Support to the SCOOP project	0005
SCOOP Team	SARvatore for CS-2	Sentinel-3	North Sea	70N 50N 6W 16E	01/10/2012 31/12/2013	Support to the SCOOP project	0006
SCOOP Team	SARvatore for CS-2	Sentinel-3	Agulhas	25S 44S 13.8E 40.2E	01/10/2012 31/12/2013	Support to the SCOOP project	0007
SCOOP Team	SARvatore for CS-2	Sentinel-3	North Indian Coast	24.4N 5.2N 66.9E 98.1E	01/10/2012 31/12/2013	Support to the SCOOP project	0008
SCOOP Team	SARvatore for CS-2	Sentinel-3	Indonesia	4S 10.1S 104.6E 120E	01/10/2012 31/12/2013	Support to the SCOOP project	0009
SCOOP Team	SARvatore for CS-2	Sentinel-3	Harvest	38.1N 31N 124W 119W	01/10/2012 31/12/2013	Support to the SCOOP project	0010
D. Martínez Sanchis	SARvatore for S3	Custom (STACK)	Greenland Sea	83N 72N 30W 30E	15/06/2016 15/06/2018	Comparing Stack peakiness with OLCI data for tunning lead detection Algorithm	0011
ID=1671	SARvatore for S3	Coastal Zone	Europe - North West	64N 44N 15W 13E	11/07/2017 28/10/2017	Research purpose	0012
ID=1671	SARvatore for S3	Coastal Zone	Arctic Pole	90N 70N 180W 180E	11/07/2017 28/10/2017	Research purpose	0013
ID=1671	SARvatore for CS-2	Default	Europe - North West	64N 44N 15W 13E	01/01/2016 01/01/2018	Research purpose	0014
ESA	SARvatore for CS-2	Inland Water	Mississippi mouth	32N 28.9N 92.9W 89.8W	13/10/2014 26/06/2018	Dataset for Community	0015












Users Contribution to GPOD







- The ESA-ESRIN Altimetry Team and the ESA GPOD Team support users who want to include their processors in GPOD.
- If interested, please send an email to:

eo-gpod@esa.int

altimetry.info@esa.int





SARvatore Data in Projects & Peer-Reviewed Papers



R&D Projects using CryoSat-2 GPOD Data MASCC

- CP40 (Paolo Cipollini and Marcello Passaro, NOC & TUM)
- GOCE++ (Ole Andersen, DTU)
- SCOOP (Luciana Fenoglio, TU Bonn)
- SeaNice (Sara Fleury, LEGOS)
- SHAPE (Pierre Fabry & Nicolas Bercher, Along Track)
- Iceberg Detection (Jean Tournadre, IFREMER)
- Swell Detection (Saleh Abdallah, ECMWF)
- CRUCIAL (Philip Moore, NU)

. . . .

- SAR SSB Study (Christine Gommenginger, NOC)





Salvatore Dinardo, Luciana Fenoglio-Marc, Christopher Buchhaupt, Matthias Becker, Remko Scharroo, M. Joana Fernandes, Jérôme Benveniste, Coastal SAR and PLRM altimetry in German Bight and West Baltic Sea, Advances in Space Research, 2017, ISSN 0273-1177, https://doi.org/10.1016/j.asr.2017.12.018. (http://www.sciencedirect.com/science/article/pii/S0273117717308943)

Cipollini, Paolo; Calafat, Francisco M.; Jevrejeva, Svetlana; Melet, Angelique; Prandi, Pierre. 2017 Monitoring sea level in the coastal zone with coastal altimetry and tide gauges. Surveys in Geophysics, 38 (1). 33-57.https://doi.org/10.1007/s10712-016-9392-0

Passaro, Marcello; Dinardo, Salvatore; Quartly, Graham D.; Snaith, Helen M.; Benveniste, Jerome; Cipollini, Paolo; Lucas, Bruno. 2016 Cross-calibrating ALES Envisat and CryoSat-2 Delay-Doppler: a coastal altimetry study in the Indonesian Seas. Advances in Space Research, 58 (3). 289-303.10.1016/j.asr.2016.04.011

Bonnefond, P.; Laurain, O.; Exertier, P.; Boy, F.; Guinle, T.; Picot, N.; Labroue, S.; Raynal, M.; Donlon, C.; Féménias, P.; Parrinello, T.; Dinardo, S. Calibrating the SAR SSH of Sentinel-3A and CryoSat-2 over the Corsica Facilities. Remote Sens. 2018, 10, 92.

Gómez-Enri, J.; Scozzari, A.; Soldovieri, F.; Coca, J.; Vignudelli, S. Detection and Characterization of Ship Targets Using CryoSat-2 Altimeter Waveforms. Remote Sens. 2016, 8, 193.

Gomez-Enri, Jesus & Vignudelli, S & Cipollini, P & Coca, Josep & González, Carlos. (2017). Validation of CryoSat-2 SIRAL sea level data in the eastern continental shelf of the Gulf of Cadiz (Spain). Advances in Space Research. 10.1016/j.asr.2017.10.042.

Idžanović, *M.*, *V. Ophaug*, and O. B. Andersen (2017), The coastal mean dynamic topography in Norway observed by CryoSat-2 and GOCE, Geophys. Res. Lett., 44, 5609–5617, doi:10.1002/2017GL073777.



Contacts & References



For any question, bugs and support, please contact us at: altimetry.info@esa.int

- For G-POD platform specific questions and get access to the service, please contact: eo-gpod@esa.int
- Service Manuals available at:

http://wiki.services.eoportal.org/tiki-index.php?page=GPOD+CryoSat-

2+SARvatore+Software+Prototype+User+Manual

http://wiki.services.eoportal.org/tiki-index.php?page=GPOD+SENTINEL-3+SARvatore+Software+Prototype+User+Manual

- Services available at:

https://gpod.eo.esa.int/services/CRYOSAT_SAR/ https://gpod.eo.esa.int/services/CRYOSAT_SARIN/ https://gpod.eo.esa.int/services/SENTINEL3_SAR/







ESA-MOST China Dragon 4 Cooperation

→ ADVANCED TRAINING COURSE IN OCEAN AND COASTAL REMOTE SENSING

12 to 17 November 2018 | Shenzhen University | P.R. China

SAR & SARin Altimetry for Coastal Zone and Inland water





GPOD Data Contribution to SAR analyses (Open Ocean & Coastal Zone)



CryoSat Plus for Oceans (CP4O)





The **TWLE (total water level envelope)**, i.e. the total sea level inclusive of ocean tides and atmospheric forcing (due to pressure and wind effects) has been investigated:

TWLE = Orbit Latitude - Corrected Range -Mean Sea Surface + - (Solid Earth Tide + Load Tide)

SAR L1b Processing Options	СРР	GPOD
Hamming Weighting Function	Not Applied	Applied only in Coastal Zone
Beam Steering	Approximated	Approximated
Radar Window Size	Normal (128 bins)	Extended (256 bins)
Range pre-FFT Zero Padding	Not Applied	Applied
SAR L2 Processing Options	СРР	GPOD
SAR Return Waveform Model	Numerical Solution with real antenna pattern & real PTR	SAMOSA 2 with LUT for alpha_p (PTR width)



Figure 5: across-track and along-track distance from coast for CryoSat-2 passes around the Western coast of Scotland.



Report of Project results (1)

The noise proxy has been evaluated as a function of along & acrosstrack distance from the coast for the CPP and GPOD datasets, respectively.

It can be noticed that the specific **coastal processing used in the GPOD** run gives only a slight reduction of the noise (~ 5 to ~ 4.5 cm) away from the coast, but **improves it significantly in the last 5 km yielding a noise of** ~ 9 cm at 3 km from the coast.



Figure 6: scatterplot of the absolute value difference between consecutive TWLE measurements against **across-track** distance from coast, and the statistics of its distribution in 1-km distance bins, for the CPP dataset.

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Figure 7: as in figure 5, for the GPOD dataset.

Report of Project results (2)





Figure 8: scatterplot of the absolute value difference between consecutive TWLE measurements against **along-track** distance from coast, and the statistics of its distribution in 1-km distance bins, for the CPP dataset.



Figure 9: as in figure 7, for the GPOD dataset.



SAR analyses & Stack Editing (Inland Water domain)



CryoSat-2 Success over Inland Water and Land (CRUCIAL)

- CRUCIAL was funded by the ESA's Support To Science Element (STSE) Programme.
- **Goal**: investigate the application of **CryoSat-2 data over inland water** with a forward-look component to the Sentinel-3 mission.
- The high along-track sampling of Cryosat-2 altimeter in SAR/SARin modes offers the opportunity to recover high frequency signals.



- Range FFT over 64 pulses in burst
- Beam formation and steered to nadir direction
- Heights from OCOG/Threshold
 retracker
- Orthometric heights using EGM08
- Coarse orthometric surface recovered from polynomial fit to ocean/inland water heights
- Improved ellipsoidal surface height by reinstating geoid

Part 2: Multi-look

(~ 300 m along track)

- Form sequence of ground points at beam angle using coarse approximate steering
- Beam formation and steered to ground points
- Stack beams pointing at ground points
 - max 240 beams in SAR mode and 60 for SARin in stack for multi-look
- Apply slant range correction, tracker range correction, Doppler range correction
- Heights from empirical and OCOG/Threshold retrackers







CryoSat-2 Success over Inland Water and Land (CRUCIAL)

- Selected regions of interest (Rivers)
 - Tonlé Sap river, Cambodia (SAR) Mekong River (SAR) Amazon (SAR) Ocean off Amazon estuary (SARin) Amazon (SARin) Brahmaputra (SARin
- Processing Baselines & Retrackers



Figure 1. Amazon Basin: LRM (green), SAR (red) and SARIN(blank) tracks. Blank area is SARIN.

FBR to L1B: Innovative processing optimizing the number of beams in the stack for ML. CS-2 Baseline B SAR & SARin data as input.

Retrackers: OCOG/Threshold retrackers, re-adapted within the project, and SAMOSA2.

- ESA G-POD SARvatore & SARinvatore service data.
- Auxiliary dataset for validation: a) River Gauges data, b) Jason-2, Envisat and SARal-AltiKa data, c) LANDSAT data for river masks computation. D) ACE2 and other GDEM data to estimate river slope.



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CRUCIAL - Results (1) – SAR



- The speckle in the burst echoes affects • the recovered heights from the 80 Hz SAR data and multi-look waveforms are essential for precise heights when CRUCIAL retrackers are considered (empirical retrackers).
- A reduction from the maximum possible • number in the stack of approximately 240 to 81 looks centred on the beam directed closest to nadir reduced the variability in derived heights across Tonlé Sap.

N=40 (2N+1=81 looks) was selected

Beam-

steering/focusing

& stack formation

for all ROI in SAR mode.

•



Figure 1: Pass across Tonlé Sap of 3 Dec 2011. 80 Hz burst data (black); running average over 4 points of burst data (blue) and multi-look with N=40 (red). The orthometric height is the height on the surface above the EGM96 geoid





CRUCIAL – Results (2) – Validation for the Mekong ROI (SAR)

- SAR FBR heights along the Mekong (N=40). Gauges and range identified by lines/circles. Circles at gauge show low water level (Dec-Apr) and high water level (Aug-Sep).
- Validation of Cryosat-2 inland water heights along the Mekong are severely affected by the non-repeating orbit.
- RMS errors at the Kratie gauge are equal to 67.8 cm (N=40) and 91.9 cm (N=110), respectively.
- These differences are comparable to those of Birkinshaw et al (2010) where an RMS of 76 cm was seen for ERS-2 for the years 1995-2003 and 57 cm for Envisat for the years 2002-2008.





Figure 19: Comparison of Kratie gauge data with heights from near-by altimetric points from NCL (this study; N=110) and DTU. RMS 91.9 cm (NCL, empirical retrackers) and 96.8 cm (DTU).

Figure 20: Comparison of Kratle gauge data with heights from near-by altimetric points from NCL (this thl: study) waveforms using N=40. RMS 67.8 cm (empirical retrackers) and 66.9 cm (OCOG/Threshold) using 3 or rejection level.



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SARin analyses for Coastal Zone and Inland Water



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Figure 2-1. The three CS2 possible modes: LRM, SAR & SARin (courtesy of Thales Alenia Space).

SARin for Coastal Zone and Inland Water

- Waveforms transmitted from two antennae illuminating the same surface area.
- If the satellite roll is accounted for, heights from the two antennae should be near identical over flat terrain and inland waters.
- The **Coherence** calculated from the waveforms collected by both antennae can be used to investigate the **ground slope** (if the roll angle is not biased).
- The angle of arrival (AoA) can be used to identify off nadir clutter returns.





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Figure 2-2. Example of a Coastal Ocean contaminated waveform. TOP: Power waveform. BOTTOM Angle of Arrival waveform.



SARin for Coastal Zone in CP40



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Sea Surface Height - isardSAT(yellow), ESA(red)

Figure 3-9. Example of processing results on Cuban North East Islands, descending pass. Retracked geolocations are marked with points, and the SSH estimates (in meters) are marked with lines. Red colour is used for ESA L2I outputs, yellow colour is used for CP4O processing outputs.



Figure 3-10. Five consecutive Power Waveforms corresponding to the track of Figure 3-9 around the CP4O processing SSH jump. The retracking fitted waveform is shown in red.

SARin Analyses of Ground Slope in CRUCIAL





Figure 45: Google earth plot of descending pass on 8 September 2012 across Amazon near Tabatinga (upper). Cross angles from SARin mode (lower). The blue arrow points along direction of flight.



Figure 22: (Upper) Difference between heights from two antennae; (lower) ground slope across.

SARin Amazonas 5 May 2012. (Latitude -4.2° corresponds to longitude 70.179°W)

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Validation for the Amazon ROI (SARin)

- Comparison against data from Tabatinga gauge along a river stretch of 160 km (N=60)
- · Passes 2 days apart used to adjust for river slope.
- Heights from SARin data at Tabatinga yielded an RMS of 29.9 cm. <u>This is an improvement</u> on the best results of Birkett et al. (2002) for the Amazon (for Topex/Poseidon: for 1992-1999 were in the range 0.4–0.6 m).

The **SAMOSA2** analytical retracking in G-POD **SARin**vatore is inappropriate for inland waters (**SAMOSA+ performs better**, see slides about Lake Bracciano). Retracking G-POD waveforms using the empirical trackers developed in CRUCIAL or with the OCOG/Threshold retracker yields enhanced results.



Figure 38: Google earth image of Amazon near Tabatinga. Gauge marked in red. Yellow markers denote centre line of stretch considered for Cryosat-2 crossings.





GPOD Data Contribution: 20 Hz & 80 Hz analyses with the SAMOSA+ Retracker





Lake Bracciano is a lake of volcanic origin located in the Italian region of Lazio 32 km northwest of Rome. It is one of the major lakes of Italy and has a circular perimeter of approximately 32 km with a diameter of roughly 9 Km. Its inflow is from precipitation only as there are no inflowing rivers.

As the lake serves as a drinking water reservoir for the city of Rome, it has been under control since 1986 to avoid the pollution of its waters. For this reason, Bracciano is among the cleanest lakes of Italy.

The absence of motorized navigation favors sailing, canoeing and swimming





Lake Bracciano: 20 Hz & 80 Hz analyses with SAMOSA+(2)



In the first six months of 2017 less than half of average rainfall in central Italy was recorded.

Lake Bracciano has seen a significant drop in water level. The receding shoreline was so prominent that it became visible in optical satellite data. While this may mean more beach space for holidaymakers, it indicated a depleted supply of water for the Italian capital.

Lake Bracciano's water level is closely monitored by local authorities but, in remote parts of the world, water levels of other large lakes can also be monitored by satellite radar altimeters, helping governments better manage water resources.





Lake Bracciano: 20 Hz & 80 Hz analyses with SAMOSA+(3)







- In this study, Sentinel-3 products ٠ made available by the ESA GPOD SARvatore for Sentinel-3 online and on-demand processing service (https://gpod.eo.esa.int/services /SENTINEL3_SAR) have been analyzed.
- The scope is to maximize the • exploitation of Sentinel-3 data over all surfaces providing user with specific processing options not yet available in the official Sentinel-3 processing chain.

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Processing Parameters Pick profile Select the processing configuration you want to use Inland Water Here you find a fist of processing options that you can select according to the processing level For a wiki user menual of the service, so here: wiki Filter out Duplicated CryoSat-2 Products during the processing time Enable Data Posting Rate 20 Hz/80 Hz 20 Hz Hamming Weighting Window Yes, apply it Exact Ream-Forming Approximated FFT Zero-Padding Yes, apoly Zero-Padding + 256 range bins Radar Receiving Window Size intenna Pattern Compensation Dump SAR Stack Data in output

L2 Processor

Restrict the re-tracking on specific surfaces

PTR width alphap parameter

SAMOSA Model Generation

Single Look or Multi Look Model

Dump RIP in output

Dump SAR Echo Waveforms in output



rocess only water points -

Lake Bracciano: 20 Hz & 80 Hz analyses with SAMOSA+(4)

A preliminary check indicated that the majority of the data is corrupted (multi-peaks, top figures). Two independent approaches have been used:

1 - The DAHITI approach has been adopted to filter outliers [Schwatke et al., 2015]. Thresholds on water height, height error (ADM: "absolute deviation around the median") and Sigma0 have been applied. These have been applied after a supervised selection of regions (latitude threshold) in which water height, sigma0 and ADM error were stable and within the bounds suggested in [Schwatke et al., 2015].

Some tuning has been performed to optimize the thresholds. These are similar but not identical for the 20Hz and 80Hz cases.

The median and 2*std (error bar) of the selected values have been considered to build the final time series.

C. Schwatke et al., DAHITI – an innovative approach for estimating water level time series over inland waters using multi-mission satellite altimetry. Hydrol. Earth Syst. Sci., 19, 4345–4364, 2015. https://doi.org/10.5194/hess-19-4345-2015

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