



Introduction to SAR Polarimetry

ESA-MOST Dragon 4 Cooperation

ADVANCED LAND REMOTE SENSING
INTERNATIONAL TRAINING COURSE

“龙计划4”高级陆地遥感国际培训班

Eric POTTIER

20–25 November 2017 | Yunnan Normal University
Kunming, Yunnan Province, P.R. China

2017年11月20日—11月25日
云南师范大学，中国，昆明

University of Rennes 1 - France



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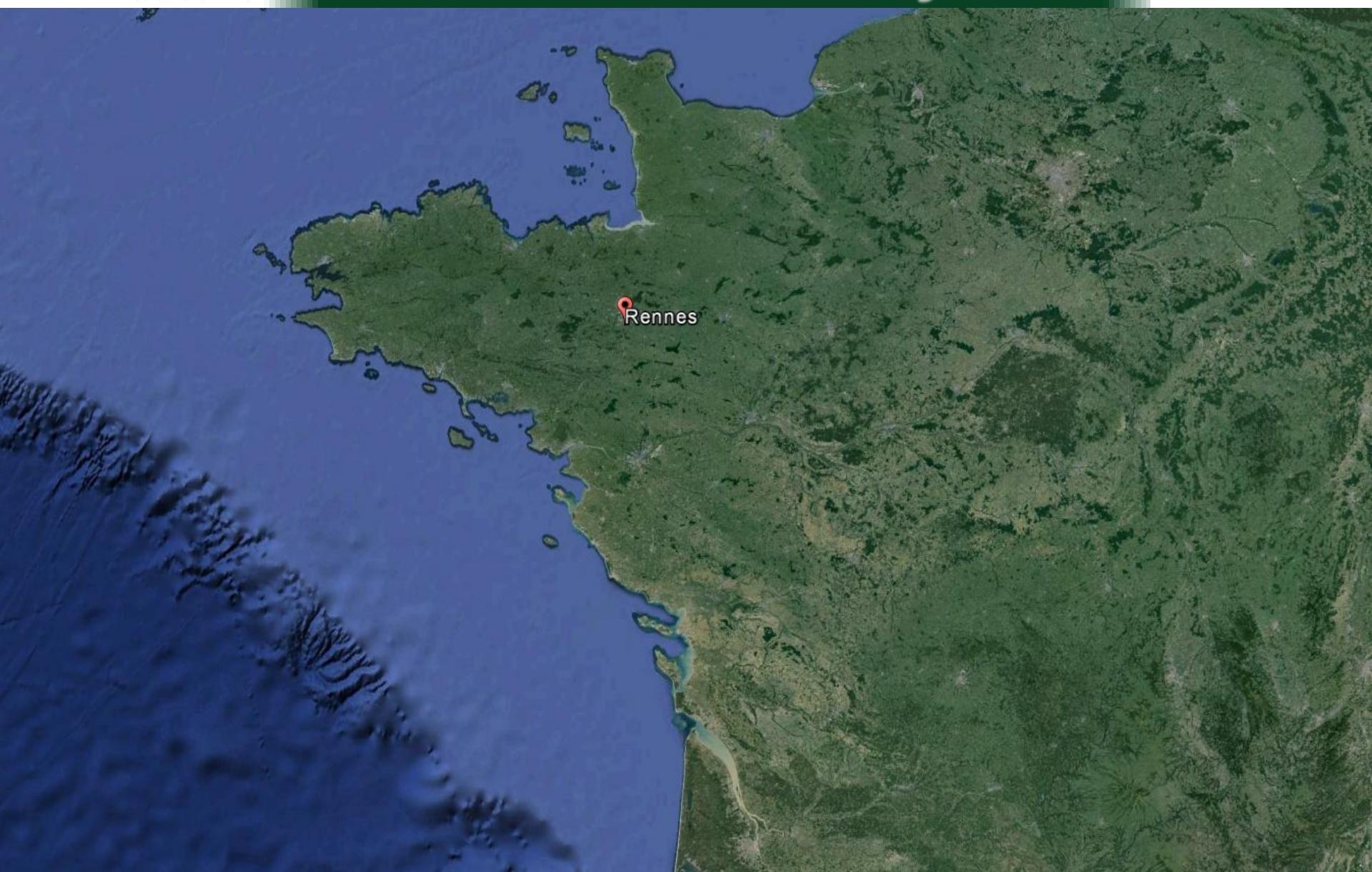
I.E.T.R. - UMR CNRS 6164
Université de Rennes I - Campus de Beaulieu
Pôle Micro Ondes Radar - Bat 11D
263 Avenue Général Leclerc
CS 74205 - 35042 Rennes Cedex – France

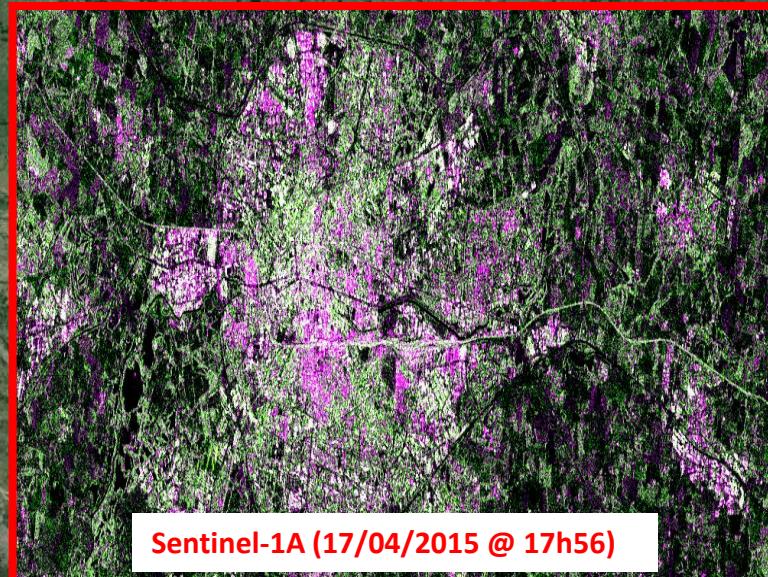
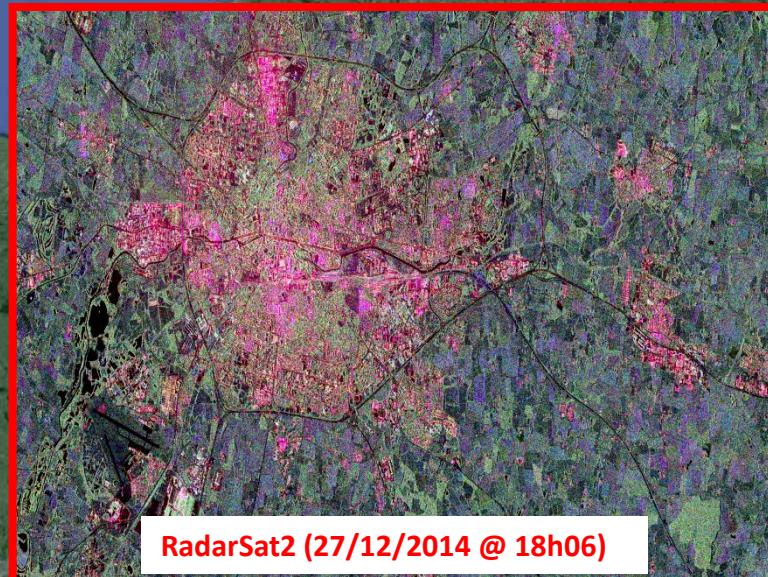
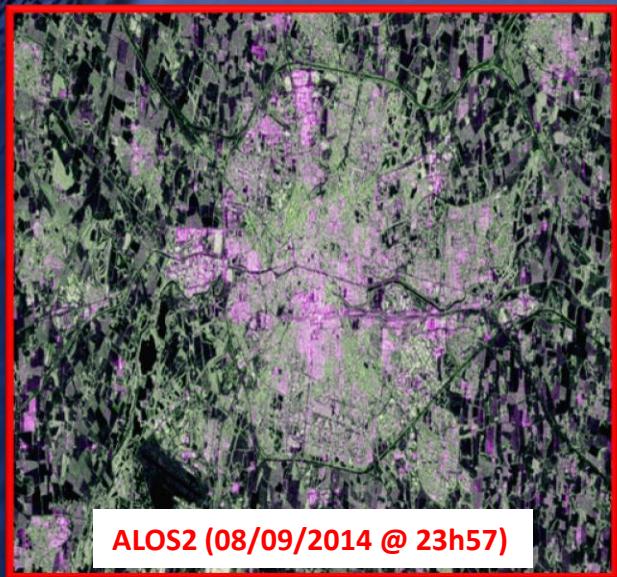


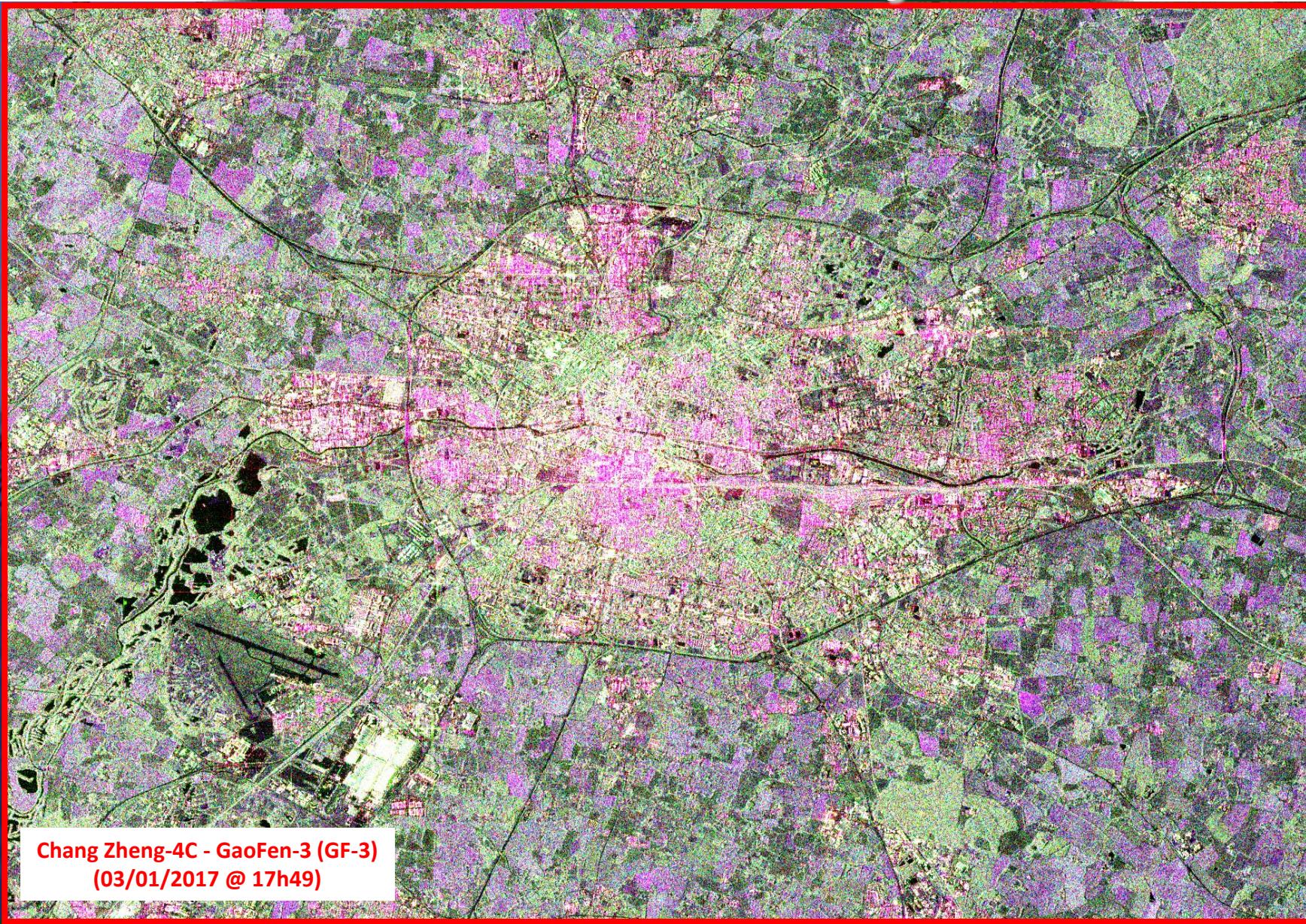
SAR & Hyperspectral multi-modal Imaging
and signal processing,
Electromagnetic modeling



Rennes - Brittany







Chang Zheng-4C - GaoFen-3 (GF-3)
(03/01/2017 @ 17h49)



Objective

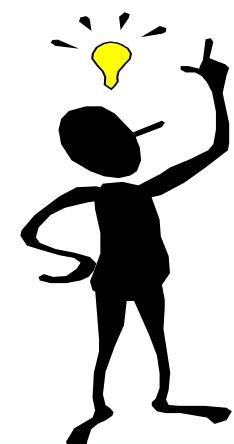
To provide

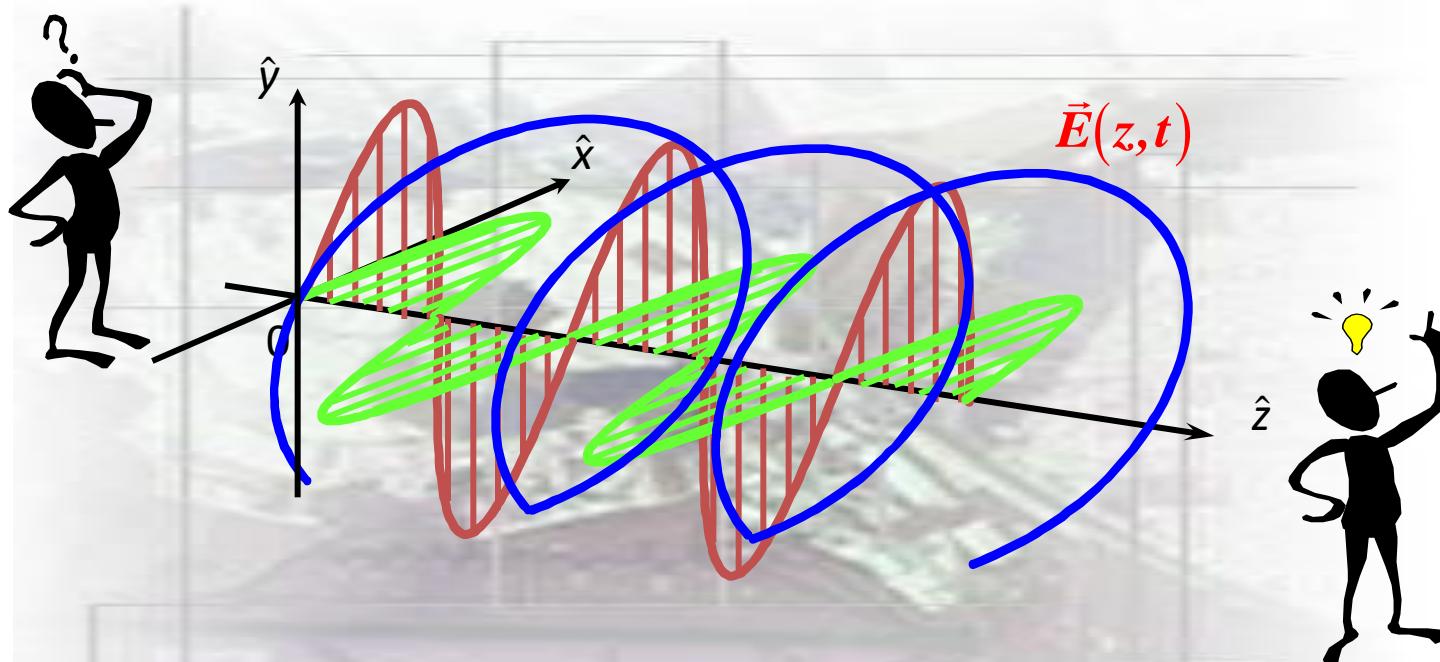
**the minimum, but necessary,
amount of knowledge required**

to understand

scientific works on

SAR Polarimetry (PolSAR)





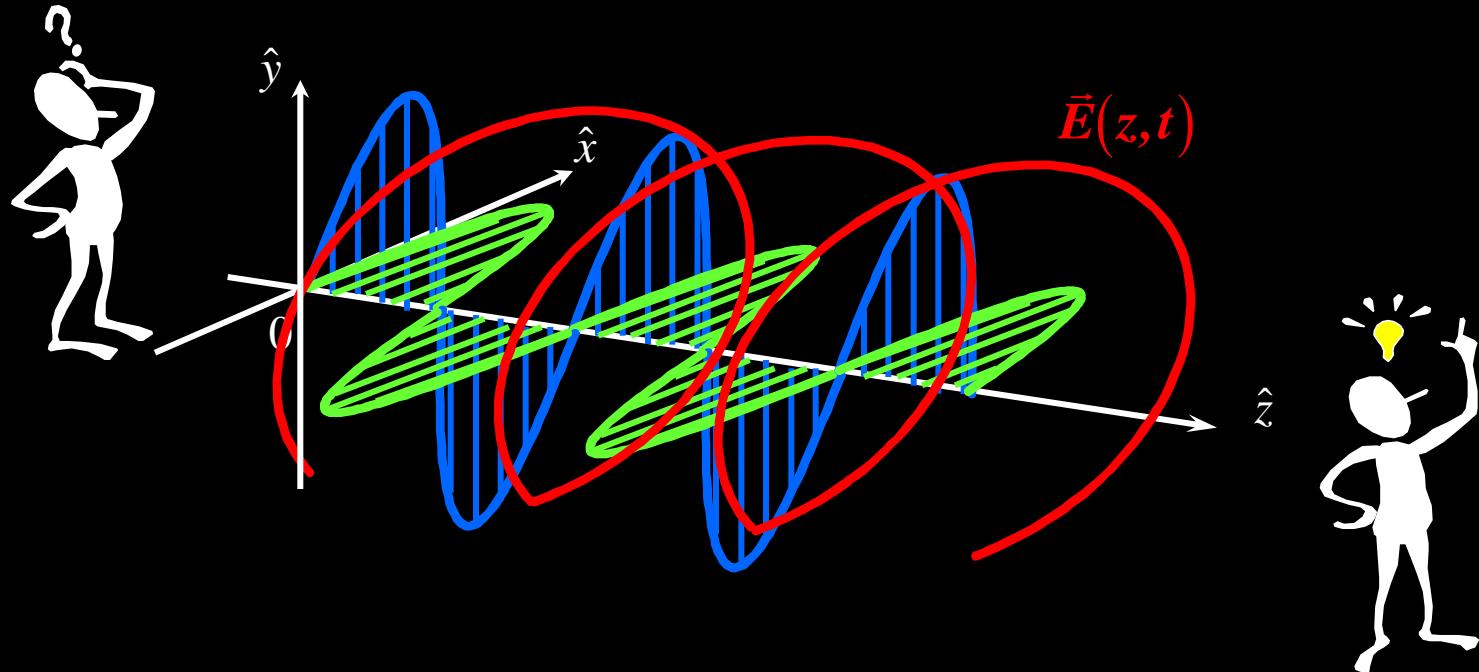
GENERAL INTRODUCTION

RADAR POLARIMETRY



- **A bit of History**
- **Airborne and Space-borne
Polarimetric SAR Sensors**
- **Software / Toolbox**
- **Learning / Training / Results**

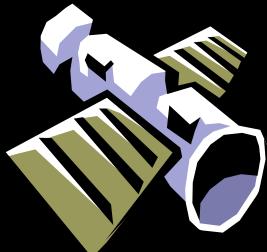
Radar Polarimetry



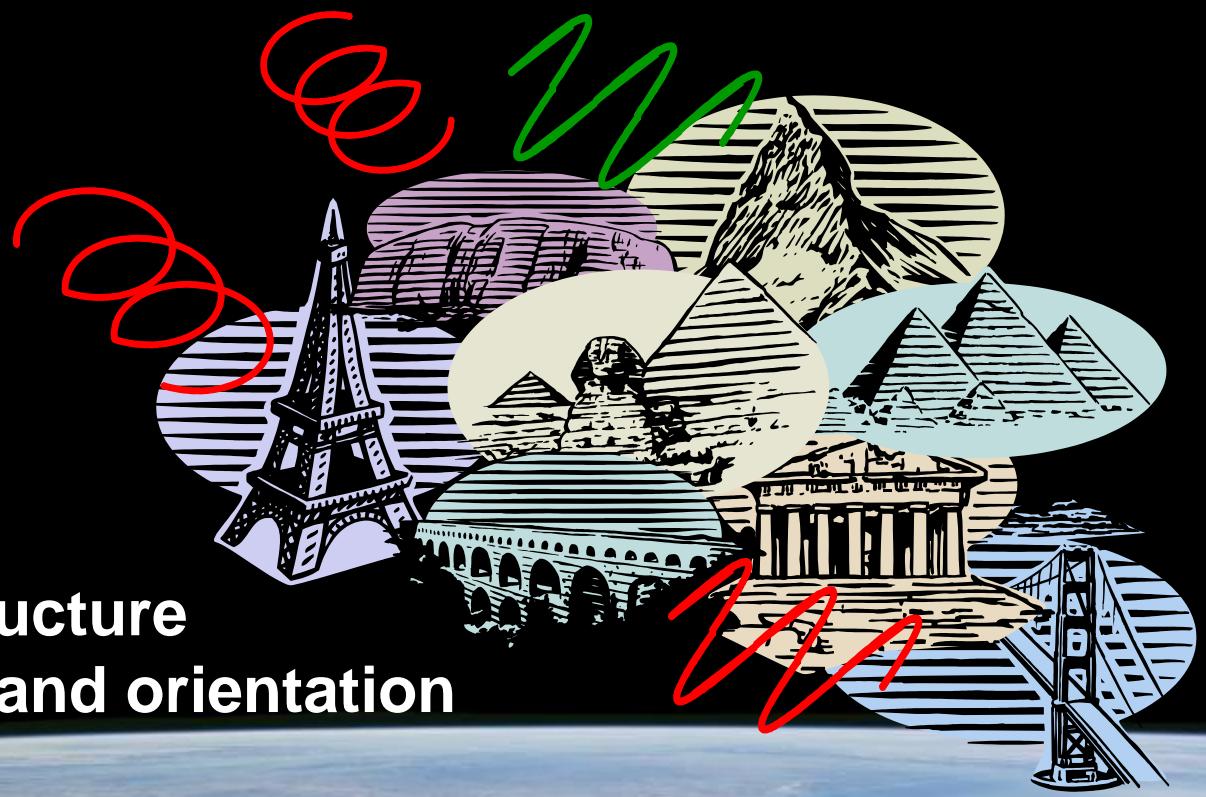
Radar Polarimetry (**Polar** : polarisation **Metry**: measure)
is the science of acquiring, processing and analysing
the polarization state of an electromagnetic field

Radar Polarimetry deals with the full vector
nature of polarized electromagnetic waves

Radar Polarimetry



The POLARISATION information
Contained in the waves backscattered
from a given medium is highly related to:



its geometrical structure
reflectivity, shape and orientation

its geophysical properties such as humidity, roughness, ...

SAR Polarimetry Applications



Forest Vegetation

- Forest Height
- Forest Biomass
- Forest Structure
- Canopy Extinction
- Underlying Topography

- Forest Ecology
- Forest Management
- Ecosystem Change
- Carbon Cycle



Agriculture

- Soil Moisture Content
- Soil roughness
- Height of Vegetation Layer
- Extinction of Vegetation Layer
- Moisture of Vegetation Layer

- Farming Management
- Water Cycle
- Desretification



Snow and Ice

- Topography
- Penetration Depth / Density
- Snow Ice Layer
- Snow Ice Extinction
- Water Equivalent

- Ecosystem Change
- Water Cycle
- Water Management



Urban Areas

- Geometric Properties
- Dielectric Properties

- Urban Monitoring



Courtesy of Dr. I. Hajnsek

A Bit Of History



Radar Polarimetry

Discovery of the Phenomena of Polarized Electromagnetic Energy

AD 1000

Use of the polarized skylight to locate a hidden sun



Crystal of calcite
Iceland Spar
Sunstone

1669

First known Quantitative work on light observation



Bartholinus



Discovery of the double refraction in calcite

1677

Wave nature of light discovery
Explanation of the double refraction

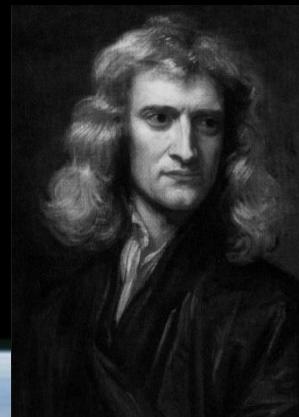


Huygens

Corpuscular model or « longitudinal » waves

1704

Corpuscular Model of light



Newton

1808

Discovery of the polarization of light (intrinsic property of light and not of crystals)



Malus

X-1795

Non Exhaustive Chronological List of the Main Pionners who contributed to the discovery of Polarization leading to Radar Polarimetry

Brewster



1816

Fresnel



1820

Faraday



1832

Stokes



1852

Maxwell



1873

Helmholtz



1881

Rayleigh



1881

Kirchhoff



1883

« Transverse » nature
of light waves

Electromagnetic
theory of light



Non Exhaustive Chronological List of the Main Pionners who contributed to the discovery of Polarization leading to Radar Polarimetry

Brewster



1816

Hertz



1886

Fresnel



1820

Faraday



1832

Stokes



1852

Maxwell



1873

Helmholtz



1881

Rayleigh



1881

Kirchhoff



1883

Drude



1889

Sommerfeld



1896

Poincaré



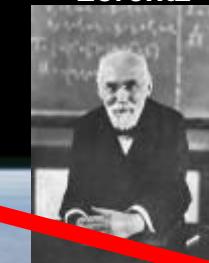
1892

Lie



1897

Lorentz



1908

Marconi



1922

Wiener



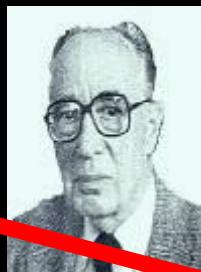
Non Exhaustive Chronological List of the Main Pionners who contributed to the discovery of Polarization leading to Radar Polarimetry

Pauli



1950

Deschamp



1951

Born



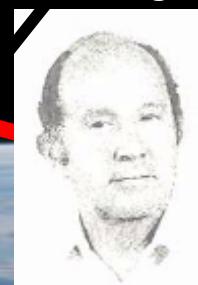
1954

Wolf



1954

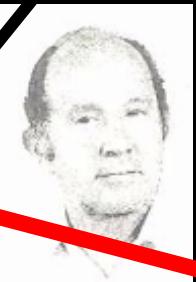
Kennaugh



1952

Non Exhaustive Chronological List of the Main Pionners who contributed to the discovery of Polarization leading to Radar Polarimetry

Kennaugh



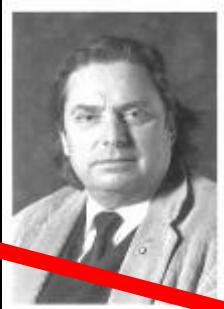
1952

Huynen



1970

W. M. Boerner



1980

**The
Radar Polarimetric
Triptych**

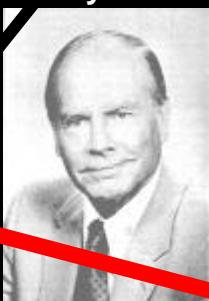
Non Exhaustive Chronological List of the Main Pionners who contributed to the discovery of Polarization leading to Radar Polarimetry

Kennaugh



1952

Huynen



1970

W. M. Boerner



K. Raney



J.J. Van Zyl



A. Freeman



R. Touzi



J.S. Lee



T. Ainsworth



S.R. Cloude



E. Pottier



P. Dubois



Y. Yamaguchi



C. Lopez



H. Mott



E. Lueneburg



E. Krogager



A. Moreira



Y.L. Desnos



Z. Czyz



K. Papathanassiou



I. Hajnsek



T. Le Toan



L. Ferro-Famil
#E. Pottier (06/2017)



J.C. Souyris

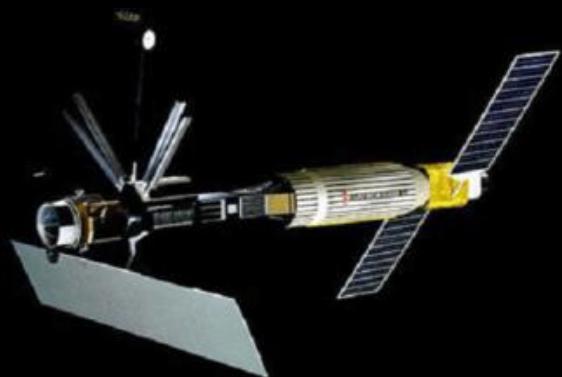
**1990 - 2000
Radar Polarimetry
Scientific Progress**

Polarimetric Radar (SAR)

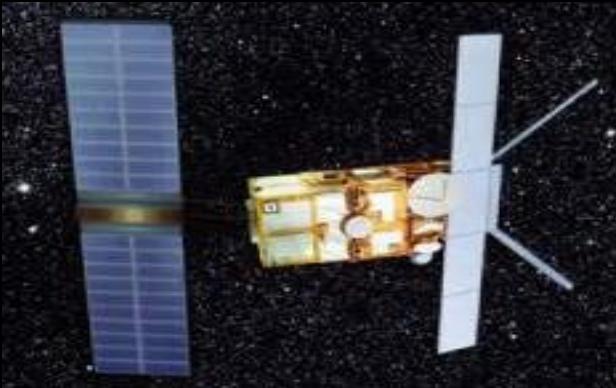


Spaceborne Sensors

Space-borne Sensors



SEASAT
NASA/JPL (USA)
L-Band, 1978



ERS-1
European Space Agency (ESA)
C-Band, 1991-2000



J-ERS-1
Japanese Space Agency (NASDA)
L-Band, 1992-1998



RadarSAT-1
Canadian Space Agency (CSA)
C-Band, 1995

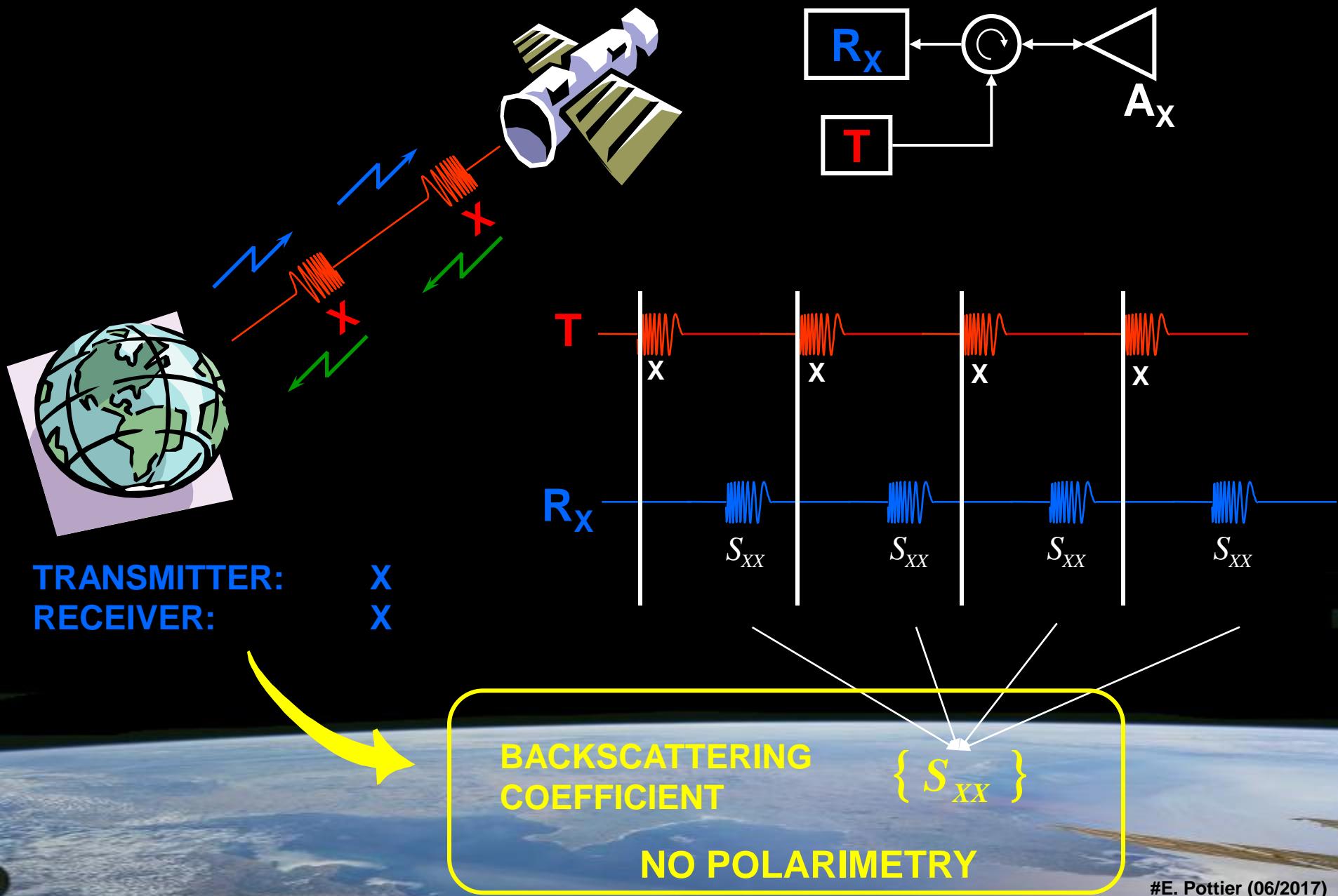


ERS-2
European Space Agency (ESA)
C-Band, 1995

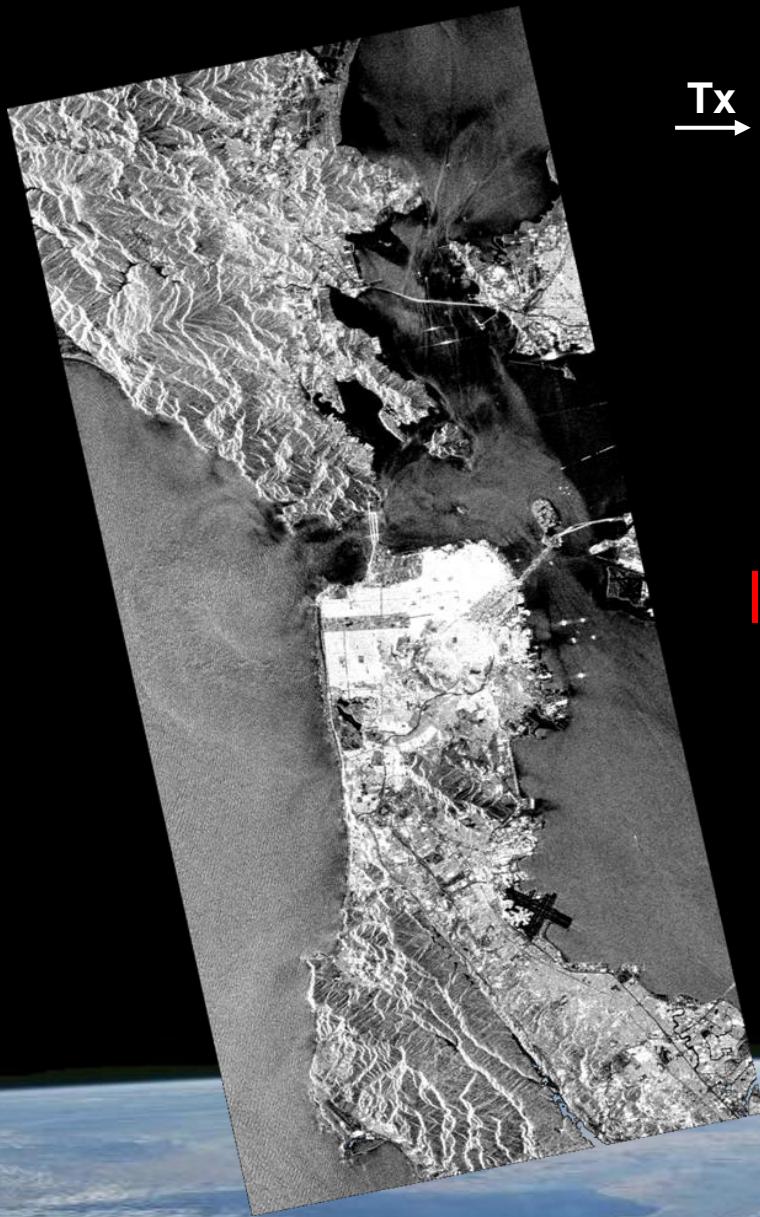


Shuttle Radar Topography Mission
NASA/JPL (C-Band), DLR (X-Band)
February 2000

Scattering Coefficient



Space-borne Sensors



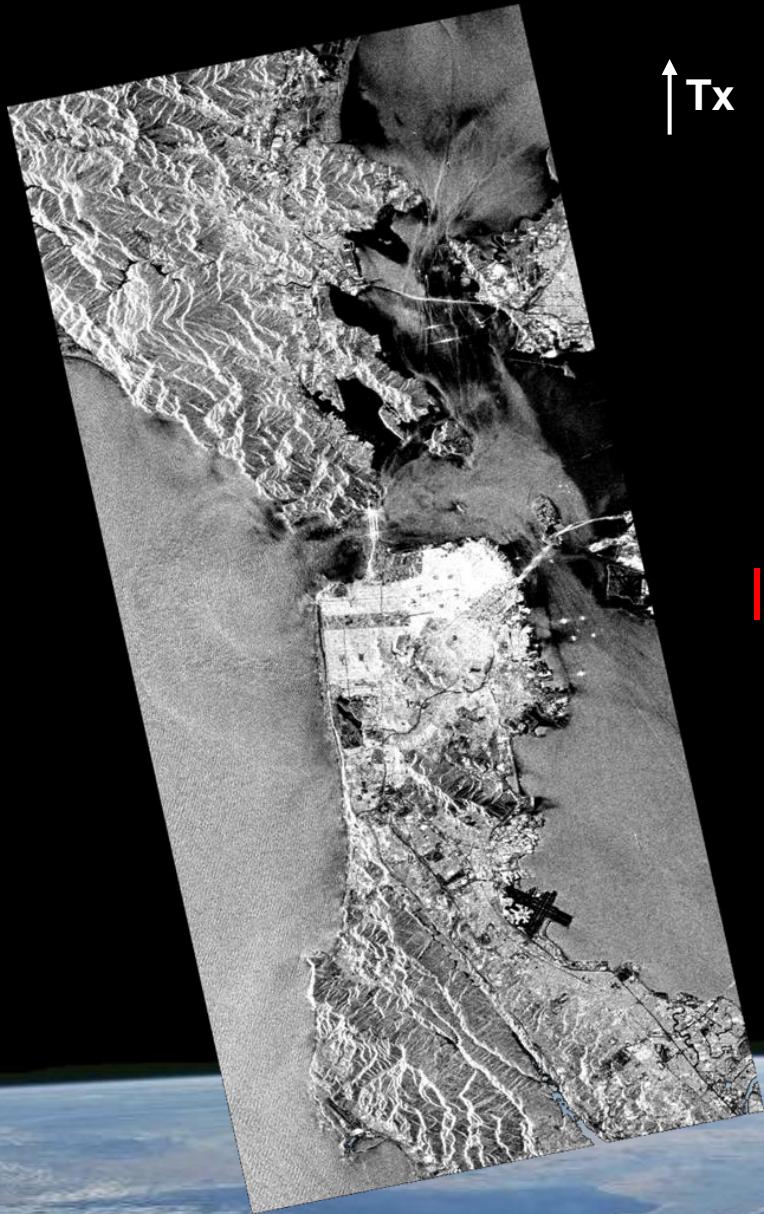
Tx → Rx →

$|HH|_{dB}$

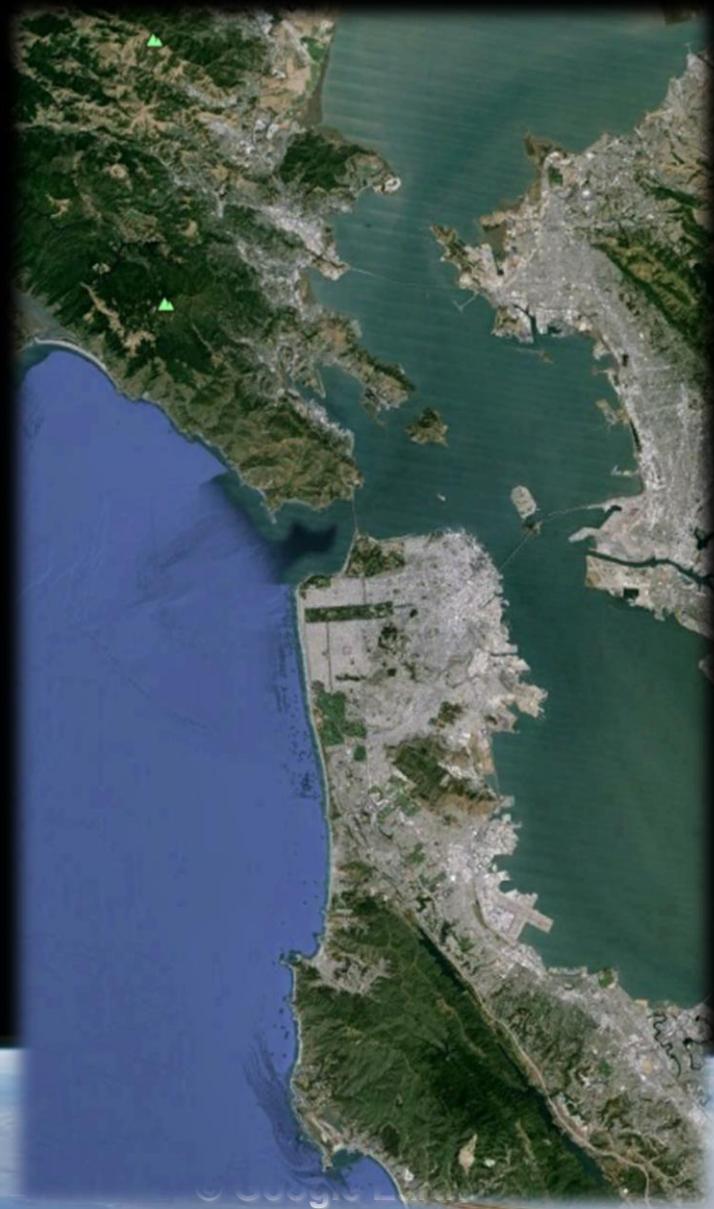


San Francisco Bay – (L-Band)

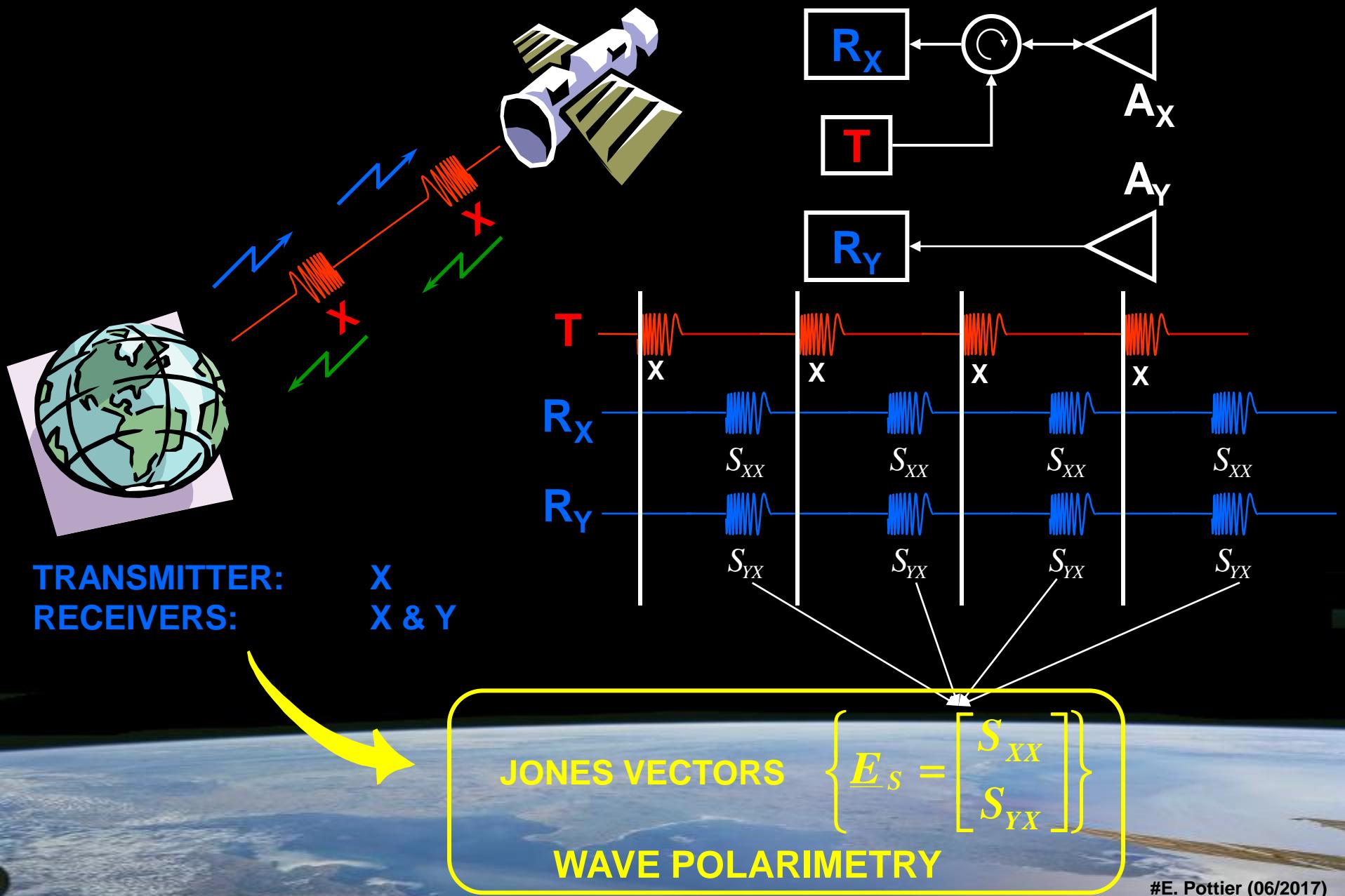
Space-borne Sensors



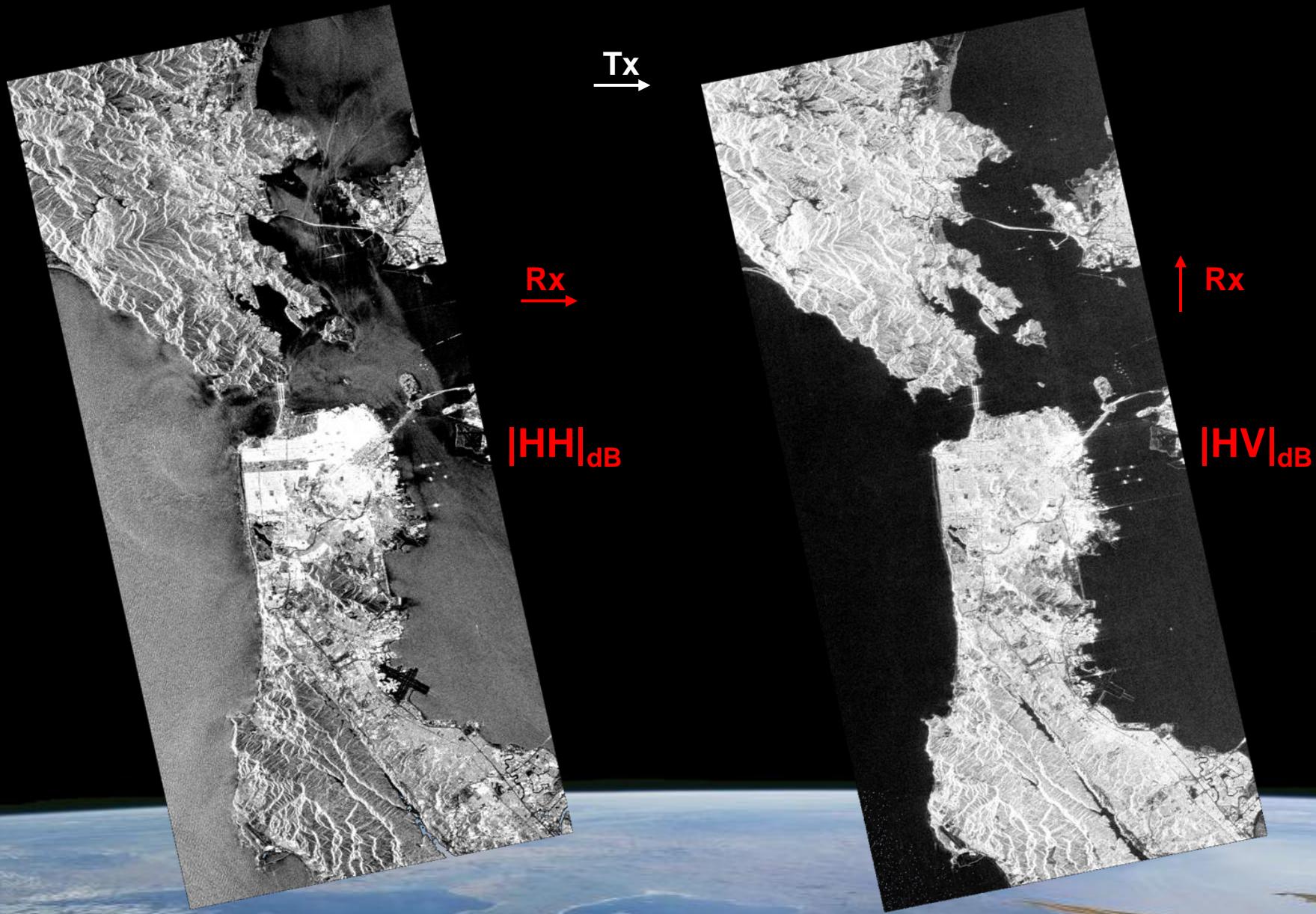
San Francisco Bay – (L-Band)



Wave Polarimetry



Space-borne Sensors



San Francisco Bay – (L-Band)

Space-borne PolSAR Sensors

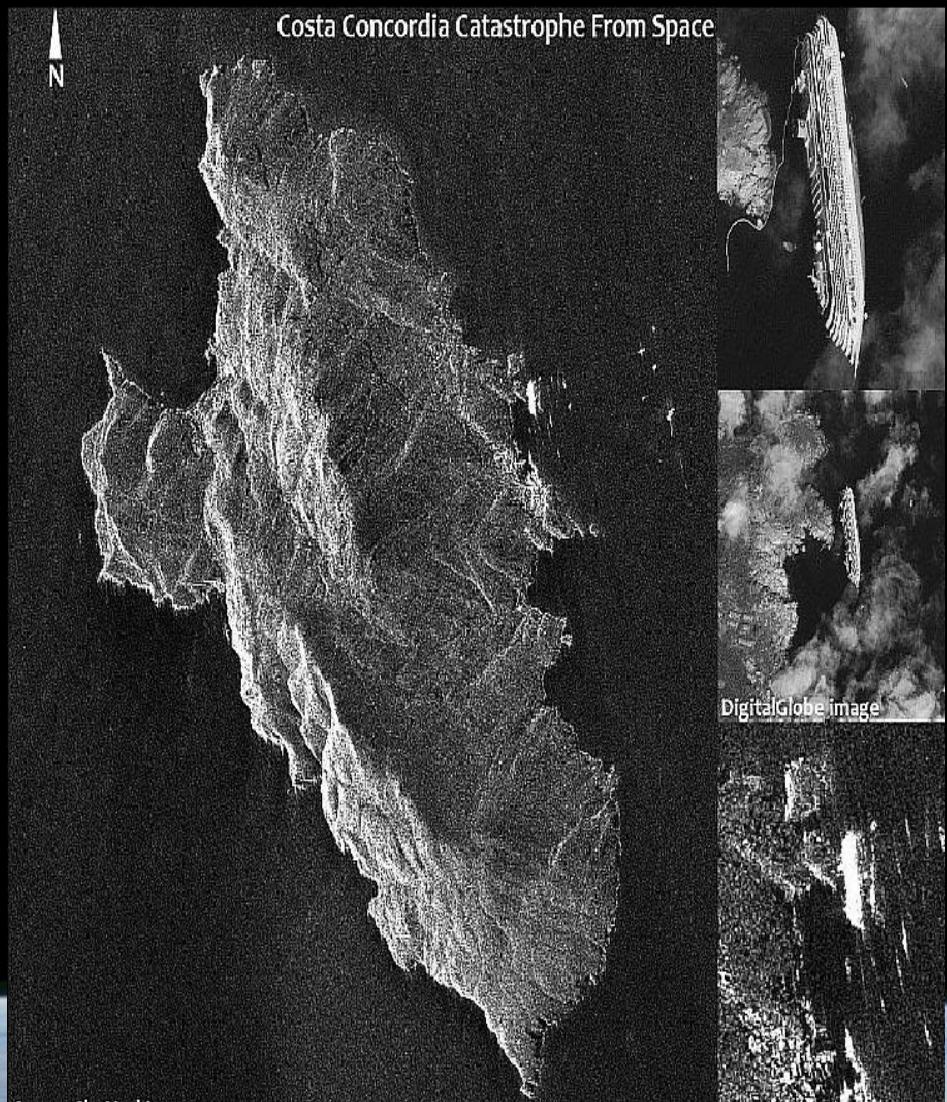
ENVISAT - ASAR

October 2001
C-Band (Sngl / Dual Inc)



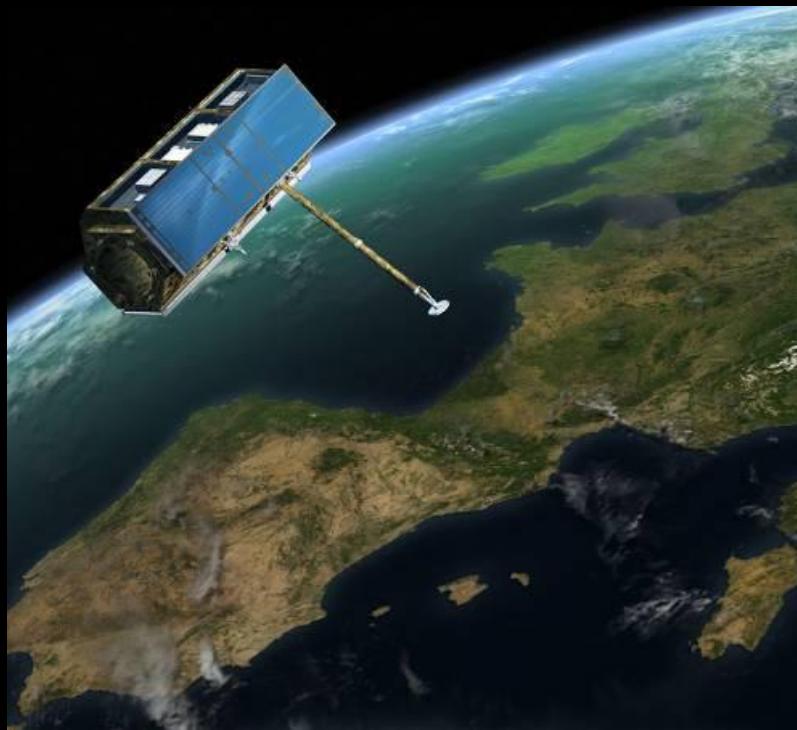
Space-borne PolSAR Sensors

COSMO - SkyMed



Space-borne PolSAR Sensors

TerraSAR - X



Rostok (Twin)



June 2007

X-Band (Sngl / Twin HH-VV / Quad Exp.)



Space-borne PolSAR Sensors

RISAT-1A



26 April 2012
C-Band (Sngl, Dual, Hybrid)
Operational since 2015

Rajasthan (Dual)



Sabarmati (Hybrid)



Kolkata (Hybrid)

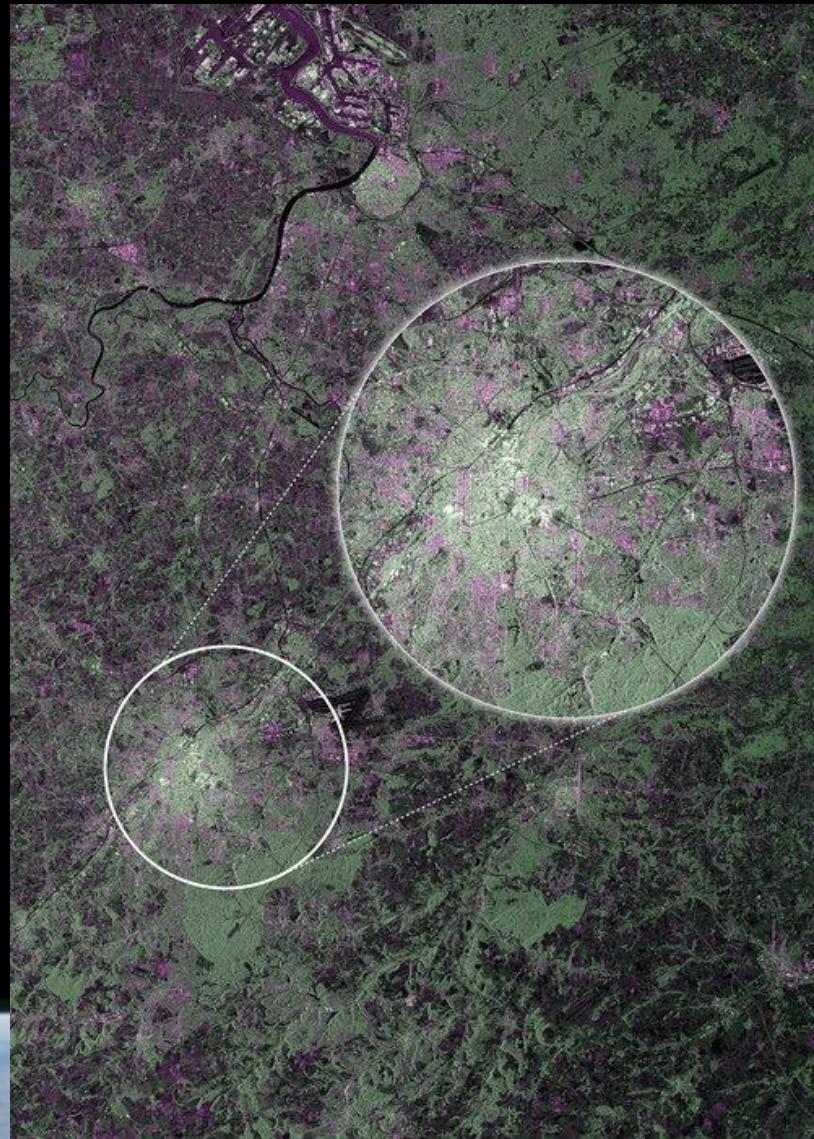


Space-borne PolSAR Sensors

SENTINEL – 1A



S1A : April 2014 S1B : April 2016
C-Band (Sngl, Dual)
Revisit : 6 days

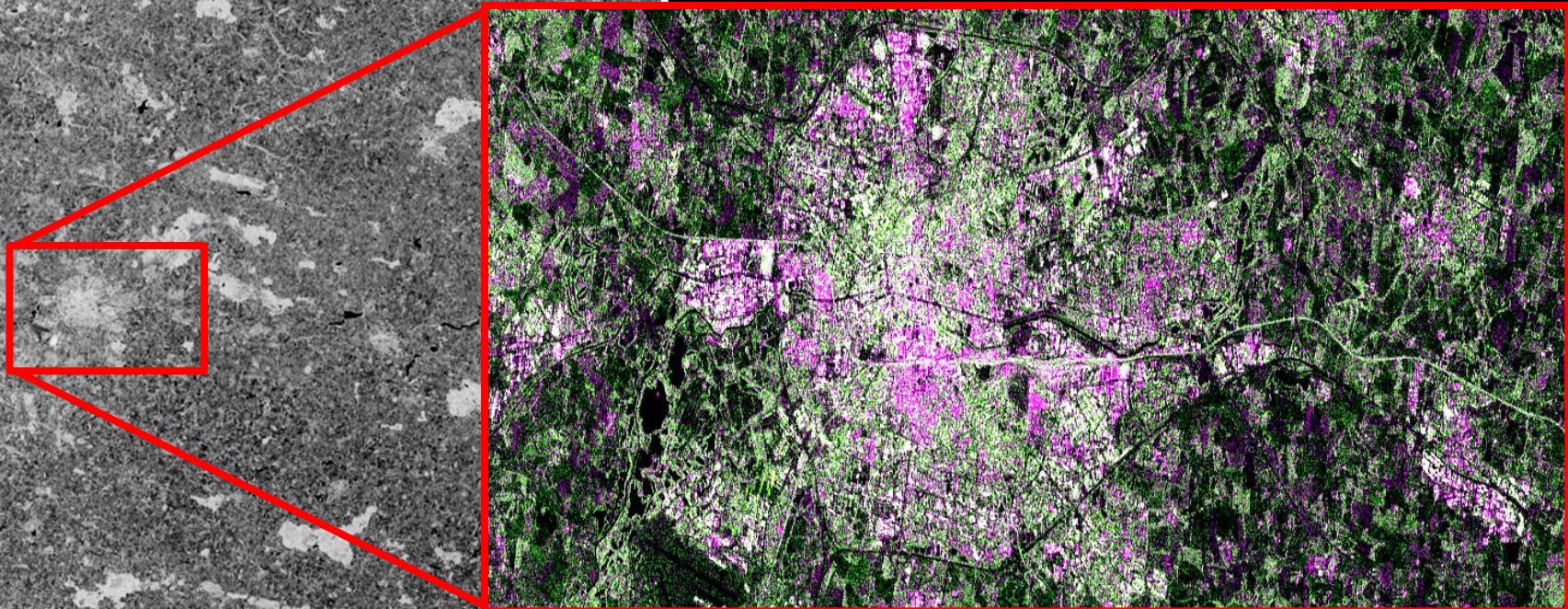


Brussels – 12 April 2014

Space-borne PolSAR Sensors



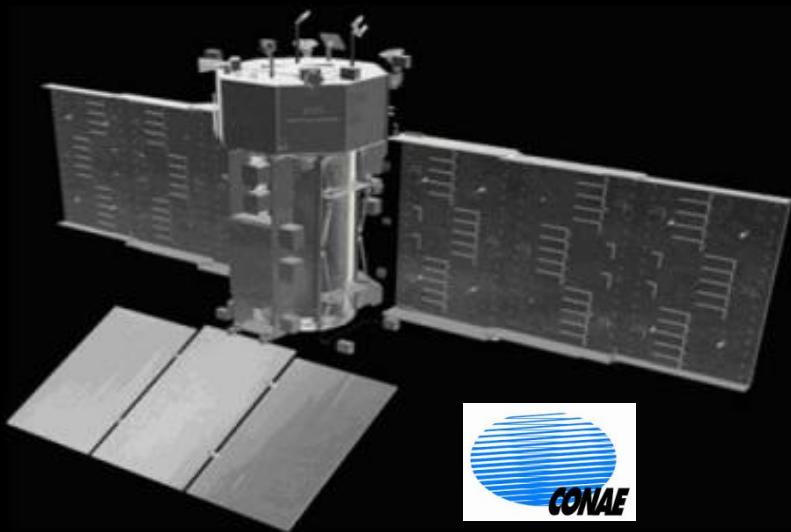
Rennes
Brittany
France



17/08/2016 @ 17h56

Space-borne PolSAR Sensors

SAOCOM – SAR-L



1A : 2017

1B : 2018

2A : 2019

2B : 2020

L-Band (Sngl, Dual, Twin HH-VV)

Revisit : 4 days

RADARSAT Constellation Mission (RCM)



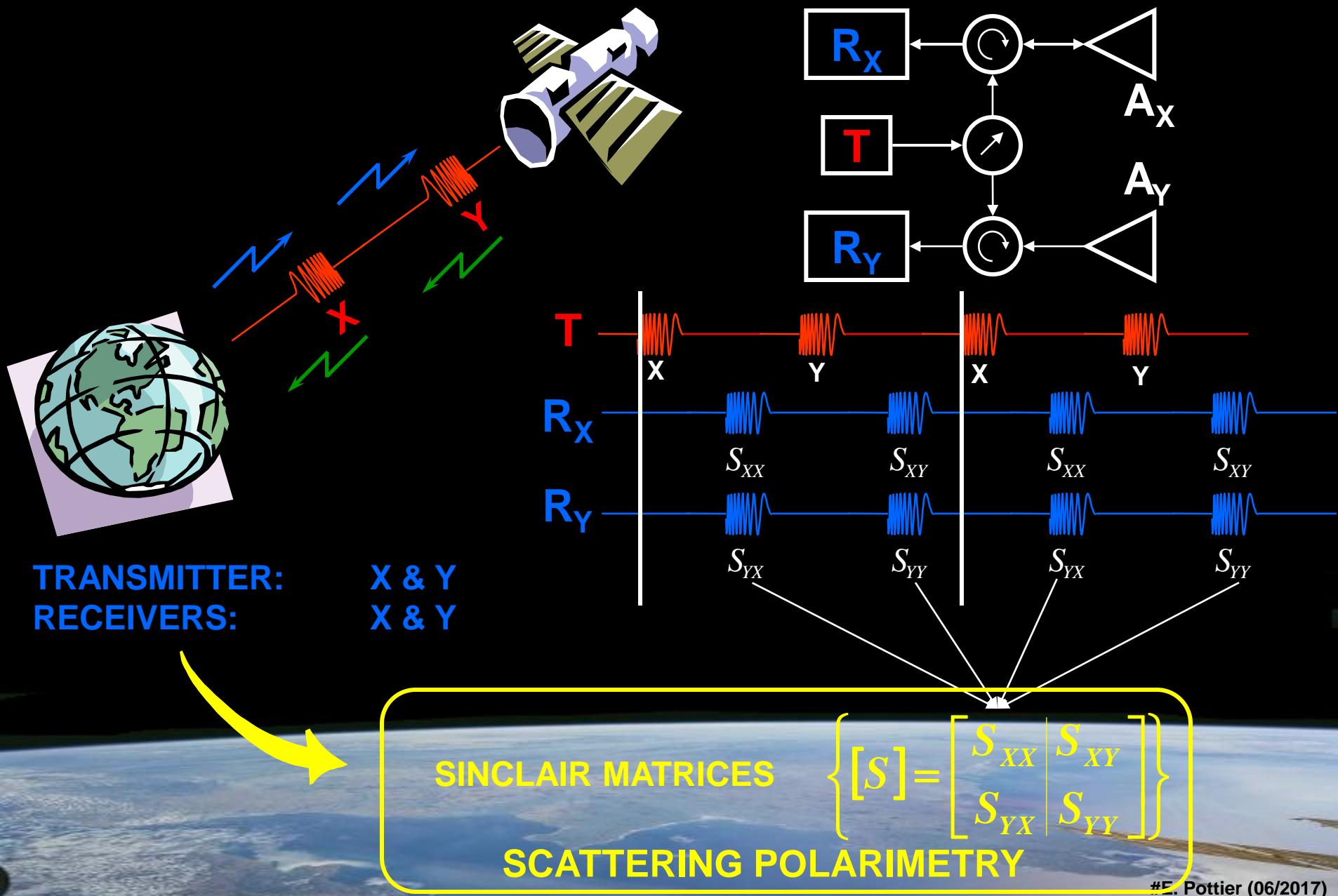
1A : 2017

1B / 1C : 2018

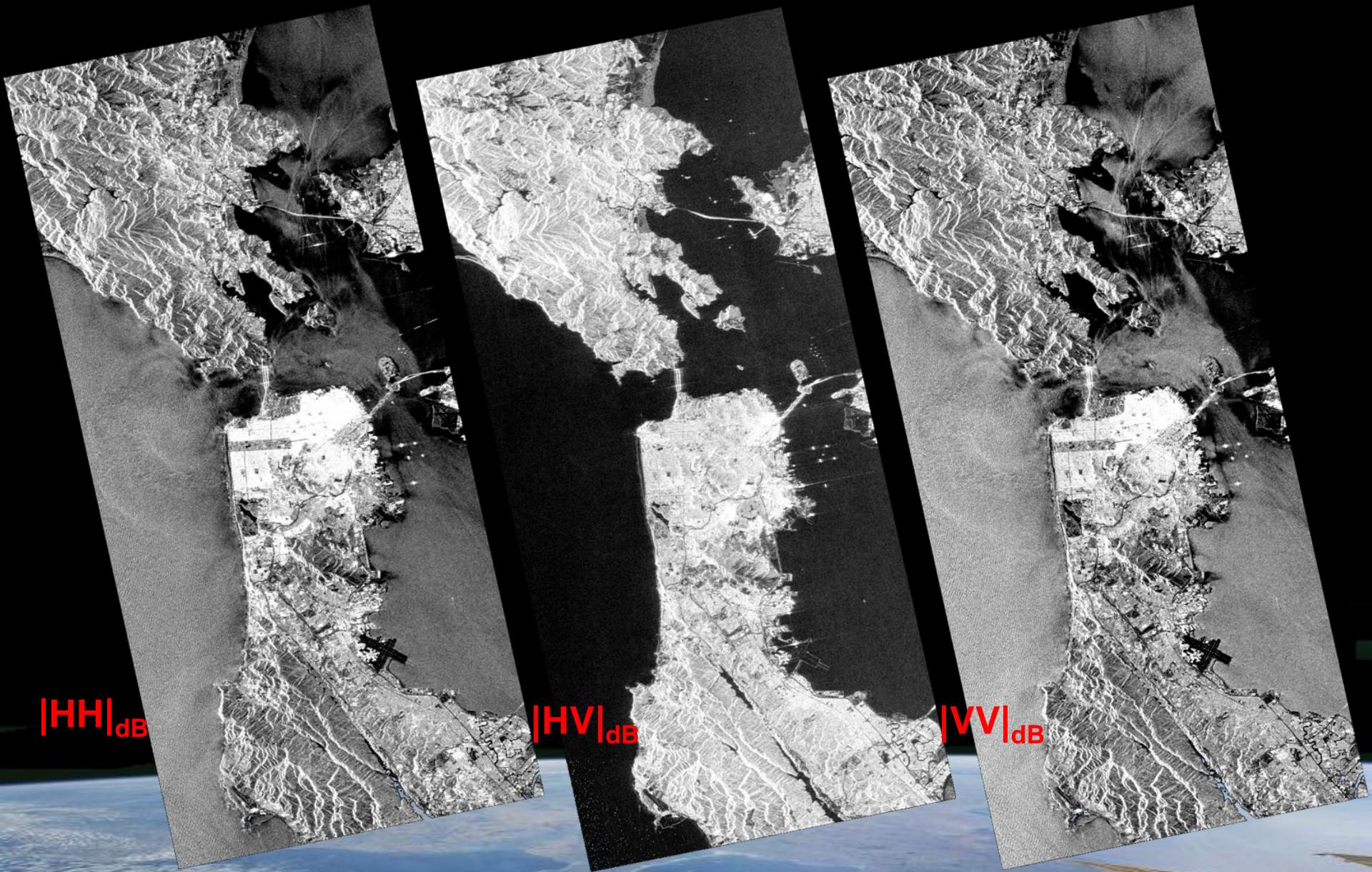
C-Band (Sngl, Dual, Hybrid)

Revisit : 4 days

Scattering Polarimetry



Space-borne Sensors



San Francisco Bay – (L-Band)

Space-borne Sensors



$|HH|_{dB}$

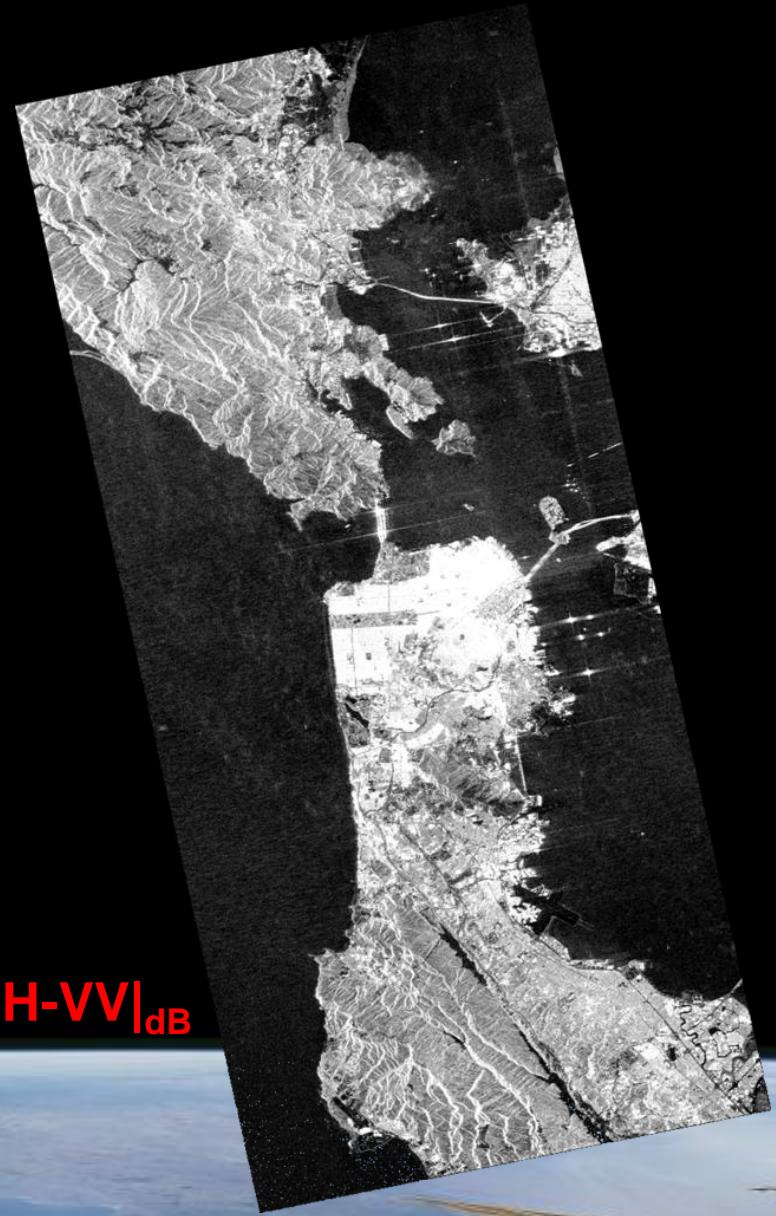
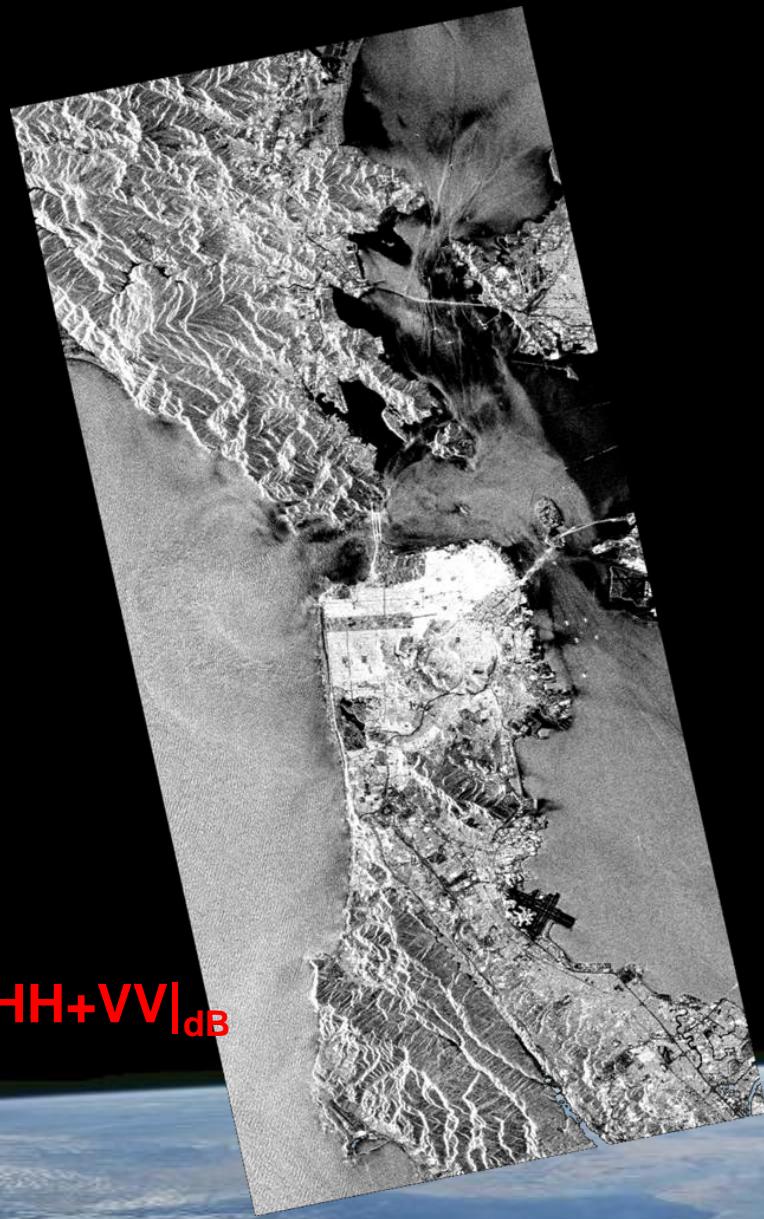
$|HV|_{dB}$

$|VV|_{dB}$



San Francisco Bay – (L-Band)

Space-borne Sensors



San Francisco Bay – (L-Band)

Space-borne Sensors



$|HH+VV|_{dB}$

$|HV|_{dB}$

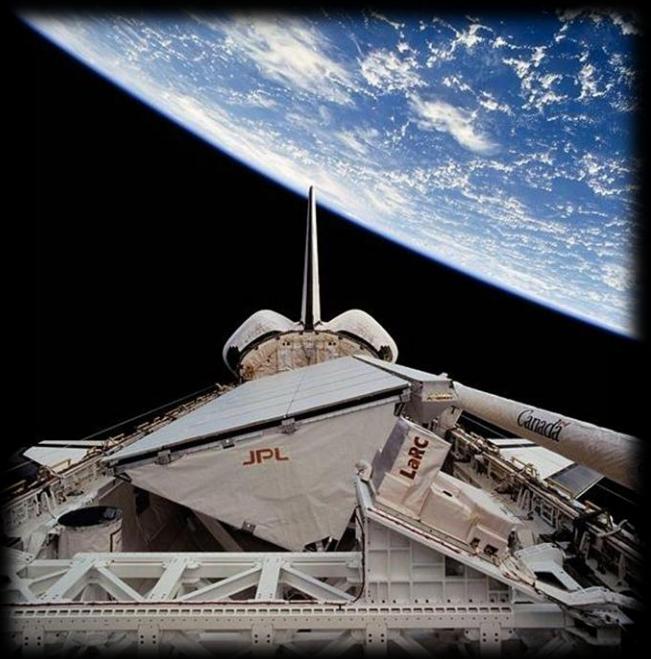
$|HH-VV|_{dB}$



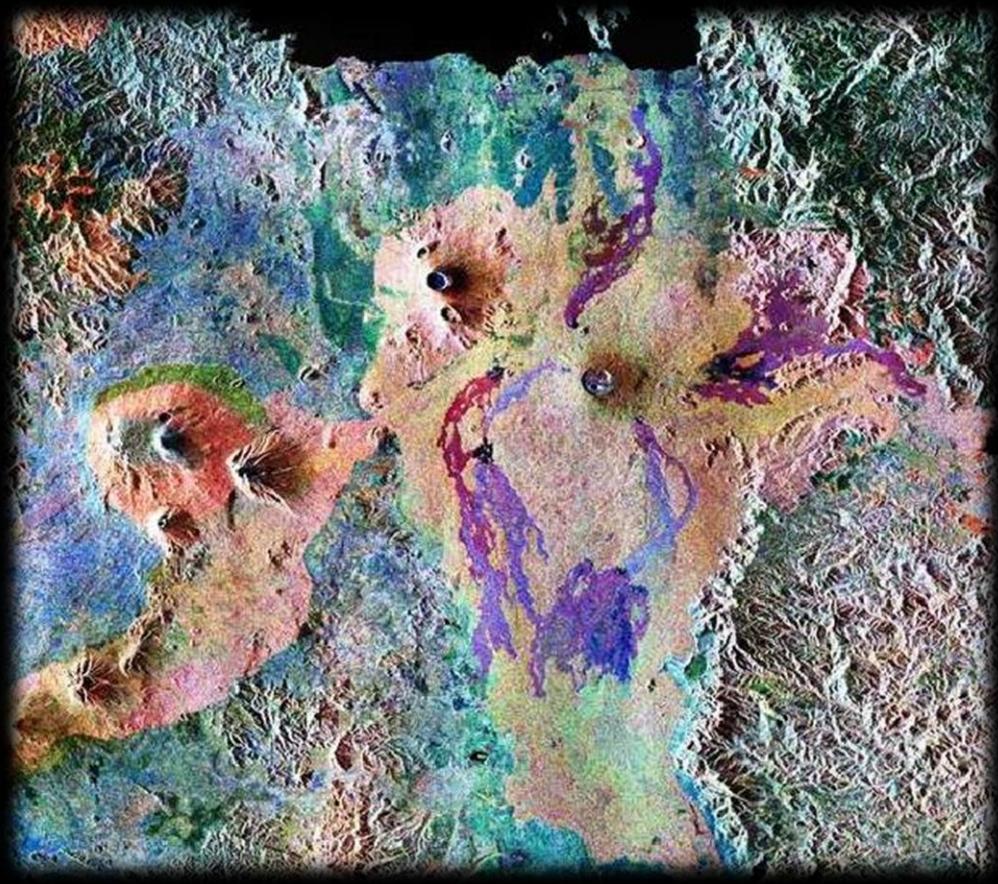
San Francisco Bay – (L-Band)

Space-borne PolSAR Sensors

SIR-C / X-SAR



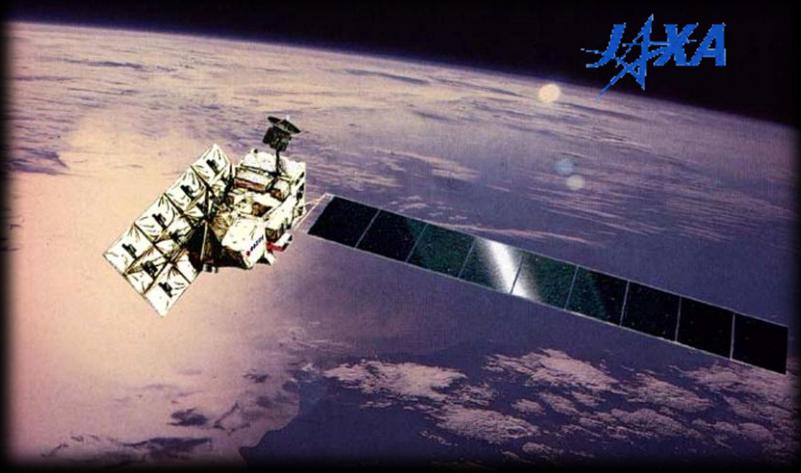
April 1994
L- and C-Band (Quad)
X-Band (Sngl)



Rwanda, Zaire, Uganda

Space-borne PolSAR Sensors

ALOS - PALSAR



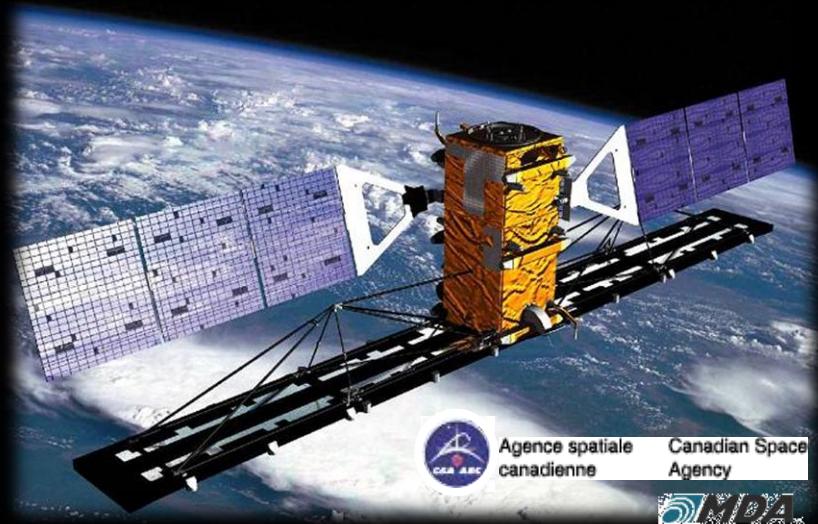
January 2006
L-Band (Sngl / Twin / Quad)



ALOS : Advanced Land Observing Satellite
PALSAR : Phase Array L-Band SAR

Space-borne PolSAR Sensors

RADARSAT - 2



December 2007
C-Band (Quad)



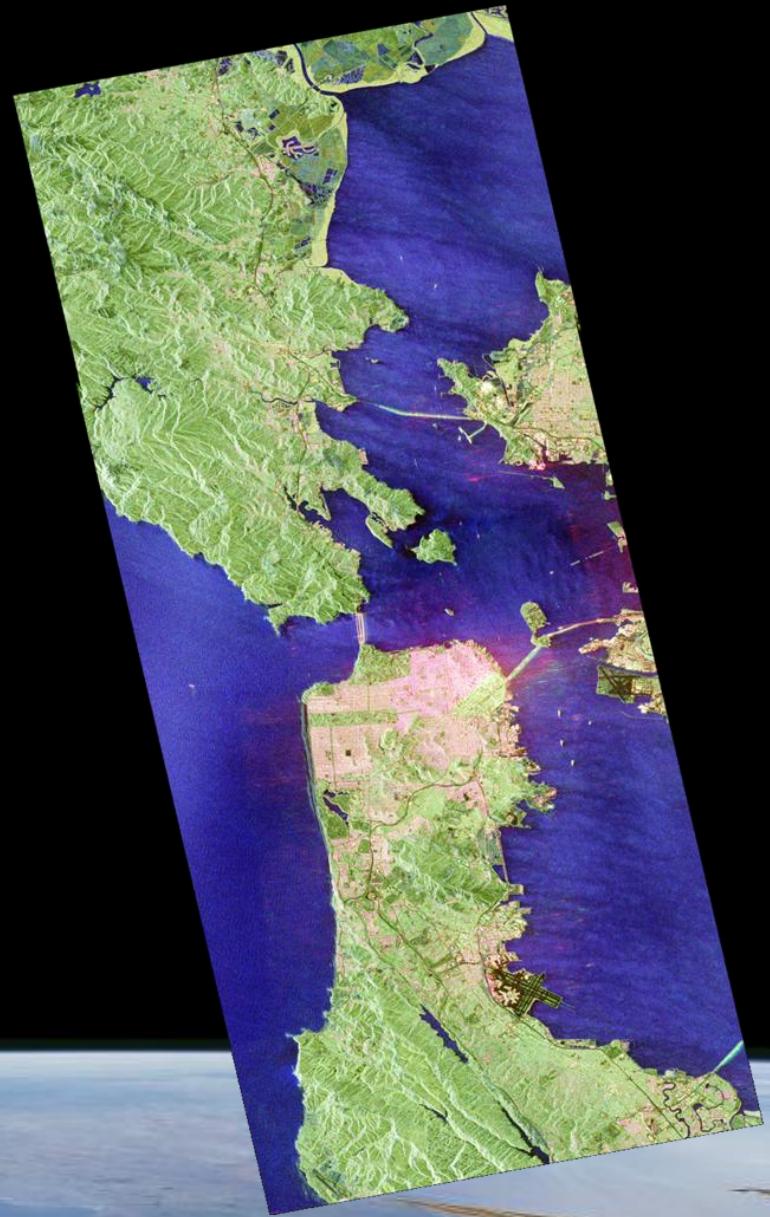
Space-borne Sensors



$|\text{HH}+\text{VV}|_{\text{dB}}$

$|\text{HV}|_{\text{dB}}$

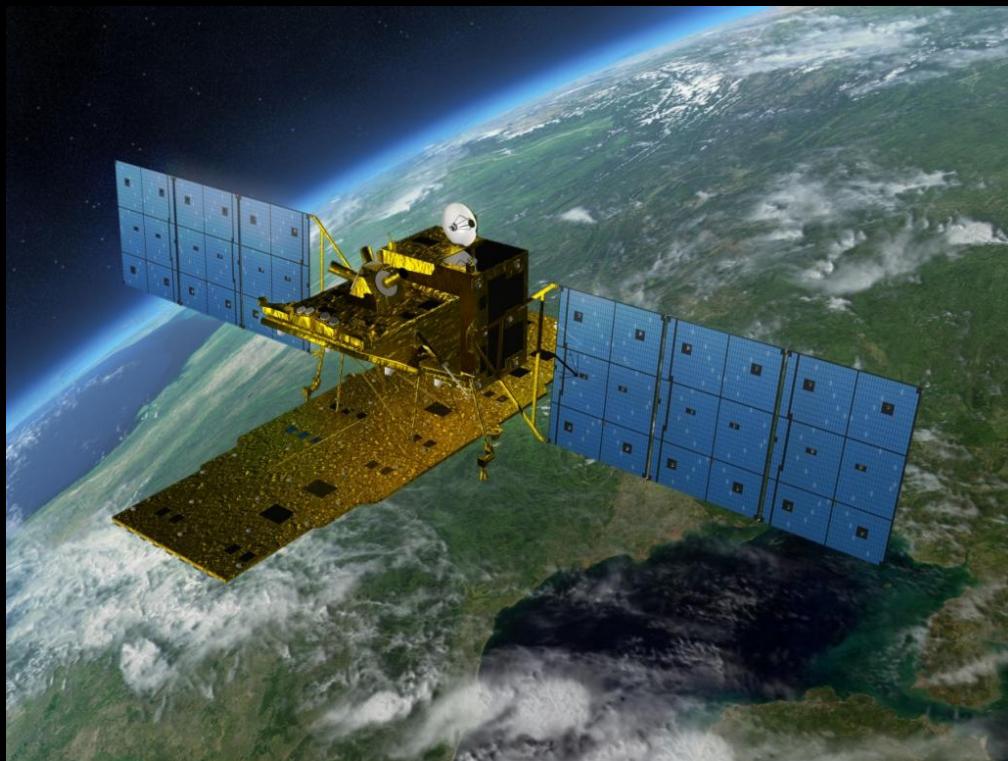
$|\text{HH}-\text{VV}|_{\text{dB}}$



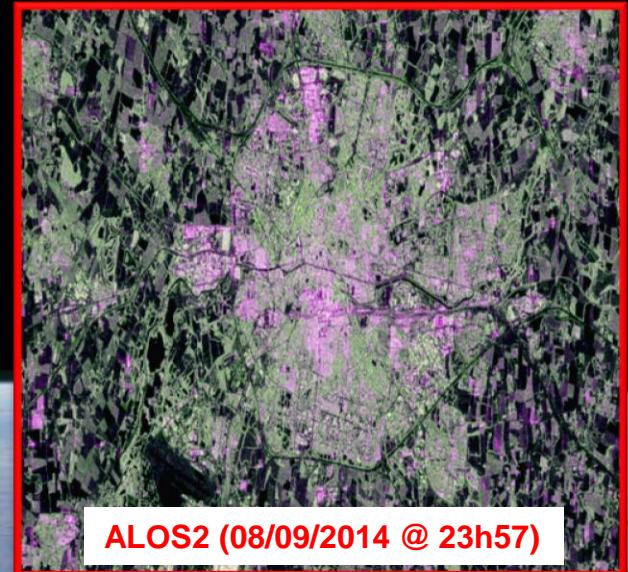
San Francisco Bay – (L-Band and C-Band)

Space-borne PolSAR Sensors

ALOS - 2



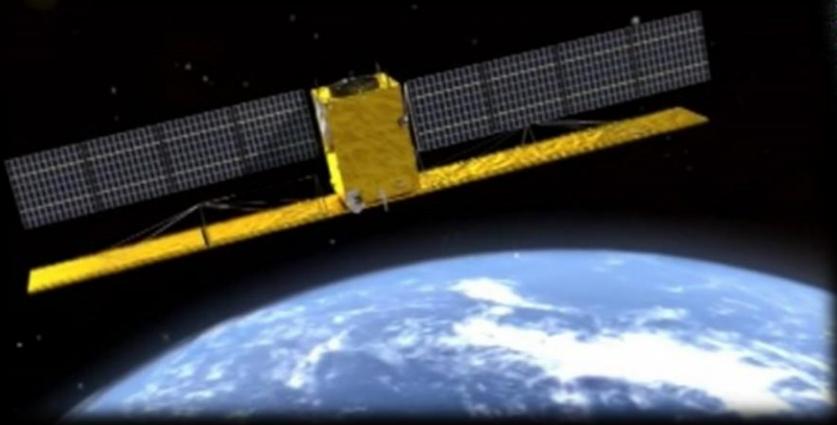
May 2014
L-Band (Quad)



Space-borne PolSAR Sensors

Chang Zheng-4C - GaoFen-3 (GF-3)

Long March-4C - High Resolution-3



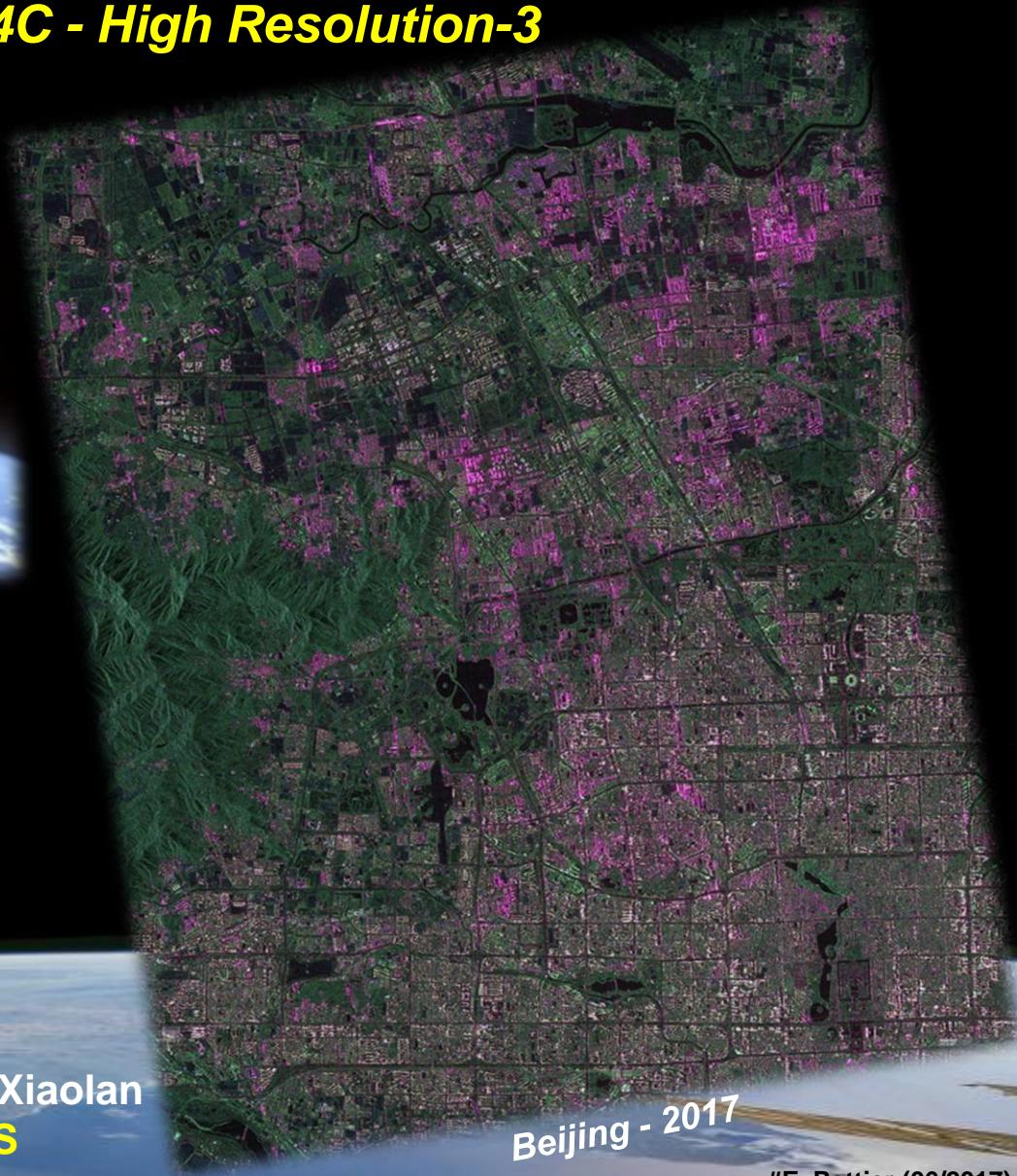
August 2016
C-Band (Quad)



中国空间技术研究院
China Academy of Space Technology



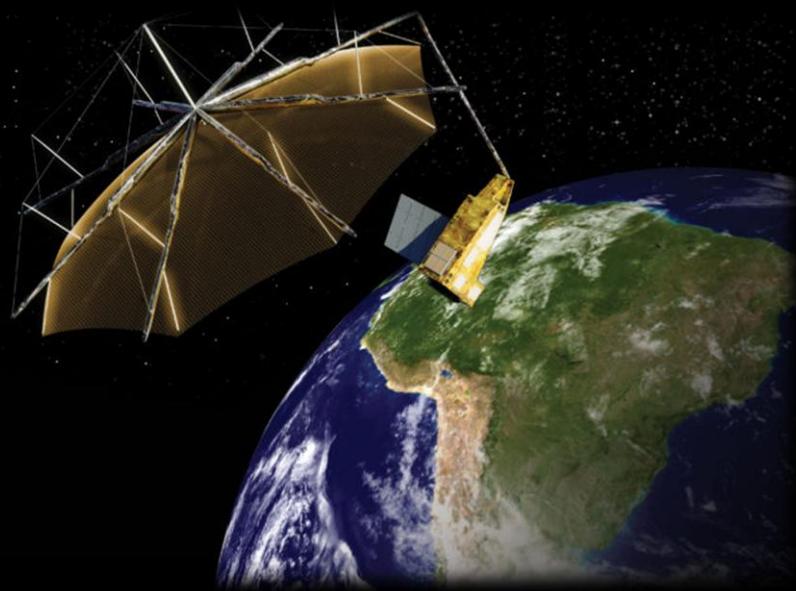
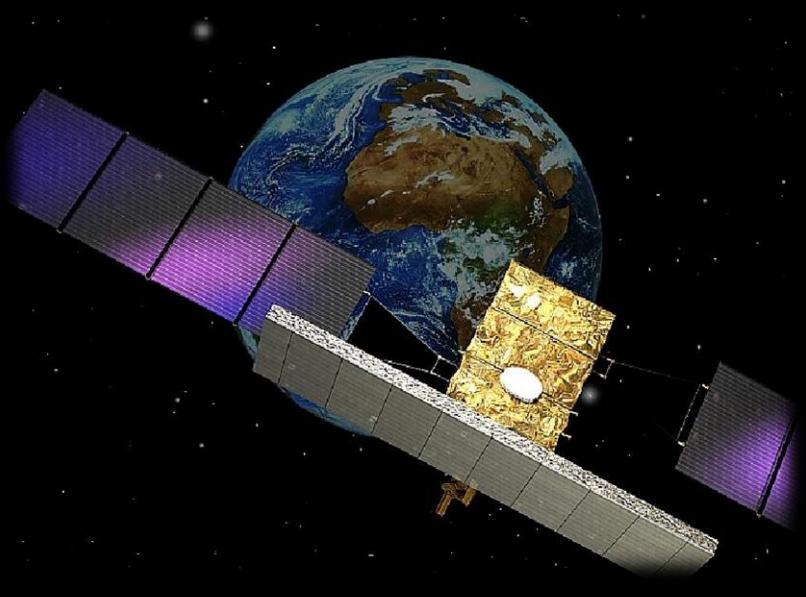
Courtesy of Dr. Qiu Xiaolan
IECAS / GIPAS



Space-borne PolSAR Sensors

COSMO - SkyMed - CSG

Earth Explorer - BIOMASS



2A : 2018

2B : 2019

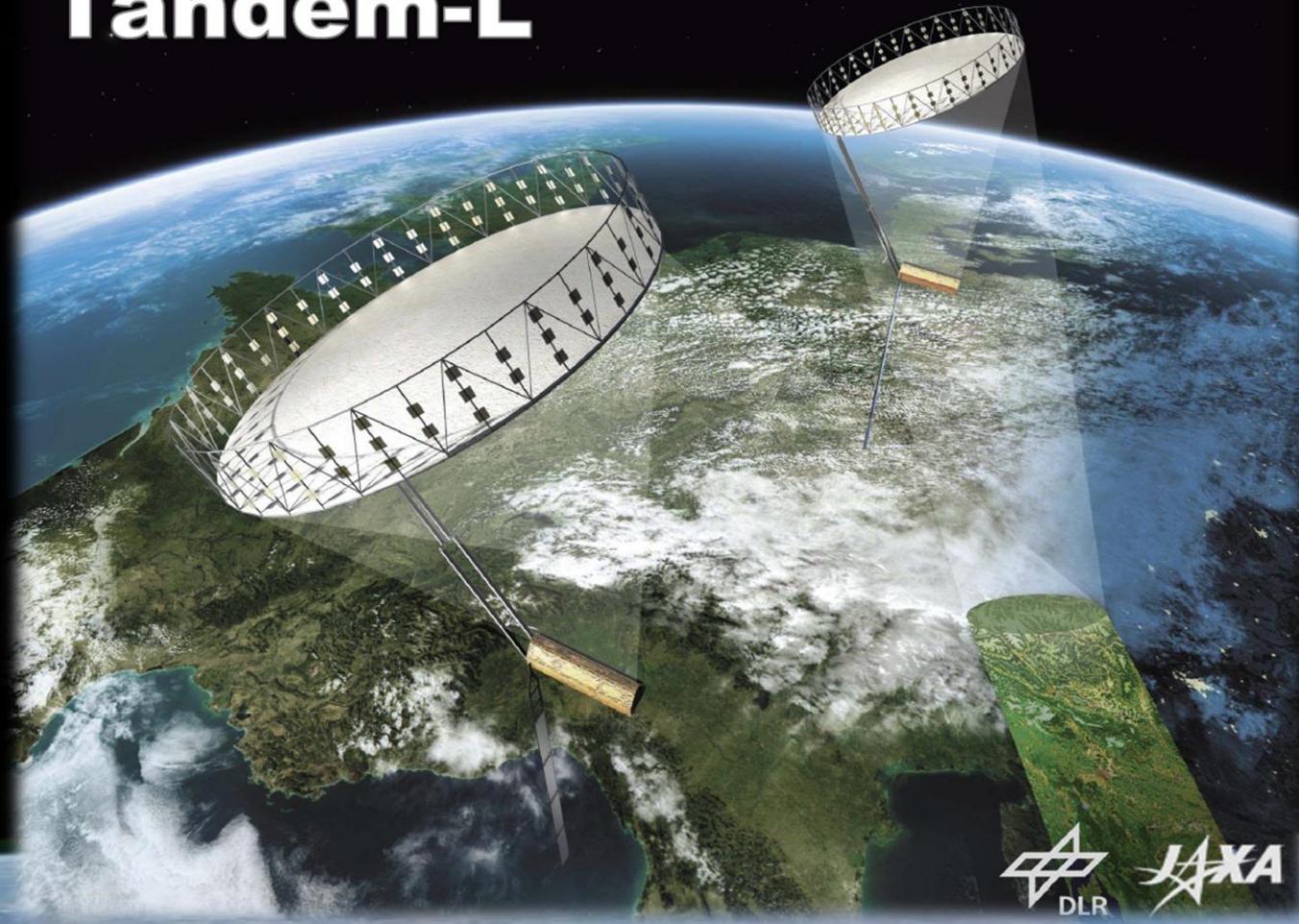
X-Band (Sngl / Dual / Quad Exp.)

2021

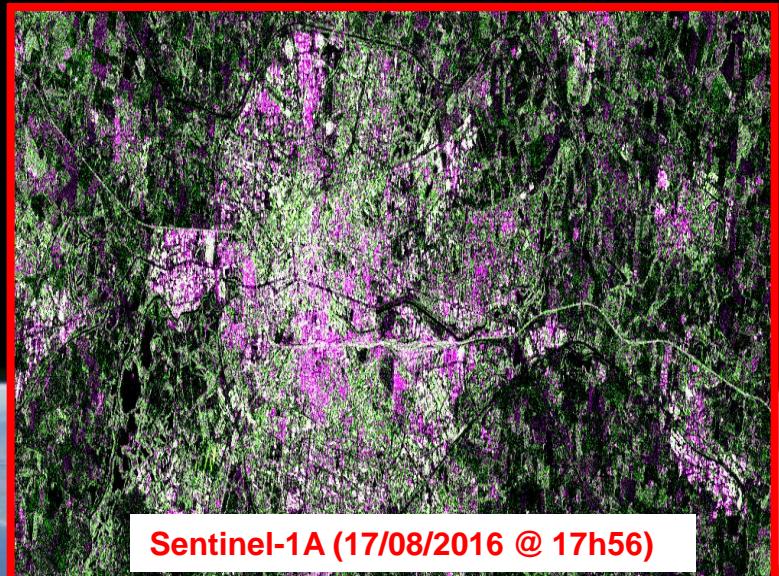
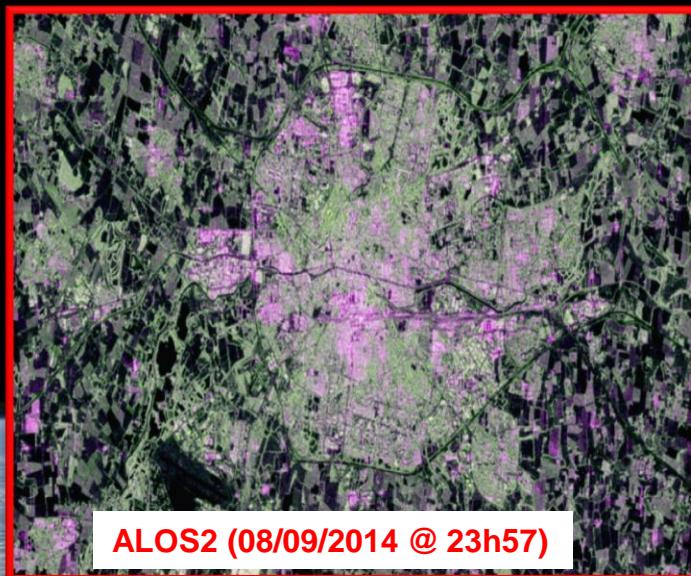
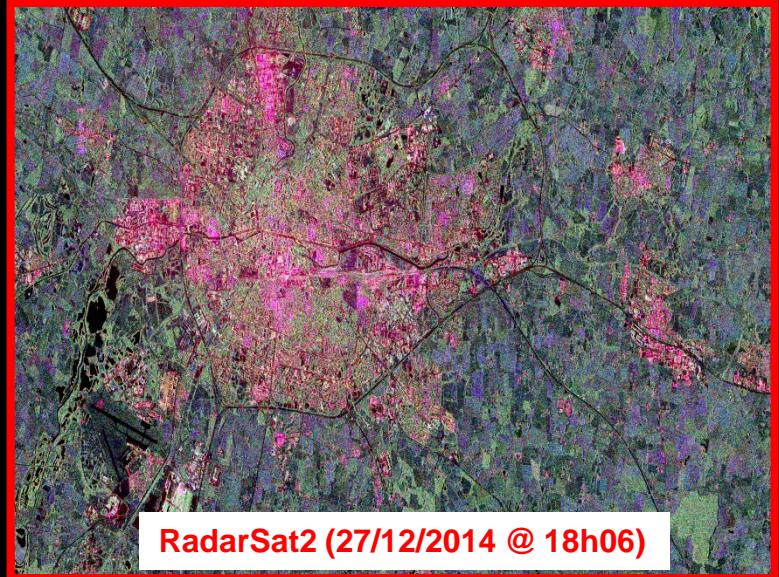
P-Band (Quad)

Space-borne PolSAR Sensors

Tandem-L



Space-borne PolSAR Sensors



Space-borne PolSAR Sensors



Chang Zheng-4C - GaoFen-3 (GF-3)
(03/01/2017 @ 17h49)

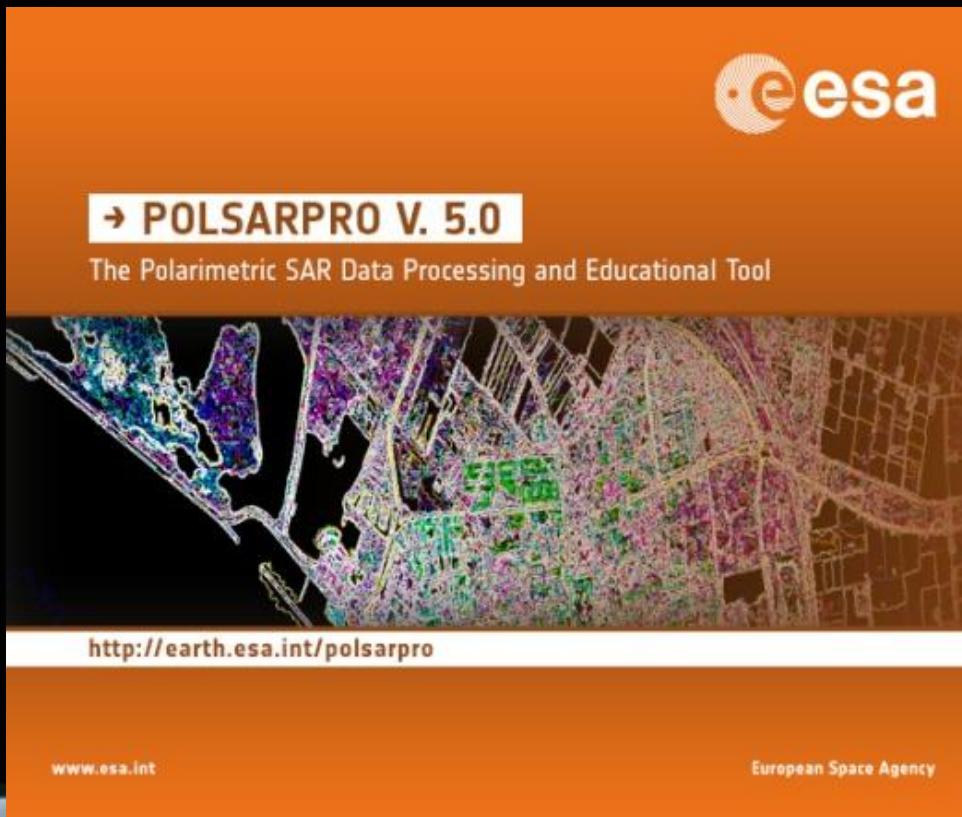
What About



Software / Toolbox ?

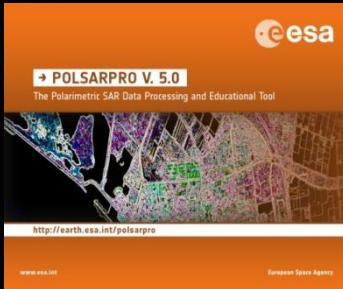
ESA PolSARpro Toolbox

The Polarimetric SAR Data Processing and Educational Toolbox



ESA PolSARpro Toolbox

Polarimetric SAR data processing and educational toolbox



ESA funded project since 2003

+ 3000 registered users / + 70 foreign countries

Toolbox specifically designed to handle : Pol-SAR, Pol-InSAR and Pol-TimeSAR data

Educational Software offering a tool for self-education in the field of Polarimetric SAR data processing and analysis

International collaborative project : space agencies (4), research centres (14) and universities (19).

Airborne sensors : AIRSAR, CONVAIR, ESAR, EMISAR, FSAR, PISAR, SATHI, UAVSAR.

Spaceborne sensors : ALOS1, ALOS2, COSMO-Skymed, RADARSAT-2, RISAT, Sentinel 1A/B, TerraSAR-X, Tandem-X,

More than 550 different Pol-SAR, Pol-InSAR, Pol-TomSAR, Pol-TimeSAR functionalities.

ESA PoSARpro Toolbox

<http://earth.esa.int/web/polsarpro>

The Web Site provides

The screenshot shows the homepage of the PoSARpro website. At the top, there's a navigation bar with links for 'Login' and 'Register'. Below the navigation is a main menu with 'Data Sources', 'Overview', 'Download and Installation', 'Documentation', and 'Results & News'. A 'Latest News' sidebar on the right lists several recent releases. Another sidebar on the left contains a list of useful links. The central content area features a large image of a satellite map.

PoSARpro
The Polarimetric SAR Data Processing and Educational Tool

Data Sources Overview Download and Installation Documentation Results & News

You are here Home

• PoSARpro Version 4.2

The PoSARpro Version 4.2 released aims to facilitate the accessibility and exploitation of multi-polarised SAR datasets including those from ESA Third Party Missions (ALOS PALSAR), Envisat ASAR, Alternating Polarisation mode products, RADARSAT-2 and TerraSAR-X.

A wide-range of tutorials and comprehensive documentation provide a grounding in polarimetry and polarimetric interferometry necessary to stimulate research and development of scientific applications that utilise such techniques; the toolbox of processing functions offers users the capability to implement them.

PoSARpro is developed under contract with ESA, a consortium IETR (*Institut d'électronique et de télécommunications de Rennes*) in conjunction with the University of Rennes 1, DLR Microwaves and Radar Institute (HR) of DLR and AEL Consultants, together with Dr Mark Williams. The initiative is a direct result of recommendations made at the [POLInSAR Workshops](#) held at ESRIN since January 2003.

All elements of the PoSARpro project are distributed by ESA free of charge, including the source code.

This website provides details of the project, giving users access to the tutorial material and software, information about sources of multi-polarised data and recently obtained results of POLInSAR studies. Navigate between pages using the menu on the left.

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Latest News

- New PoSARpro version 4.2 released
- New PoSARpro version 4.1.5 released
- New PoSARpro version 4.0 Beta 1.3 released
- PoSARpro v. 4.0 beta 1 training course -
- PoSARpro version 4.0 beta 1 released for

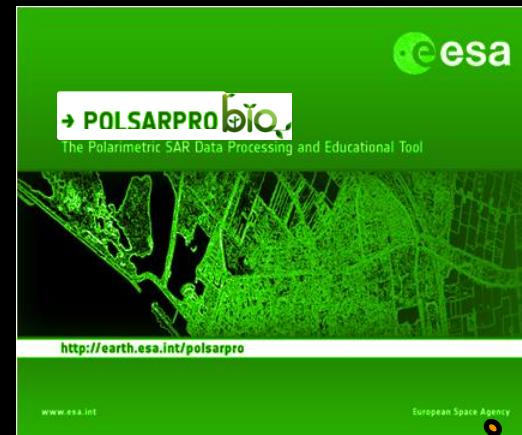
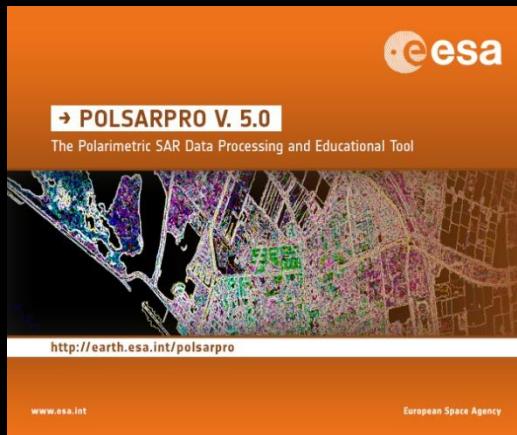
Useful Links

- Home
- Data Sources
- Overview
- Download PoSARpro 4.2
- Release Notes
- Polarimetry Tutorial
- Technical Documentation
- Results & News
- Contact

- **Details of the project**
- **Access to the tutorial and software**
- **Information about status of the development**
- **Demonstration Sample Datasets**

ESA PolSARpro Toolbox

ESA & third party fully polarimetric SAR missions (**PolSARpro-Bio**)



Future spaceborne sensors

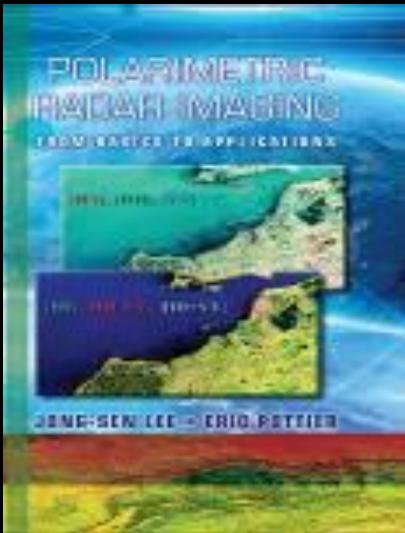
New functionalities : Pol-SAR, Pol-TomSAR and Pol-TimeSAR / Cloud-based infrastructure ...

Learning / Training

Next P.I Generations



Books On Polarimetric Radar SAR, Polarimetric Interferometry

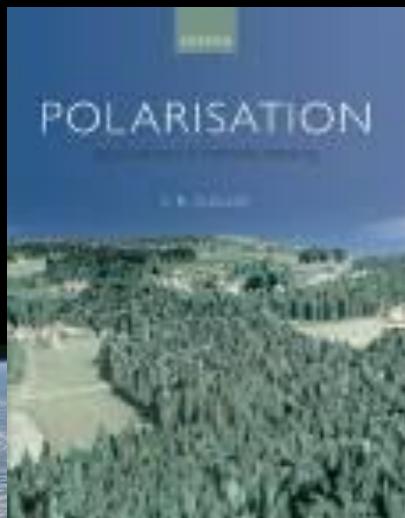


Polarimetric Radar Imaging: From basics to applications

Jong-Sen LEE – Eric POTTIER

CRC Press; 1st ed., February 2009, pp 422

ISBN: 978-1420054972



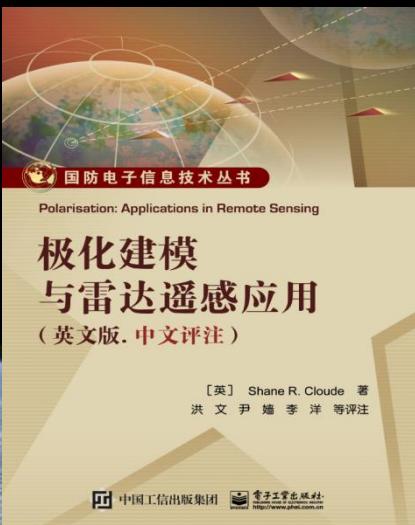
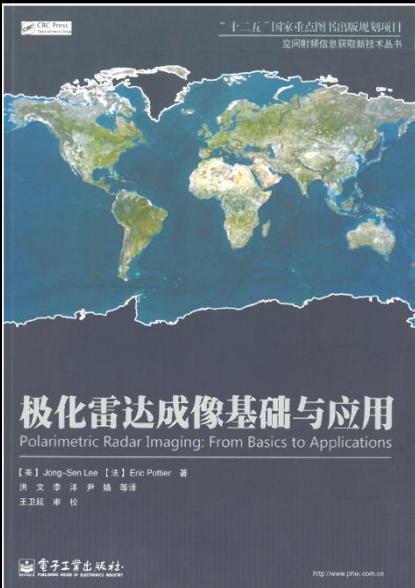
Polarisation: Applications in Remote Sensing

Shane R. CLOUDE

Oxford University Press, October 2009, pp 352

ISBN: 978-0199569731

Books On Polarimetric Radar SAR, Polarimetric Interferometry



Polarimetric Radar Imaging: From basics to applications
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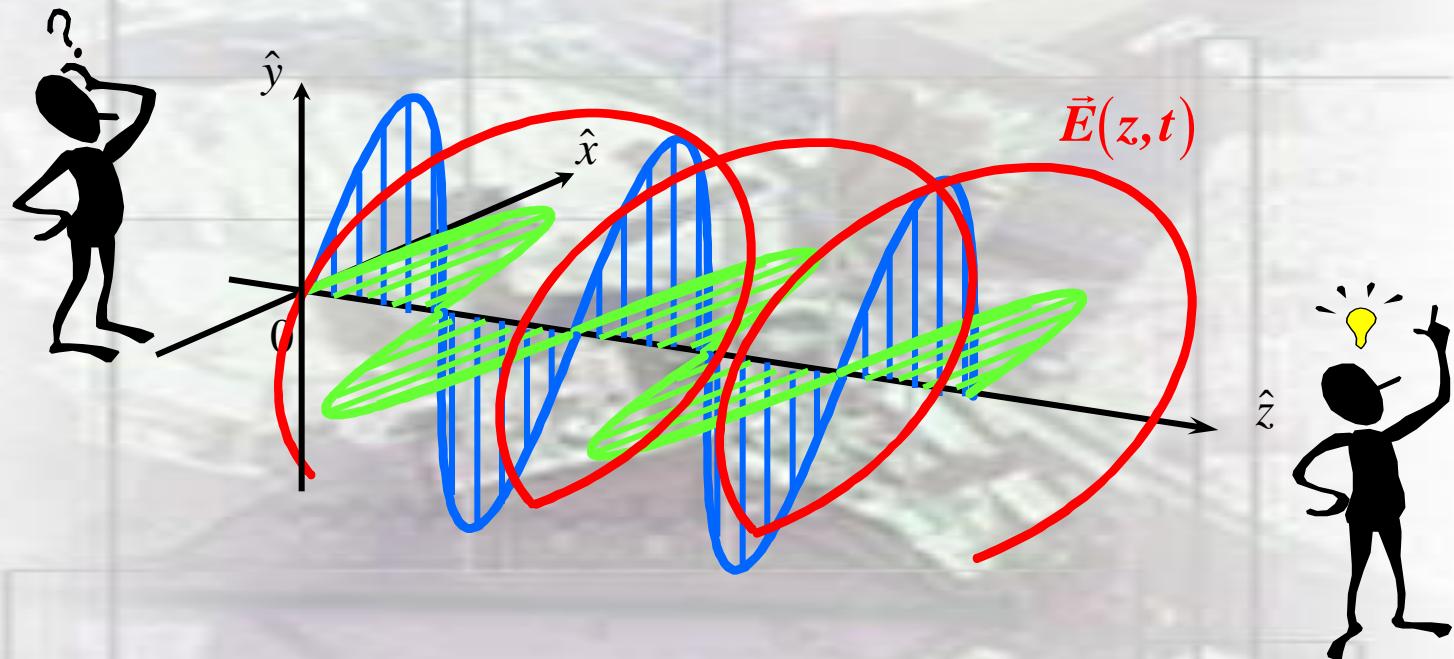
Prof. Wen HONG, Dr. Qiang YIN et al.



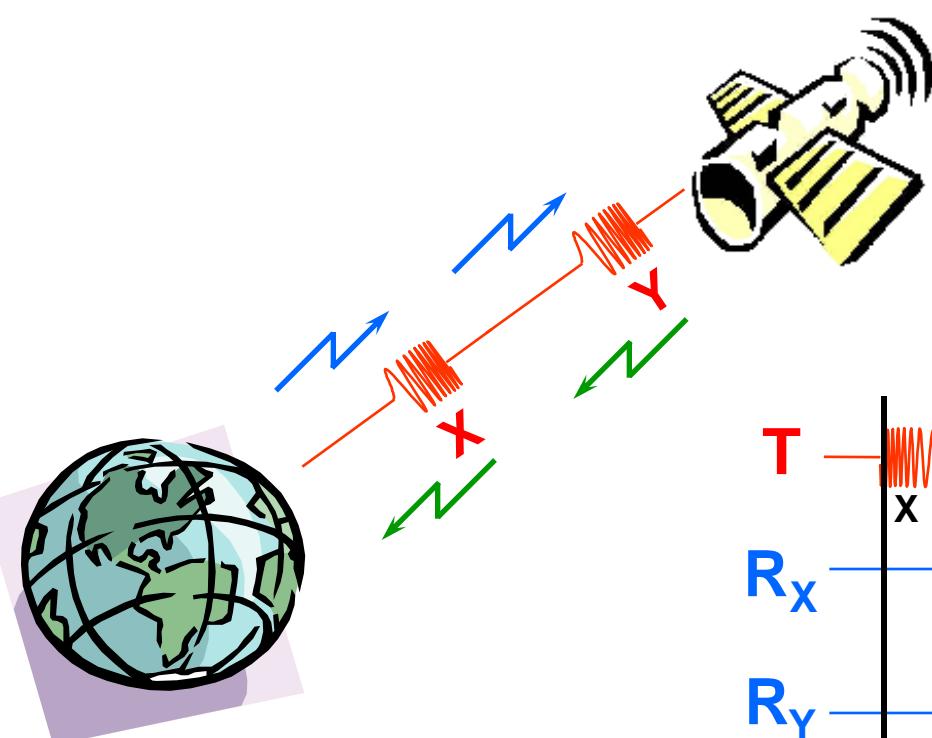
Polarisation: Applications in Remote Sensing
Shane R. CLOUDE
Oxford University Press, October 2009, pp 352
ISBN: 978-0199569731

Questions ?



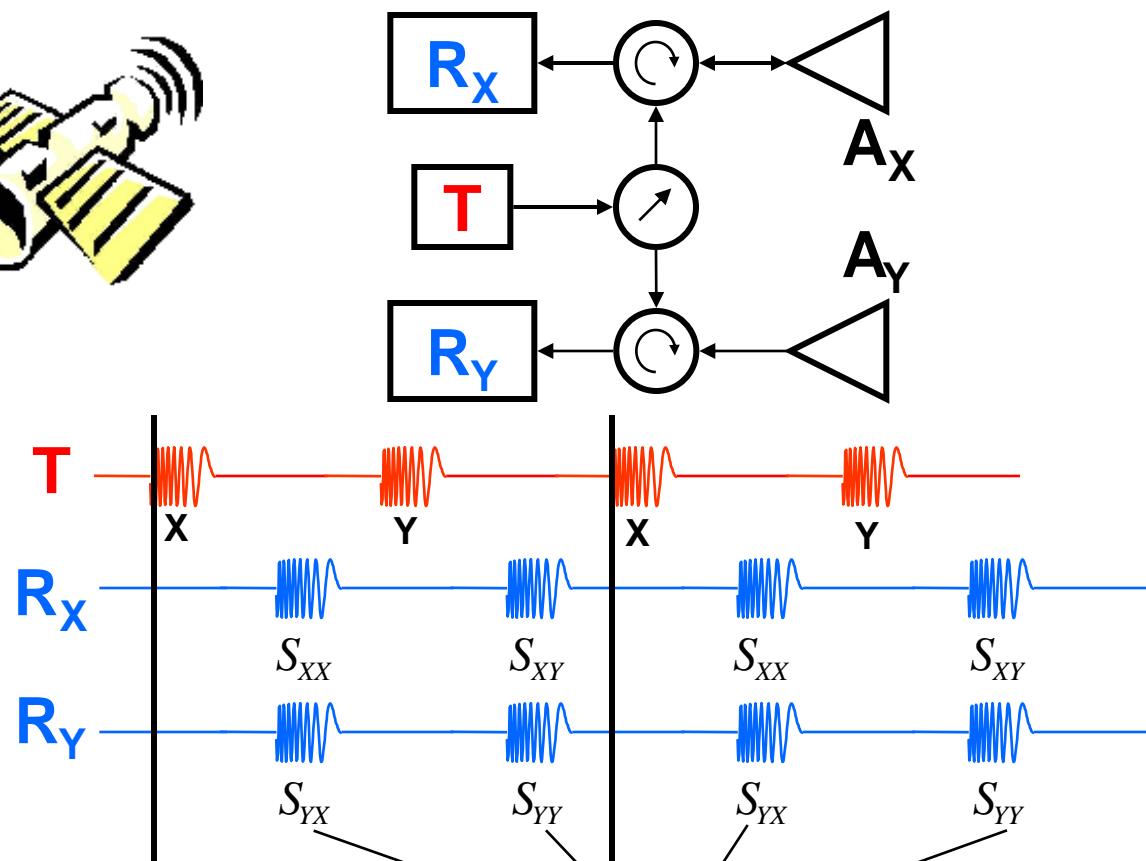


BASIC CONCEPTS



TRANSMITTER:
RECEIVERS:

X & Y
X & Y



SINCLAIR MATRICES

$$\{ [S] = \begin{bmatrix} S_{XX} & S_{XY} \\ S_{YX} & S_{YY} \end{bmatrix} \}$$

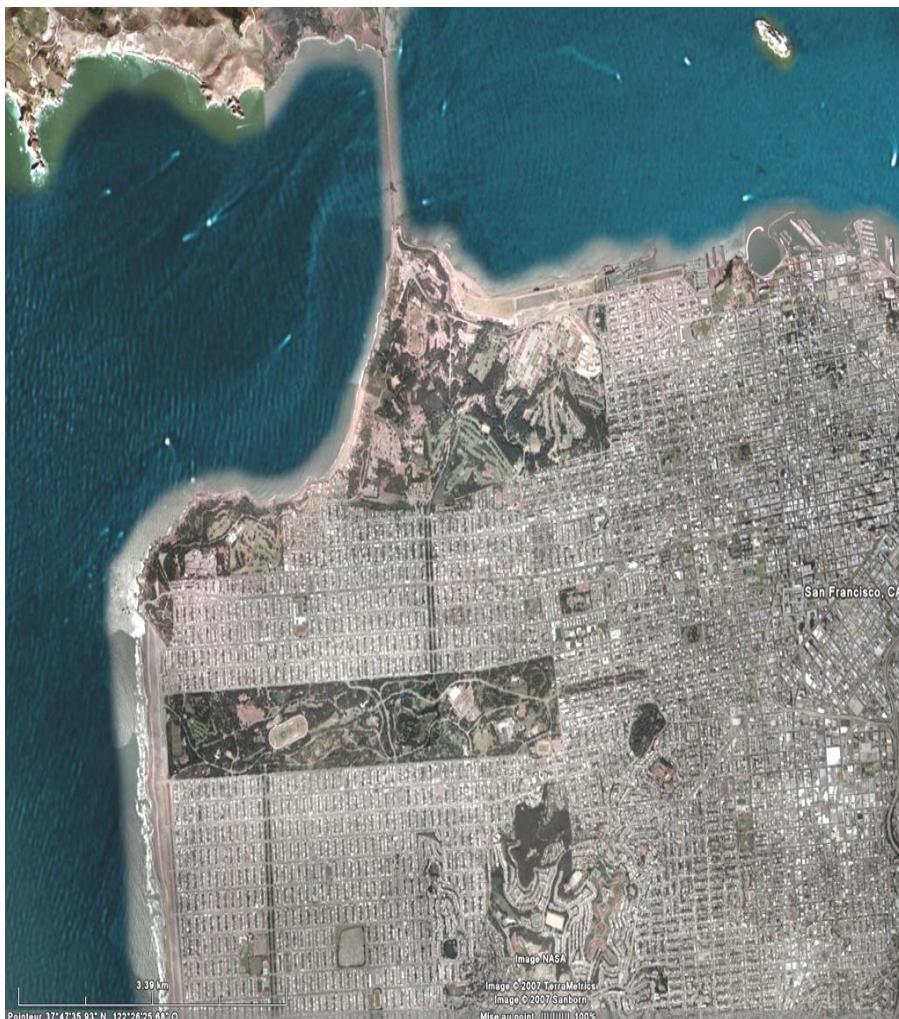
SCATTERING POLARIMETRY

$\xrightarrow{\text{Tx}}$ $\xrightarrow{\text{Rx}}$  $|\mathbf{HH}|_{\text{dB}}$  $|\mathbf{HV}|_{\text{dB}}$

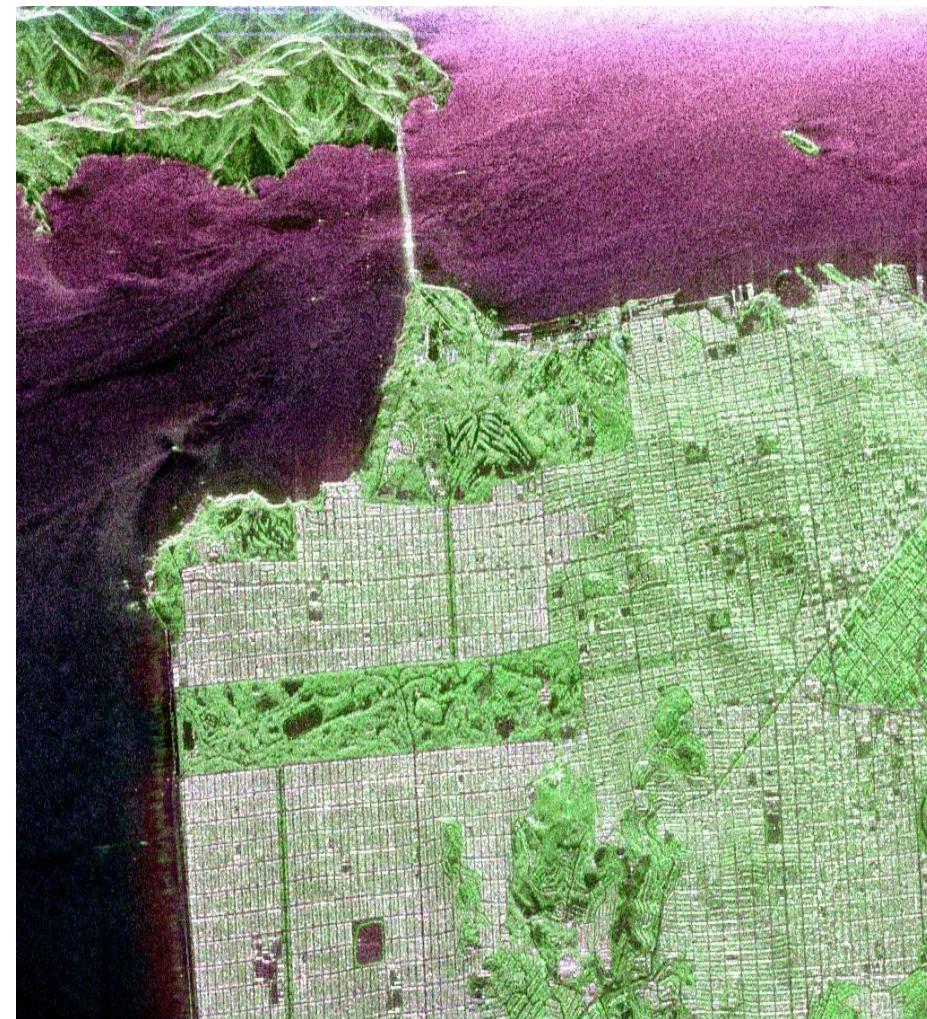
-30dB -15dB 0dB

 $|\mathbf{VV}|_{\text{dB}}$

Sinclair Color Coding



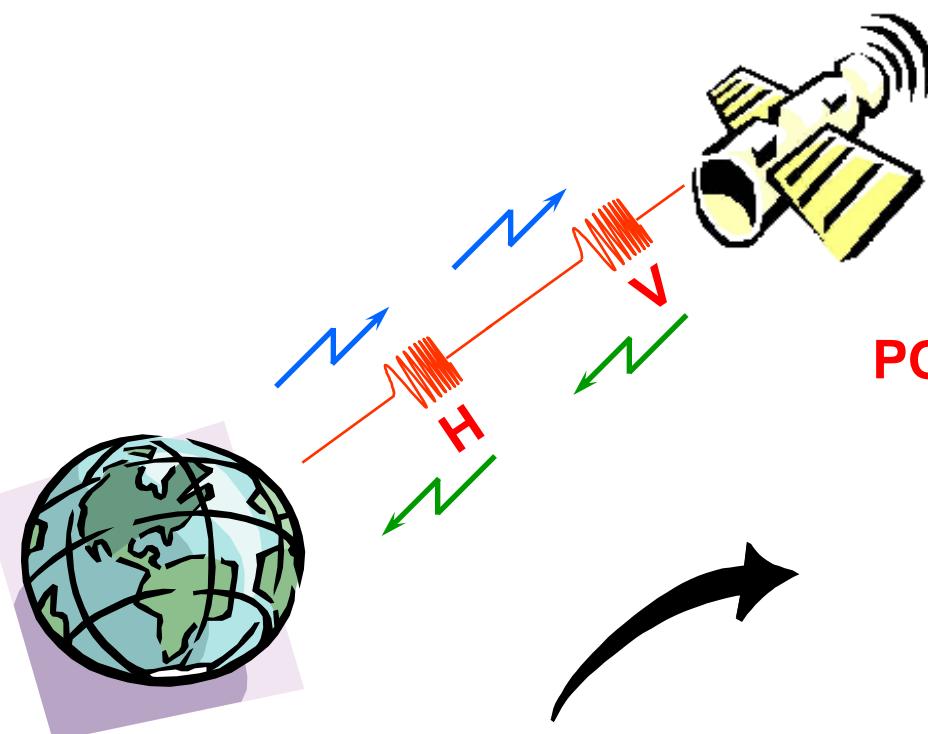
© Google Earth



|HH|

|HV|

|VV|

**POLARIMETRIC DESCRIPTORS****[S] SINCLAIR Matrix**

$$[S] = \begin{bmatrix} S_{HH} & | & S_{HV} \\ S_{VH} & | & S_{VV} \end{bmatrix}$$

TRANSMITTER: H & V
RECEIVERS: H & V**k Target Vector**
[T] 3x3 COHERENCY Matrix

TARGET VECTOR \underline{k}

$$\underline{k} = \frac{1}{\sqrt{2}} [S_{HH} + S_{VV} \quad S_{HH} - S_{VV} \quad 2S_{HV}]^T$$

COHERENCY MATRIX $[T]$

$$[T] = \underline{k} \cdot \underline{k}^{*T} = \begin{bmatrix} 2A_0 & C - jD & H + jG \\ C + jD & B_0 + B & E + jF \\ H - jG & E - jF & B_0 - B \end{bmatrix}$$

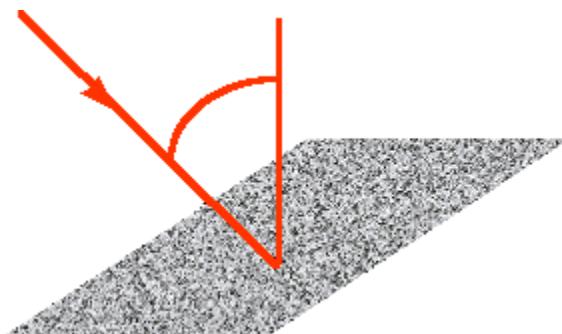
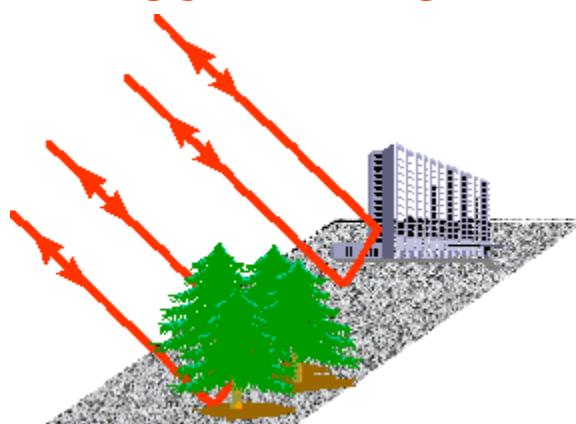
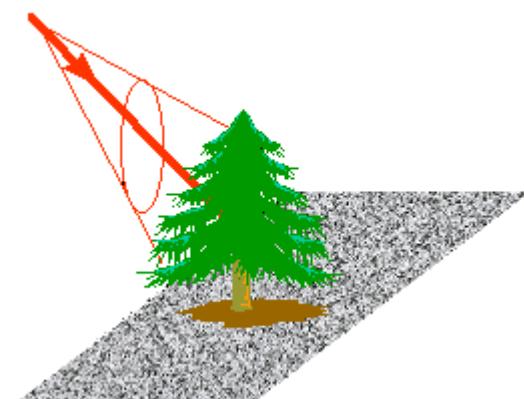
HERMITIAN MATRIX - RANK 1

A0, B0+B, B0-B : HUYNEN TARGET GENERATORS



$[T]$ is closer related to Physical and Geometrical Properties of the Scattering Process, and thus allows a better and direct physical interpretation

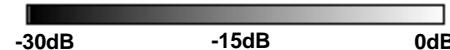
PHYSICAL INTERPRETATION

**SINGLE BOUNCE
SCATTERING
(ROUGH SURFACE)****DOUBLE BOUNCE
SCATTERING****VOLUME
SCATTERING**

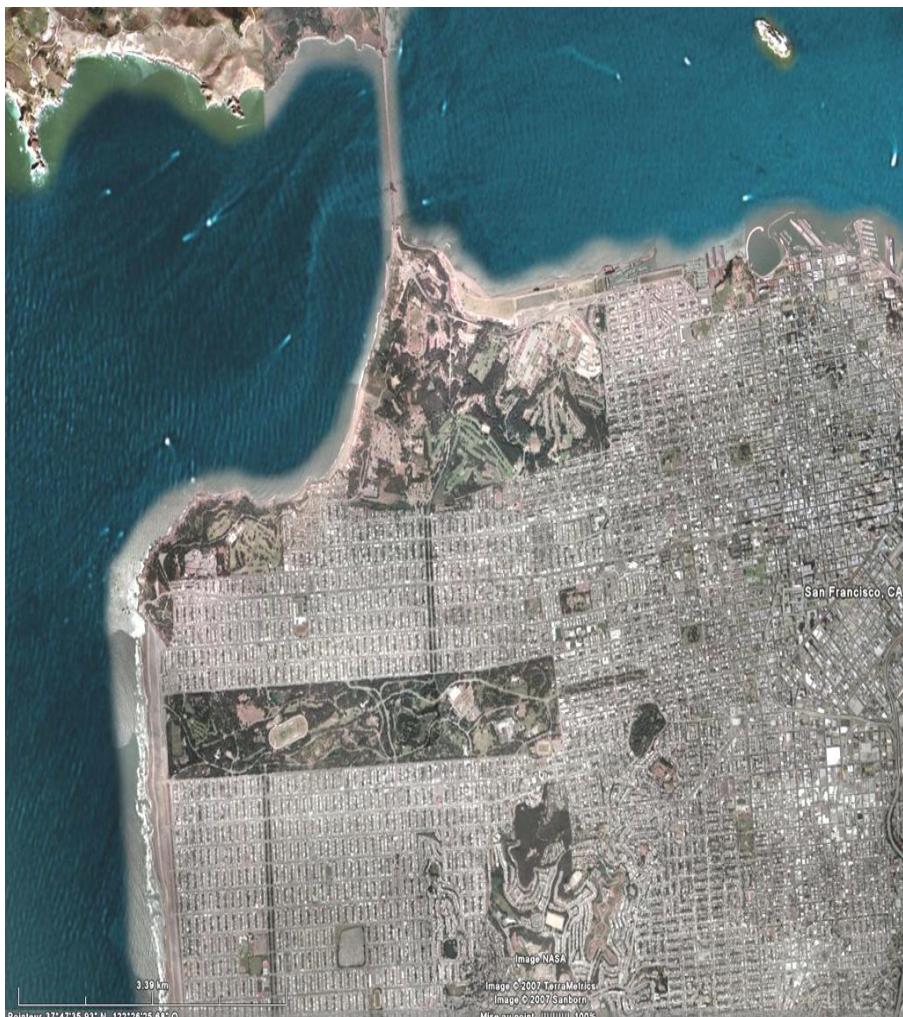
$$T_{11} = 2A_0 = |S_{XX} + S_{YY}|^2$$

$$T_{33} = B_0 - B = 2|S_{XY}|^2$$

$$T_{22} = B_0 + B = |S_{XX} - S_{YY}|^2$$

 $|HH+VV|_{dB}$  $|HV|_{dB}$  $|HH-VV|_{dB}$

TARGET GENERATORS



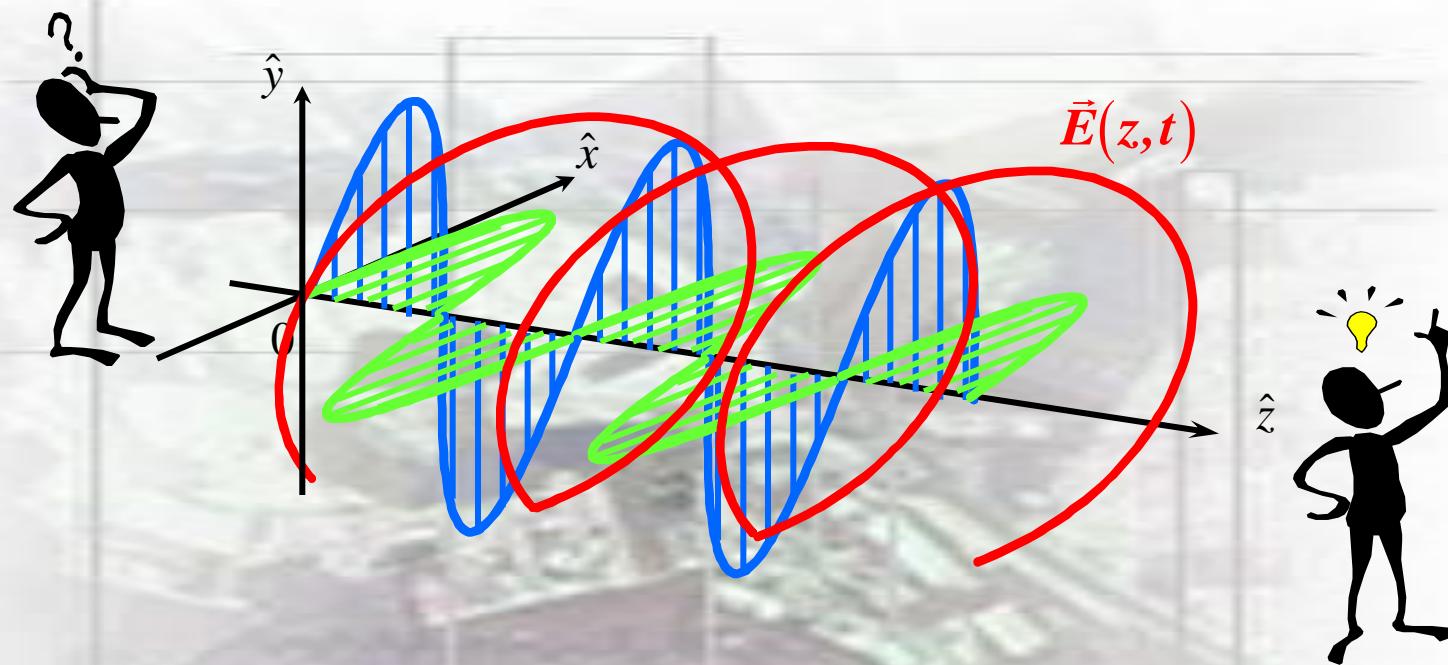
© Google Earth



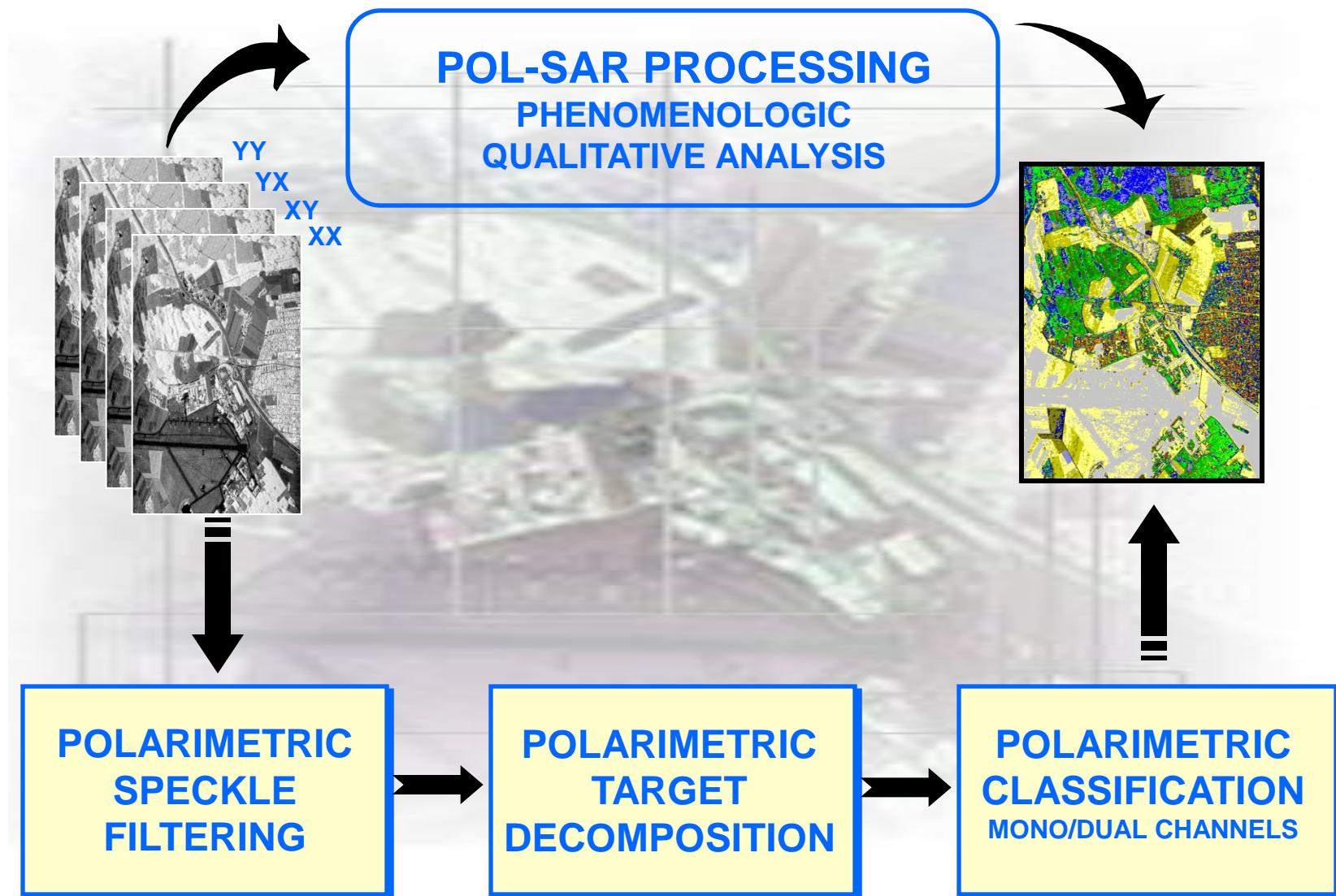
|HH+VV|

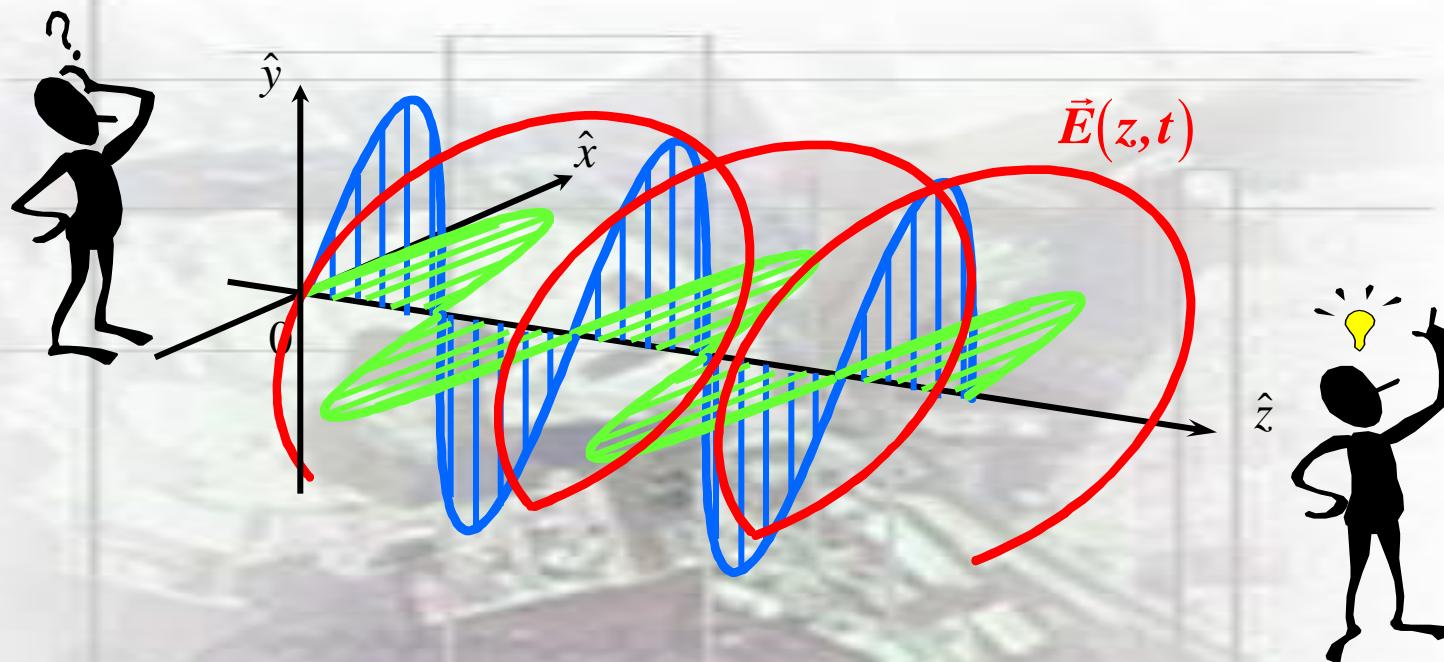
|HV|

|HH-VV|



POLARIMETRIC REMOTE SENSING





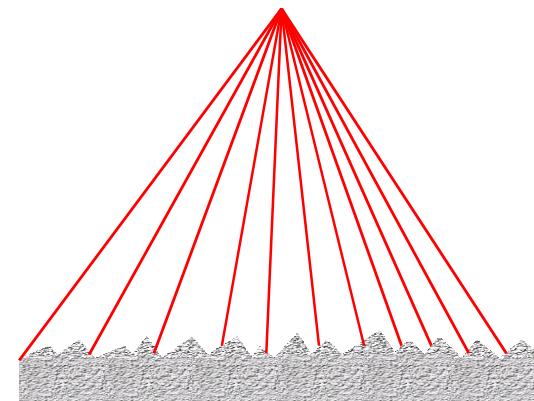
POLARIMETRIC SPECKLE FILTERING

An Introduction

SPECKLE PHENOMENON



OBSERVATION POINT



SURFACE ROUGHNESS
WAVELENGTH
SCATTERING FROM DISTRIBUTED
SCATTERERS

COHERENT INTERFERENCES OF WAVES
SCATTERED FROM MANY RANDOMLY
DISTRIBUTED ELEMENTARY SCATTERERS
INSIDE THE RESOLUTION CELL

GRANULAR NOISE

SPECKLE PHENOMENON

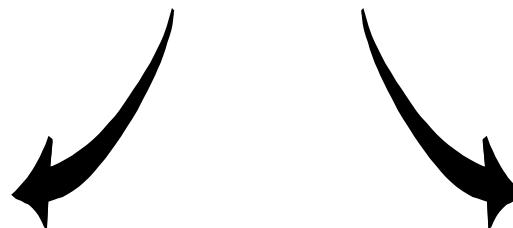
SPECKLE PHENOMENON



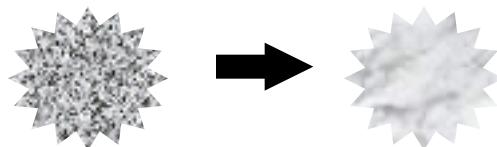
DISTORTION OF THE INTERPRETATION



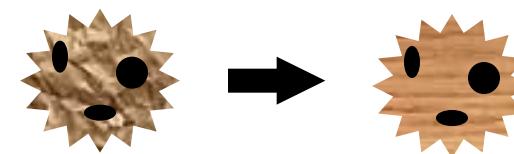
SPECKLE FILTERING

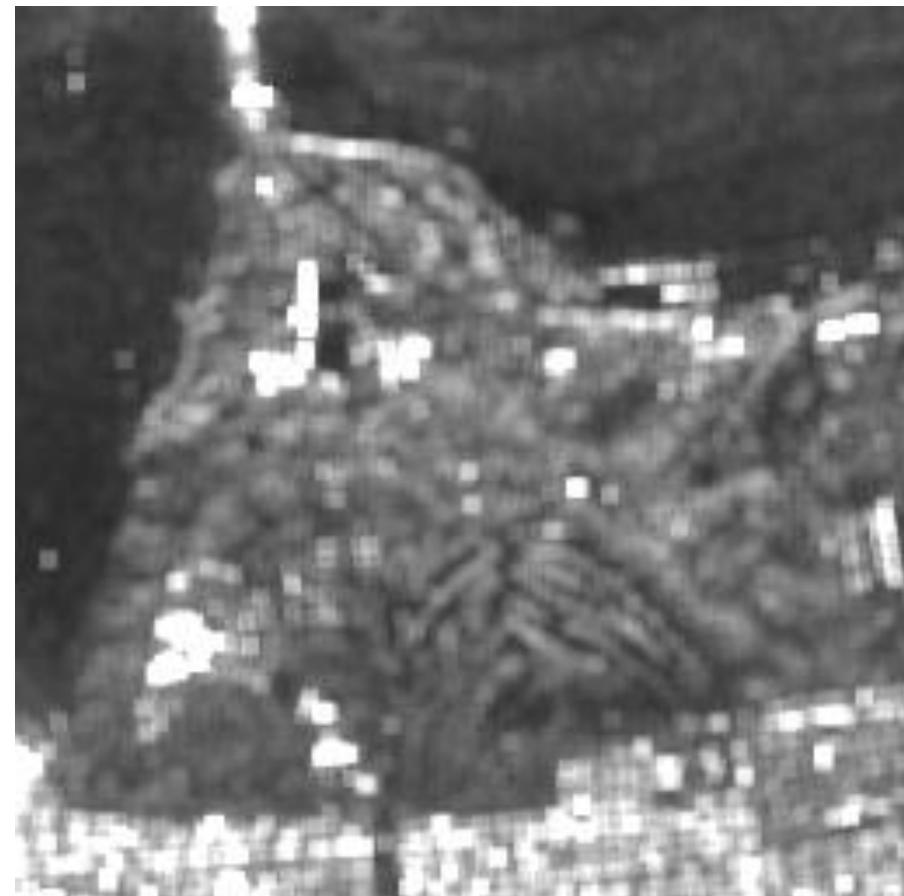


HOMOGENEOUS AREA

SPECKLE REDUCTION
(RADIOMETRIC RESOLUTION)

HETEROGENEOUS AREA

DETAILS PRESERVATION
(SPATIAL RESOLUTION)



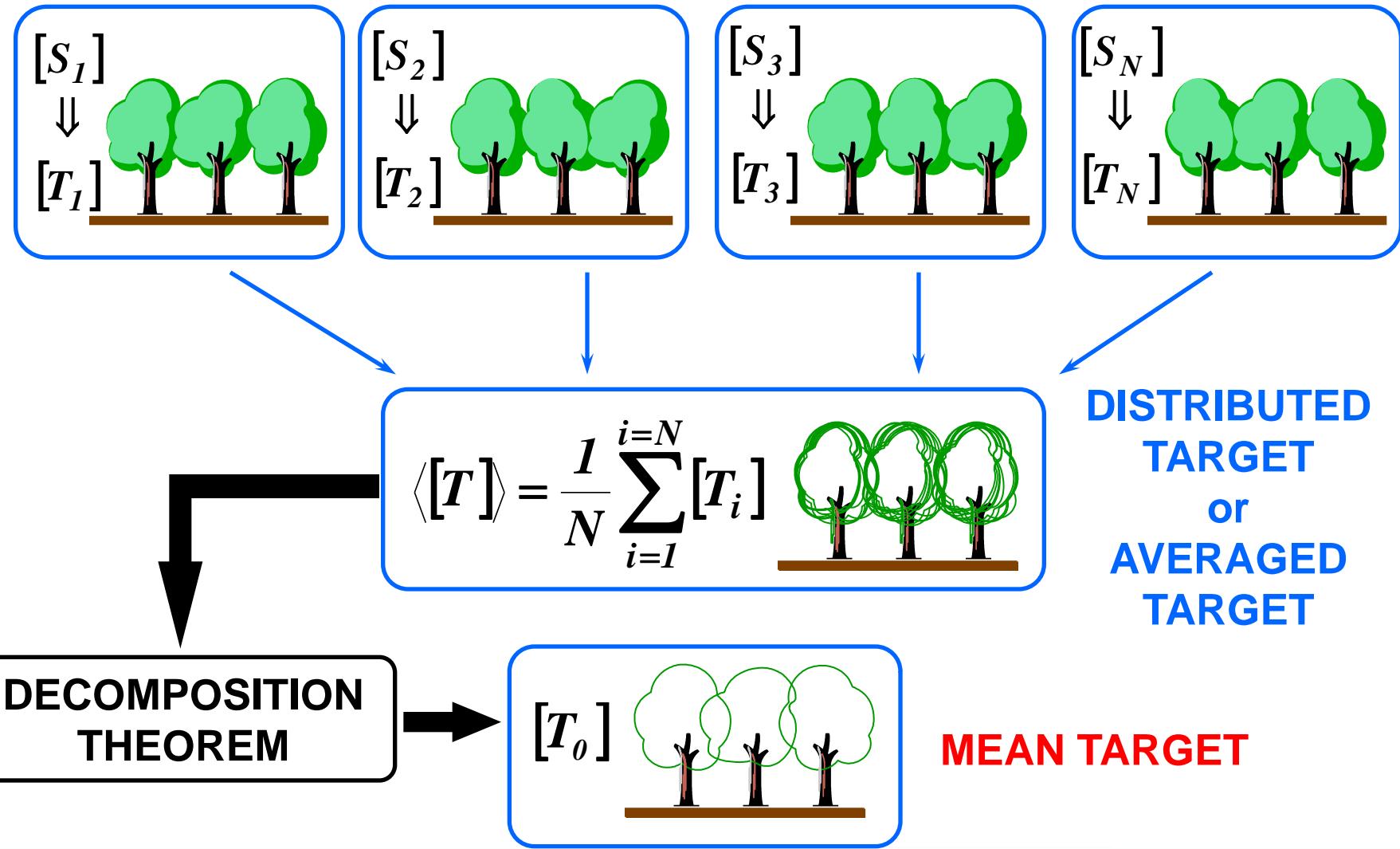
SAN FRANCISCO BAY JPL - AIRSAR L-band 1988

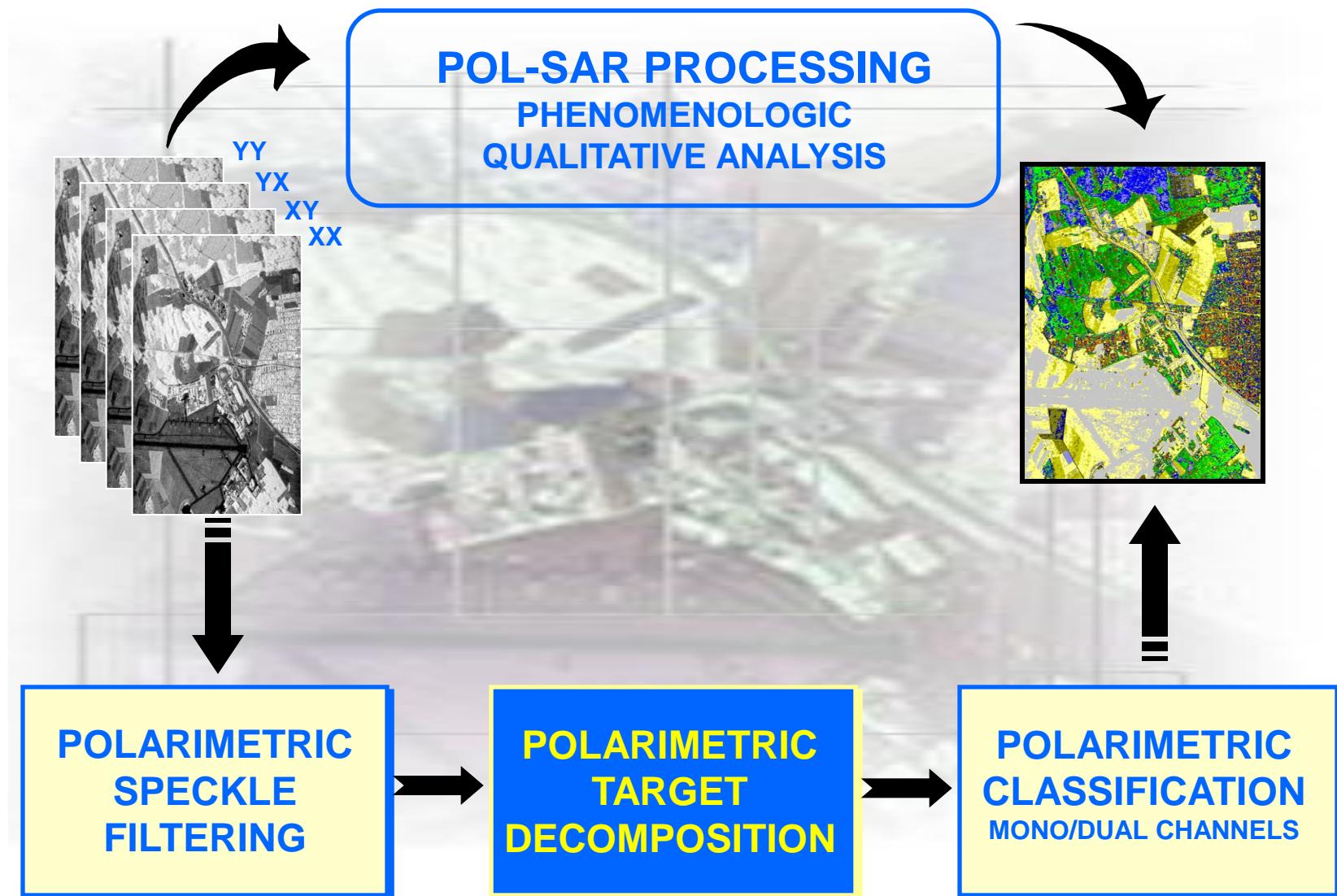
BoxCar Filter



SAN FRANCISCO BAY JPL - AIRSAR L-band 1988

J.S. Lee, D.L. Schuler, T.L. Ainsworth, M.R. Grunes, E Pottier, L. Ferro-Famil, "Scattering Model Based Speckle Filtering of Polarimetric SAR Data" IEEE – TGRS, vol 1, January 2006





[S]

COHERENT DECOMPOSITION

E. KROGAGER
(1990)W.L. CAMERON
(1990)

[K]

TARGET DICHOTOMY

J.R. HUYNEN
(1970)R.M. BARNES
(1988)

[T]

EIGENVECTORS BASED DECOMPOSITION

S.R. CLOUDE
(1985)W.A. HOLM
(1988)

EIGENVECTORS / EIGENVALUES ANALYSIS & MODEL BASED DECOMPOSITION

EIGENVECTORS / EIGENVALUES ANALYSIS ENTROPY / ANISOTROPY

S.R. CLOUDE - E. POTTIER
(1996-1997)

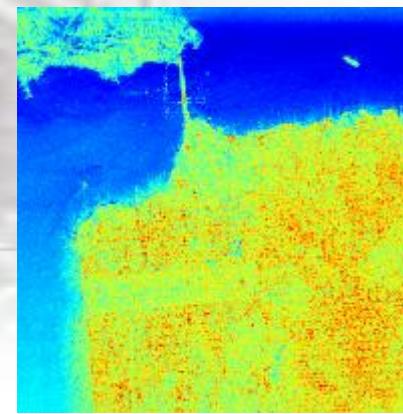
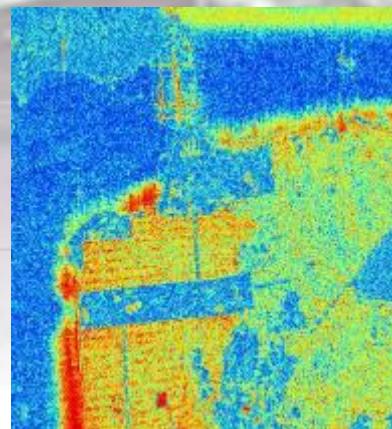
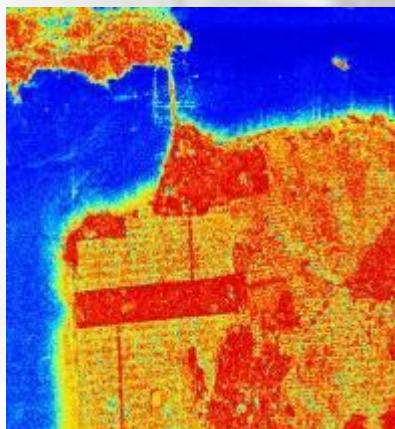
[C]

AZIMUTHAL SYMMETRY

MODEL BASED DECOMPOSITION

A.J. FREEMAN – S.L. DURDEN (1992)
Y. YAMAGUSHI (2005 - 2012), AN (2010)J.J. VAN ZYL (1992-2008), M. ARII (2010)
TSVM (R. TOUZI – 2007)

THE H/A/ α POLARIMETRIC TARGET DECOMPOSITION THEOREM



S.R. CLOUDE - E. POTTIER (1995 - 1996)

TARGET VECTOR

$$\underline{k} = \frac{1}{\sqrt{2}} [S_{XX} + S_{YY} \quad S_{XX} - S_{YY} \quad 2S_{XY}]^T$$

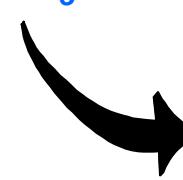
LOCAL ESTIMATE OF
THE COHERENCY MATRIX

$$\langle [T] \rangle = \frac{1}{N} \sum_{i=1}^N \underline{k}_i \cdot \underline{k}_i^{*T} = \frac{1}{N} \sum_{i=1}^N [T_i]$$

EIGENVECTORS / EIGENVALUES ANALYSIS

$$\langle [T] \rangle = [\underline{U}_3] [\Sigma] [\underline{U}_3]^{-1} = \begin{bmatrix} & & \\ \underline{u}_1 & \underline{u}_2 & \underline{u}_3 \\ & & \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} \begin{bmatrix} & & \\ \underline{u}_1 & \underline{u}_2 & \underline{u}_3 \\ & & \end{bmatrix}^{*T}$$

ORTHOGONAL EIGENVECTORS REAL EIGENVALUES
 $\lambda_1 > \lambda_2 > \lambda_3$



$$P_i = \frac{\lambda_i}{\sum_{k=1}^3 \lambda_k}$$

EIGENVALUES $\lambda_1 \ \lambda_2 \ \lambda_3$: ROLL INVARIANT

PROBABILITIES $P_1 \ P_2 \ P_3$: ROLL INVARIANT



ENTROPY

(DEGREE OF RANDOMNESS
STATISTICAL DISORDER)

$$H = -\sum_{i=1}^3 P_i \log_3(P_i)$$



PURE TARGET

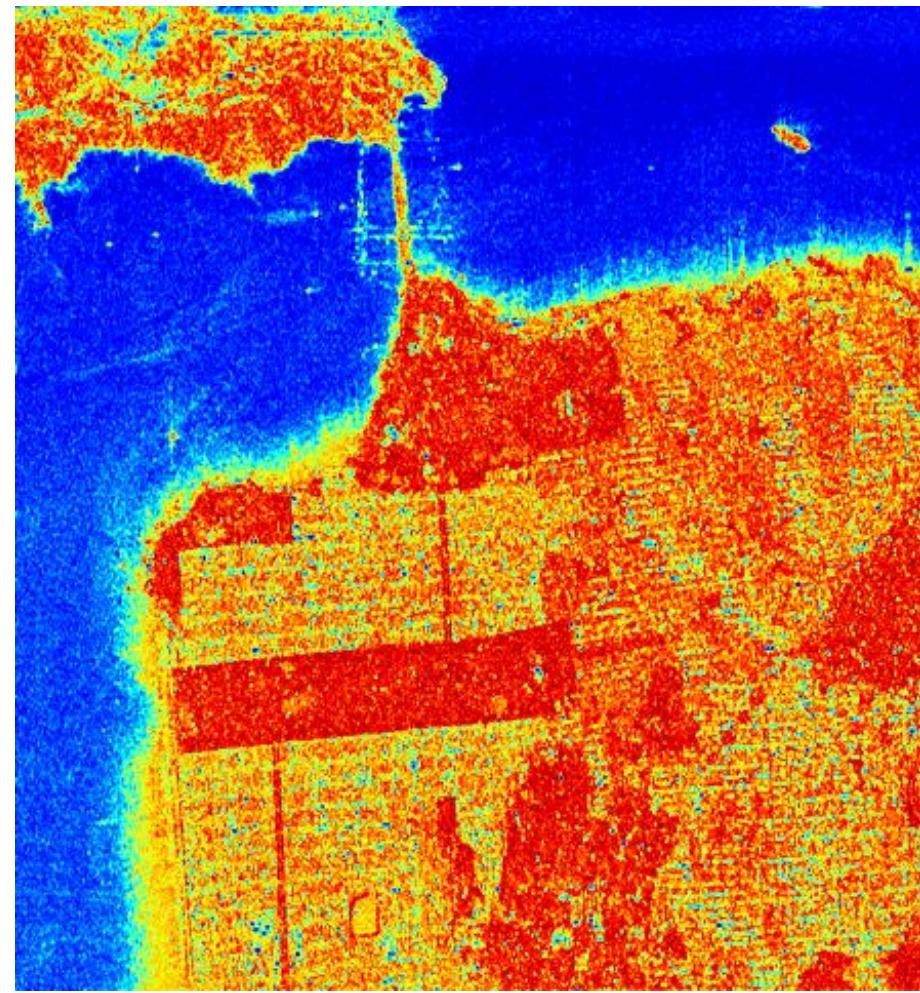
$$\lambda_1 = SPAN \quad \lambda_2 = 0 \quad \lambda_3 = 0$$

$$H = 0$$

DISTRIBUTED TARGET

$$\lambda_1 = \lambda_2 = \lambda_3 = SPAN / 3$$

$$H = 1$$

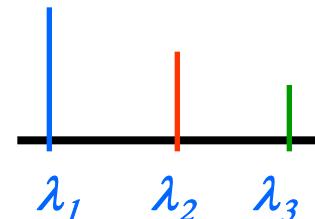
 $2A_0$ $B_0 + B$ $B_0 - B$ 

DIFFICULT MECHANISM DISCRIMINATION WHEN : $H > 0.7$

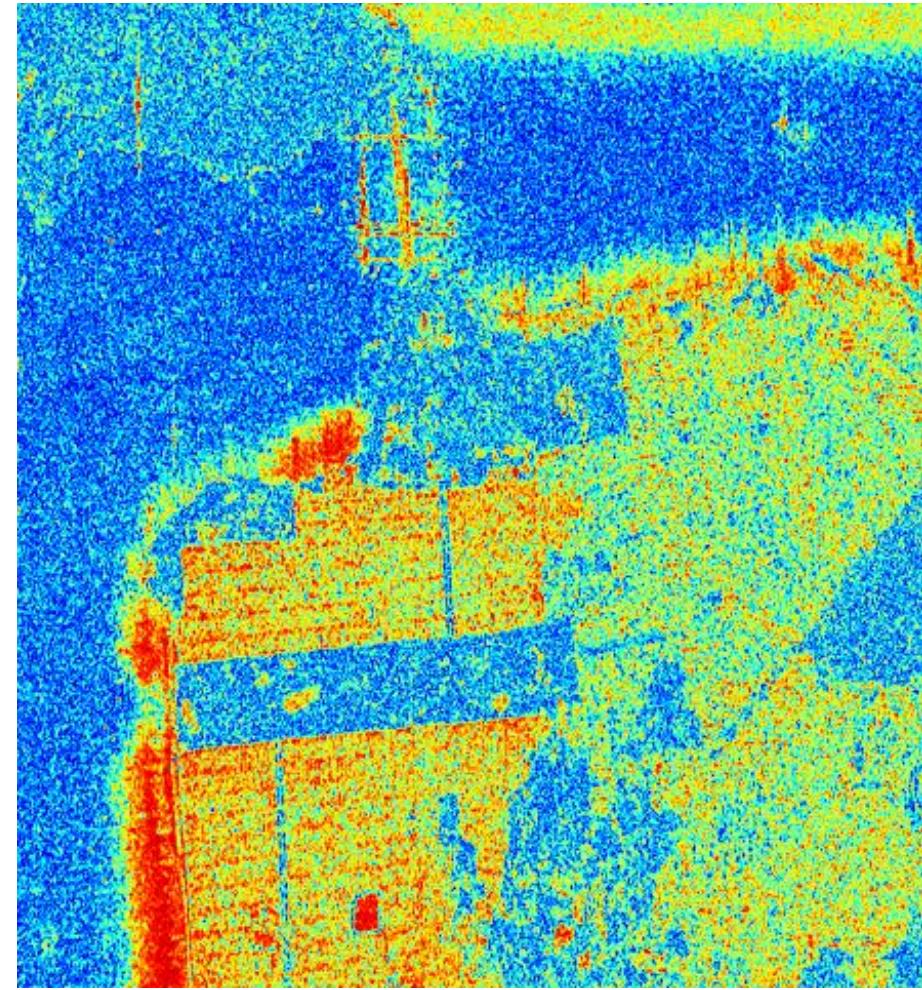


**ANISOTROPY
(EIGENVALUES SPECTRUM)**

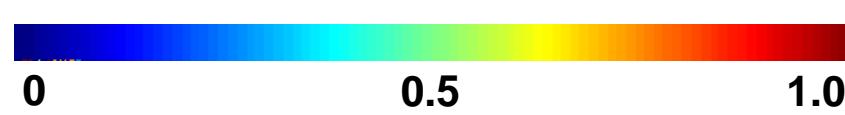
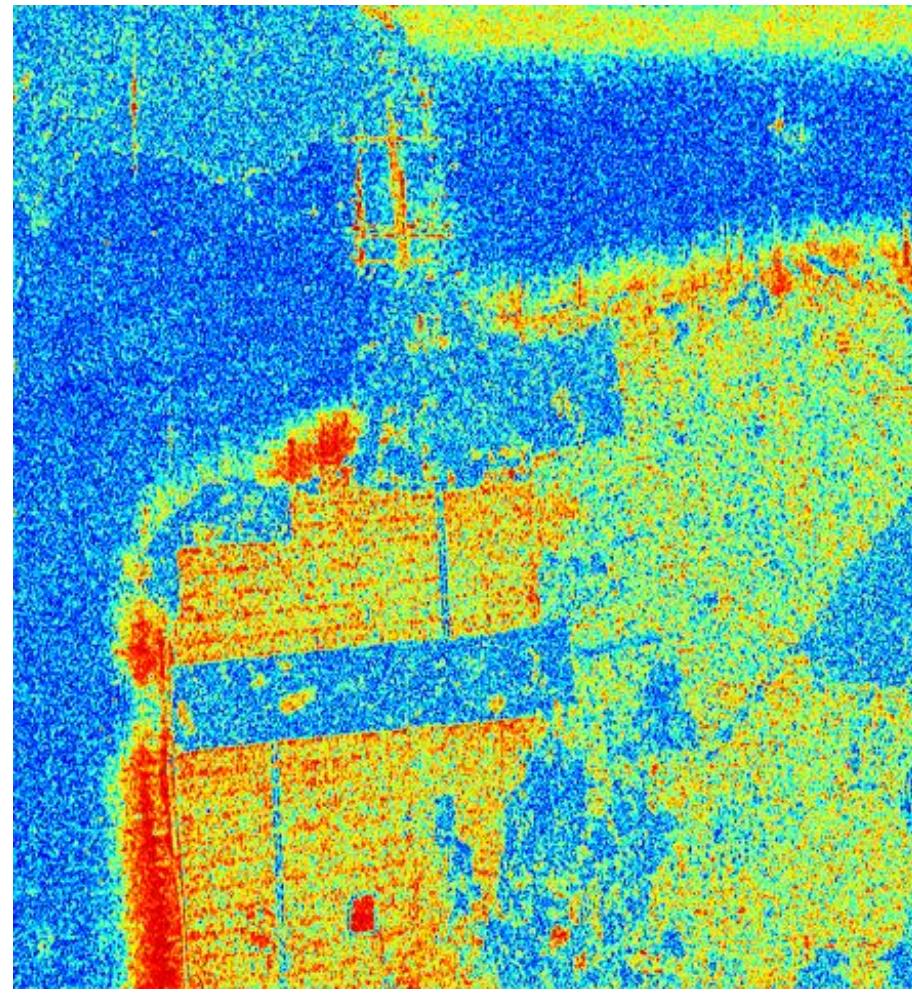
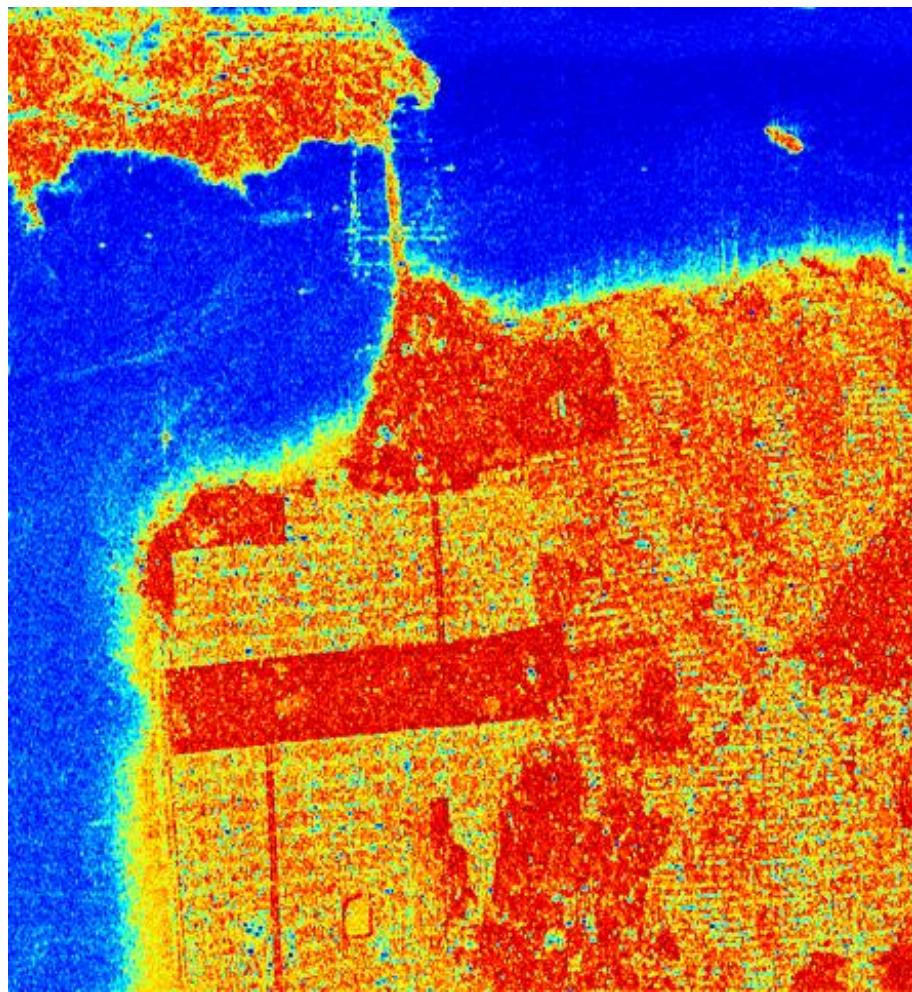
$$A = \frac{\lambda_2 - \lambda_3}{\lambda_2 + \lambda_3}$$



- COMPLEMENTARY TO ENTROPY
- DISCRIMINATION WHEN $H > 0.7$
- ROLL INVARIANT

 $2A_0$ $B_0 + B$ $B_0 - B$ 

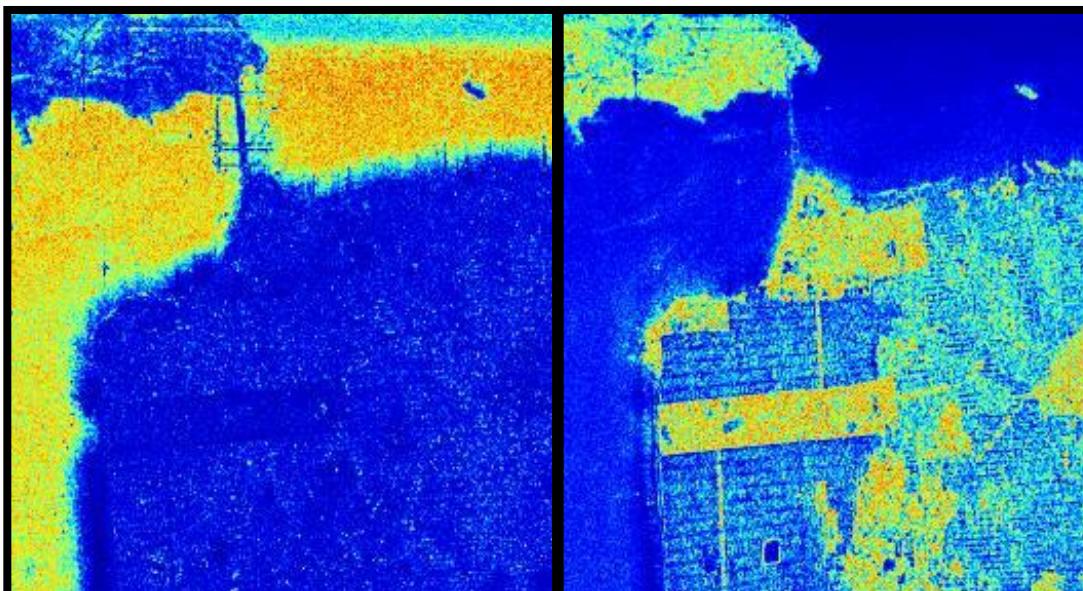
ANISOTROPY (A)



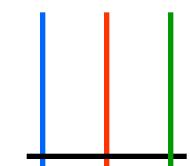
(1-H)(1-A)



1 MECHANISM

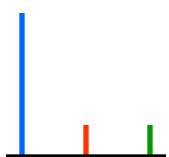


H(1-A)

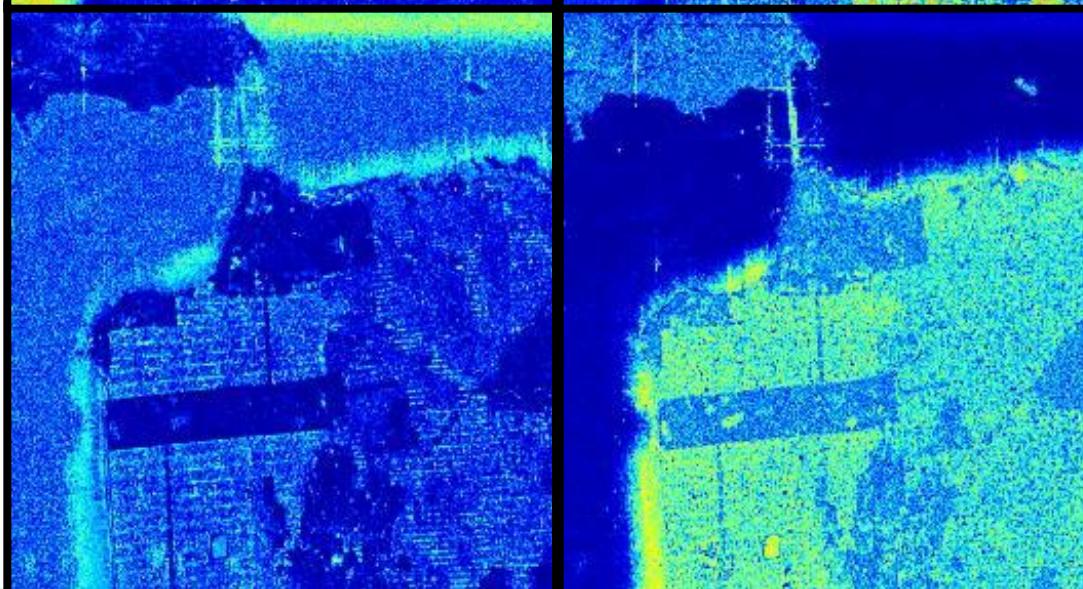


3 MECHANISMS

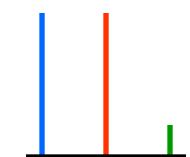
A(1-H)



2 MECHANISMS



HA



2 MECHANISMS

$$\langle [T] \rangle = [\mathbf{U}_3] [\Sigma] [\mathbf{U}_3]^{-1} = \begin{bmatrix} & & \\ \underline{u}_1 & \underline{u}_2 & \underline{u}_3 \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} \begin{bmatrix} & & \\ \underline{u}_1 & \underline{u}_2 & \underline{u}_3 \end{bmatrix}^{*T}$$

ORTHOGONAL
EIGENVECTORS

REAL EIGENVALUES
 $\lambda_1 > \lambda_2 > \lambda_3$



PARAMETERISATION OF THE SU(3) UNITARY MATRIX

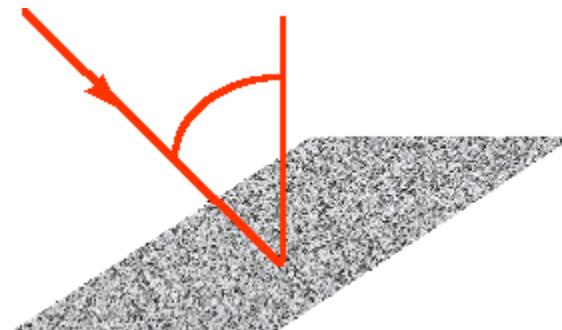
$$[\mathbf{U}_3] = \begin{bmatrix} \cos \alpha_1 e^{j\phi_1} & \cos \alpha_2 e^{j\phi_2} & \cos \alpha_3 e^{j\phi_3} \\ \sin \alpha_1 \cos \beta_1 e^{j\phi_1} e^{j\delta_1} & \sin \alpha_2 \cos \beta_2 e^{j\phi_2} e^{j\delta_2} & \sin \alpha_3 \cos \beta_3 e^{j\phi_3} e^{j\delta_3} \\ \sin \alpha_1 \sin \beta_1 e^{j\phi_1} e^{j\gamma_1} & \sin \alpha_2 \sin \beta_2 e^{j\phi_2} e^{j\gamma_2} & \sin \alpha_3 \sin \beta_3 e^{j\phi_3} e^{j\gamma_3} \end{bmatrix}$$

↓ TARGET 1 ↓ TARGET 2 ↓ TARGET 3

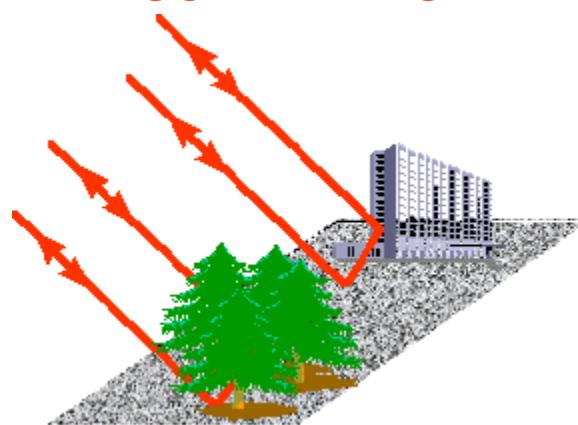
$$\underline{\alpha} = P_1 \alpha_1 + P_2 \alpha_2 + P_3 \alpha_3$$

PHYSICAL INTERPRETATION

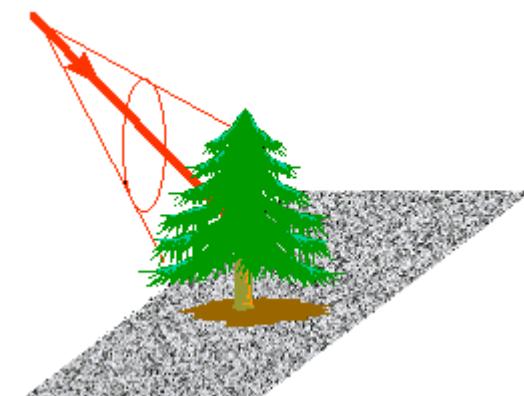
SINGLE BOUNCE SCATTERING (ROUGH SURFACE)



DOUBLE BOUNCE SCATTERING



VOLUME SCATTERING



$$a \mapsto b \Rightarrow v \mapsto 0$$

$$\downarrow$$

$$\underline{\alpha} \mapsto 0$$

$$a \mapsto -b \Rightarrow \varepsilon \mapsto 0$$

$$\downarrow$$

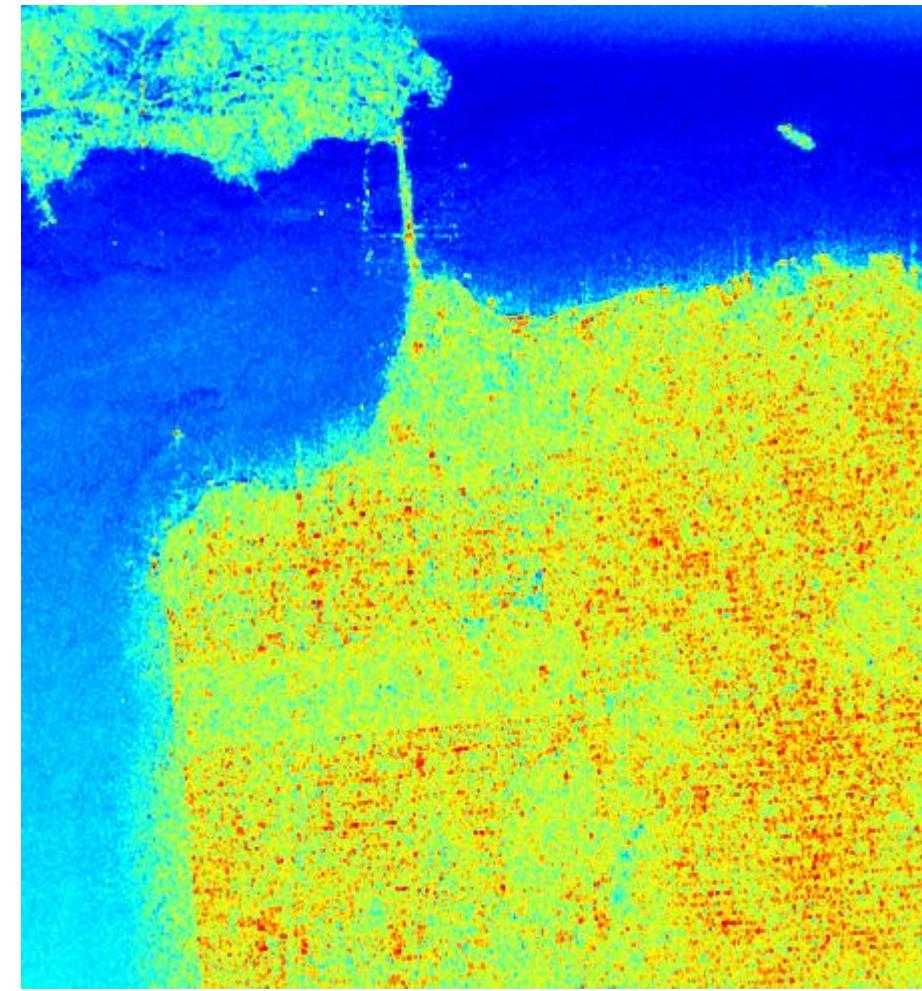
$$\underline{\alpha} \mapsto \frac{\pi}{2}$$

$$a \gg b \Rightarrow \varepsilon \approx v$$

$$\downarrow$$

$$\underline{\alpha} \mapsto \frac{\pi}{4}$$

H/A/ $\underline{\alpha}$ DECOMPOSITION

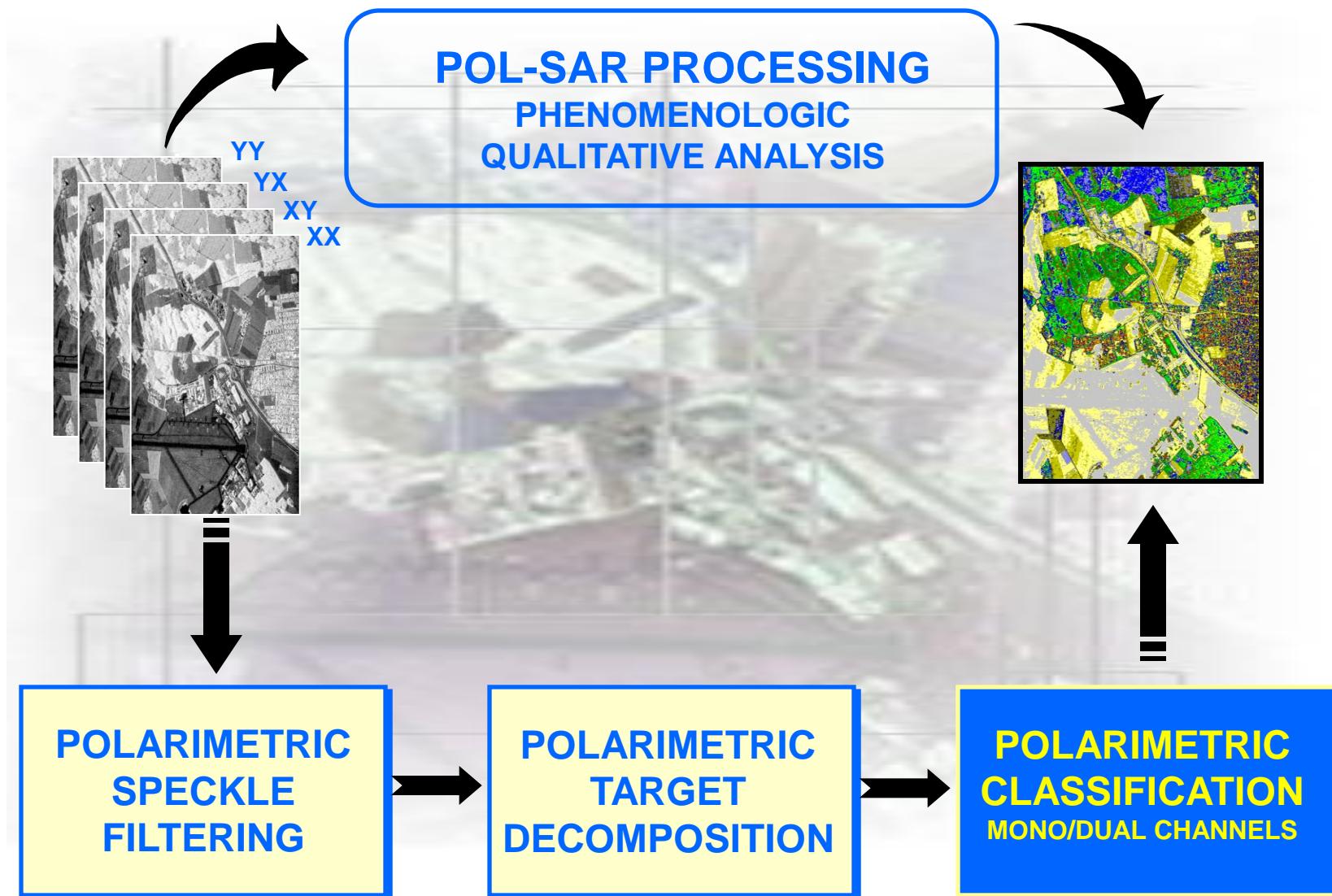
 $2A_0$ $B_0 + B$ $B_0 - B$

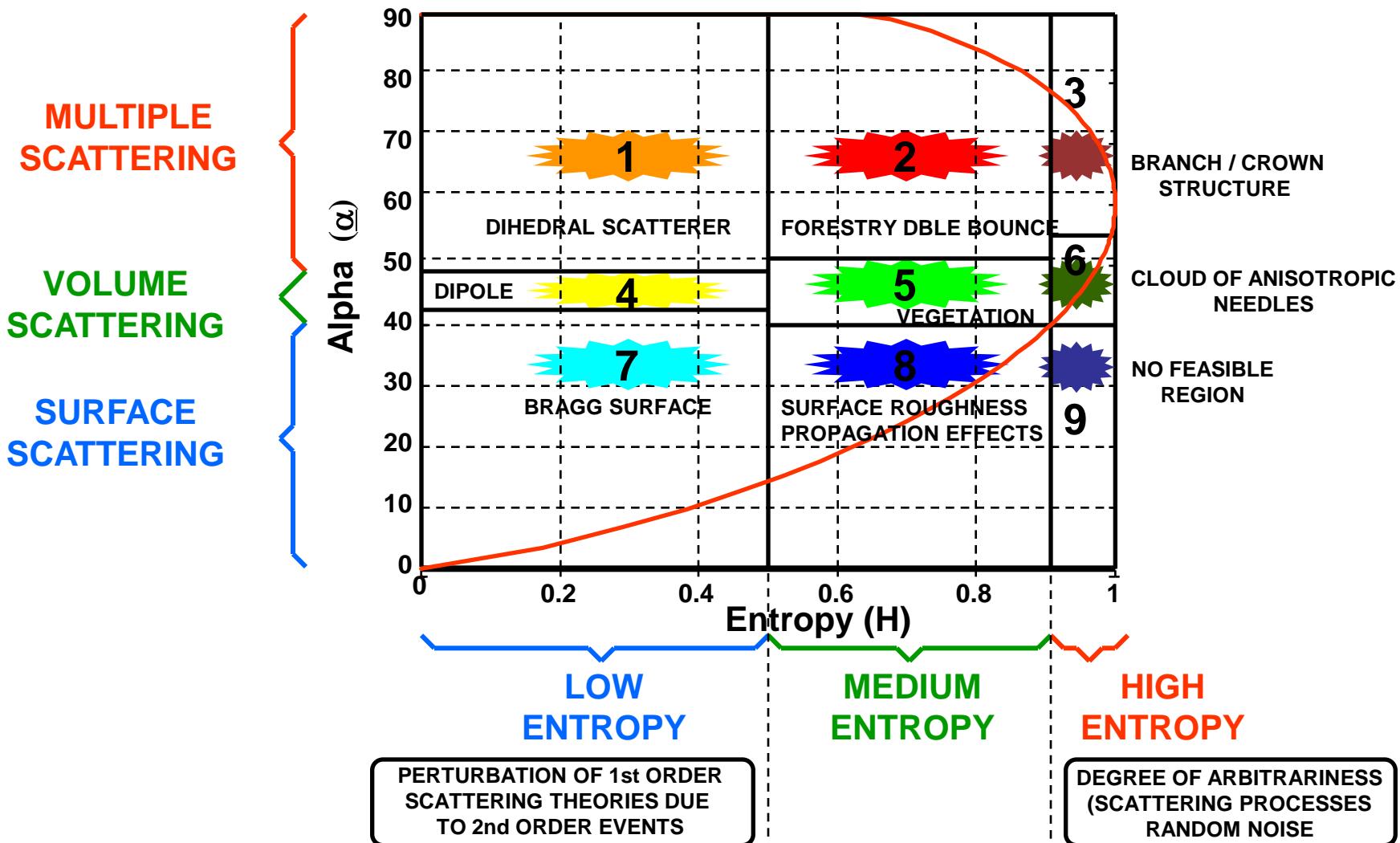
0

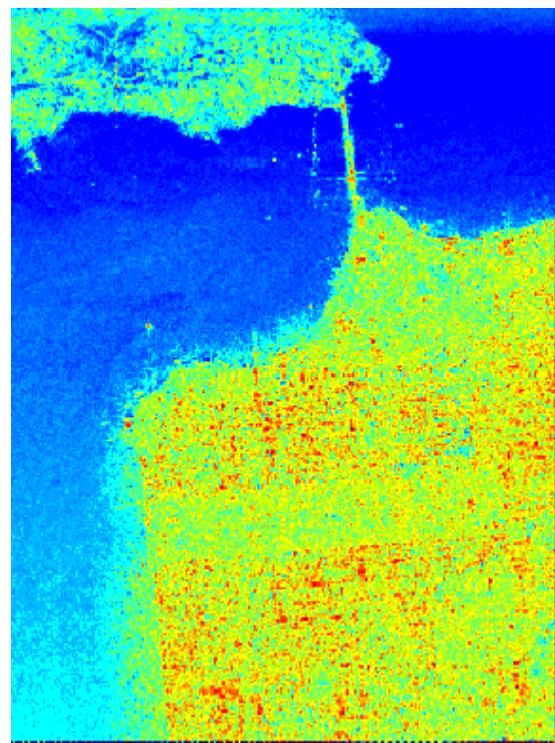
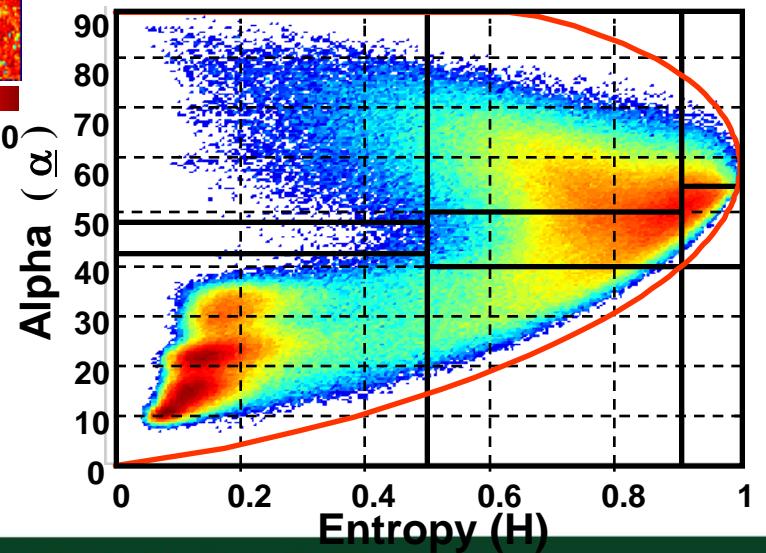
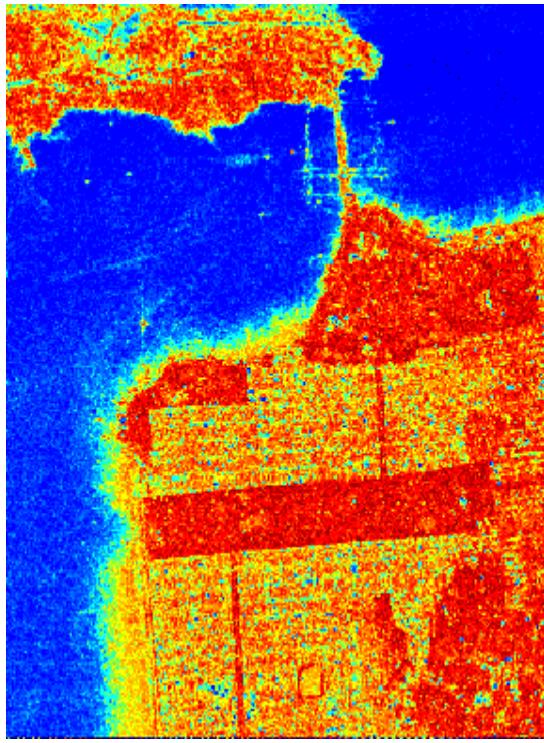
45°

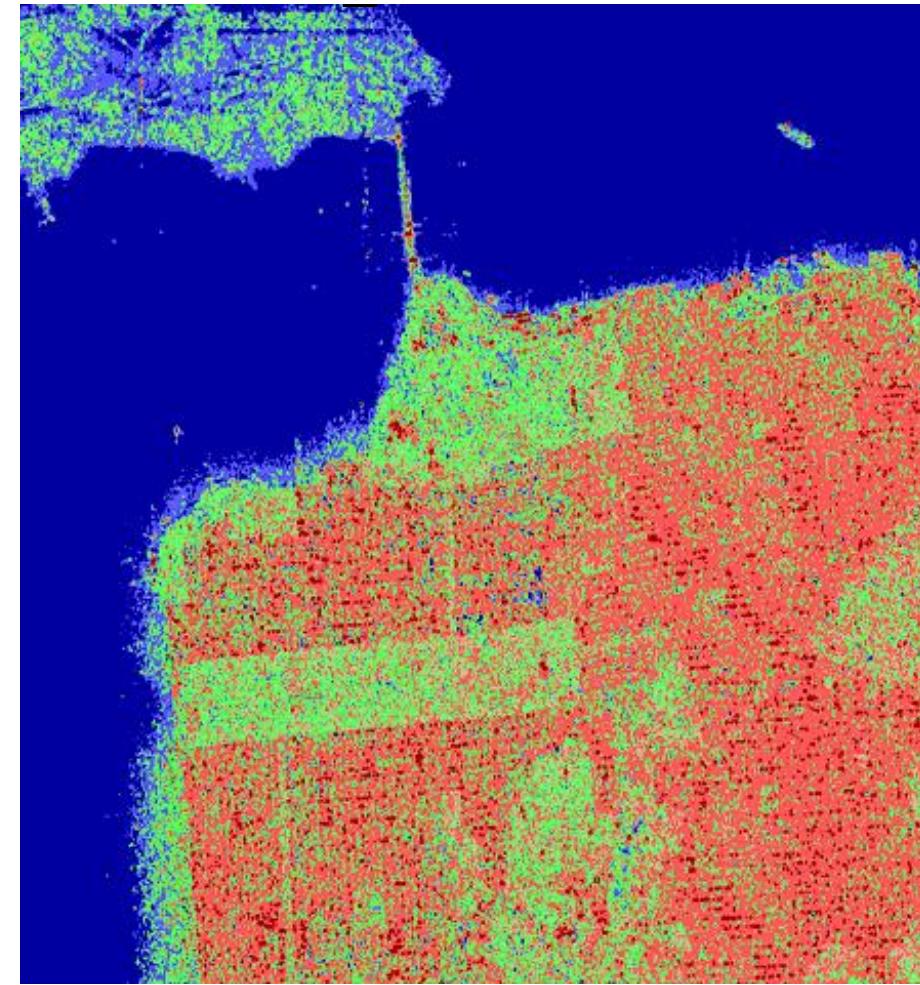
90°

 α PARAMETER



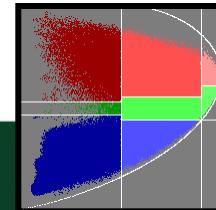
SEGMENTATION OF THE H / α SPACE



 $2A_0$ $B_0 + B$ $B_0 - B$

ADVANCED LAND REMOTE SENSING INTERNATIONAL TRAINING COURSE

20–25 November 2017 | Yunnan Normal University Kunming, Yunnan Province, P.R. China



计划4”高级陆地遥感国际培训班

年11月20日—11月25日 云南师范大学, 中国, 昆明

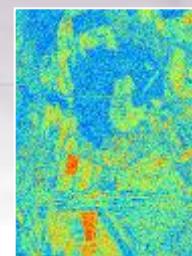
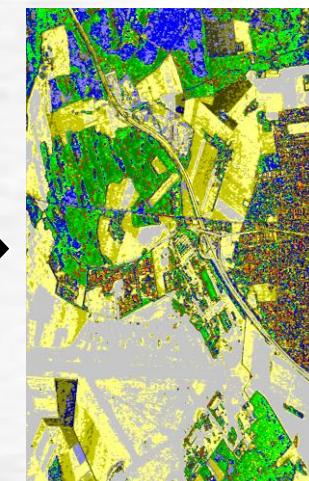
WISHART PDF

$$P([\mathbf{T}]/[\mathbf{T}_m]) = \frac{L^{Lp} |[\mathbf{T}]|^{L-p} e^{-LTr([\mathbf{T}_m]^{-1}[\mathbf{T}])}}{\pi^{\frac{p(p-1)}{2}} \Gamma(L) \dots \Gamma(L-p+1) [\mathbf{T}_m]^L}$$

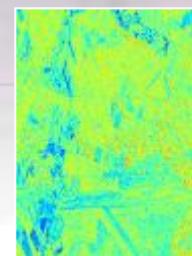


UNSUPERVISED POLSTAR CLASSIFICATION

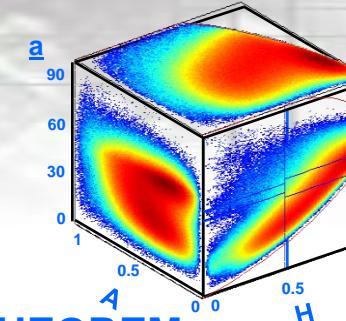
E.POTTIER, J.S LEE (2000)



A

 α

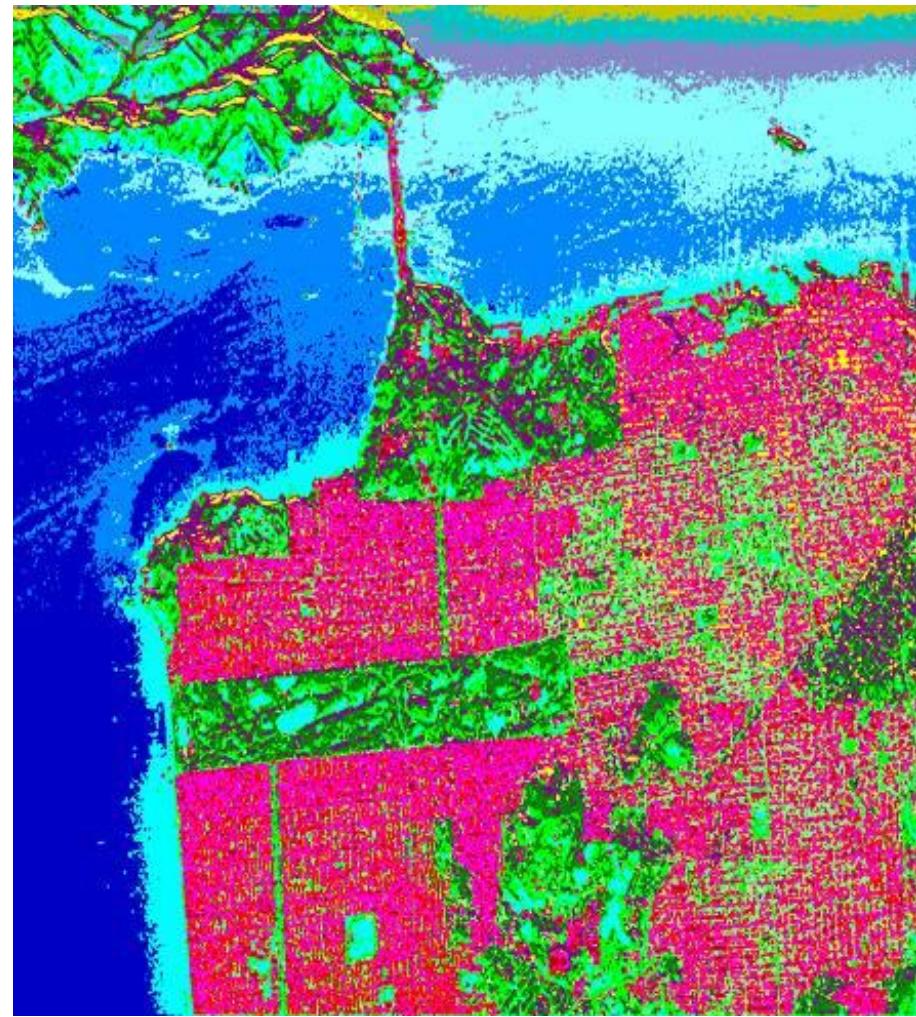
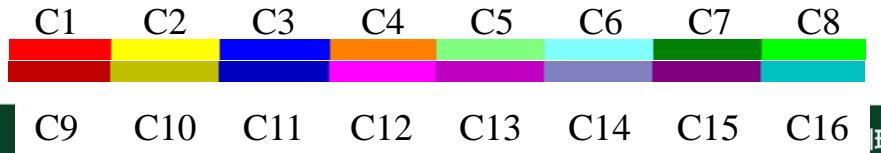
H / A / α DECOMPOSITION THEOREM



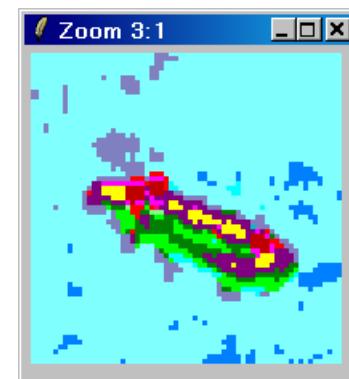
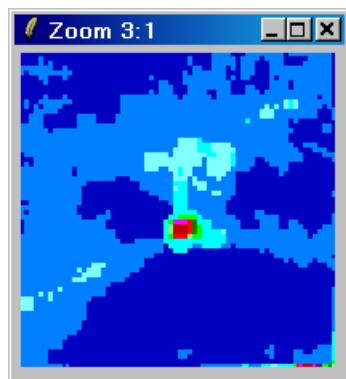
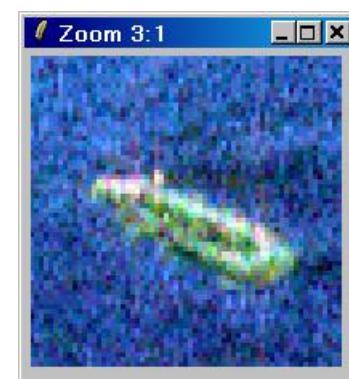
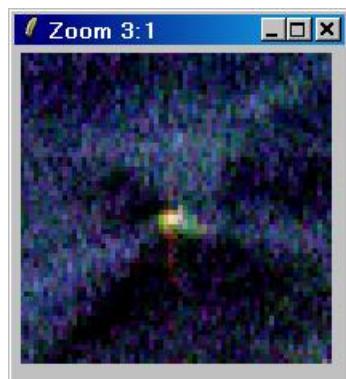
SAN FRANCISCO BAY JPL - AIRSAR L-band 1988



4th ITERATION

 $2A_0$ $B_0 + B$ $B_0 - B$ 

SAN FRANCISCO BAY JPL - AIRSAR L-band 1988



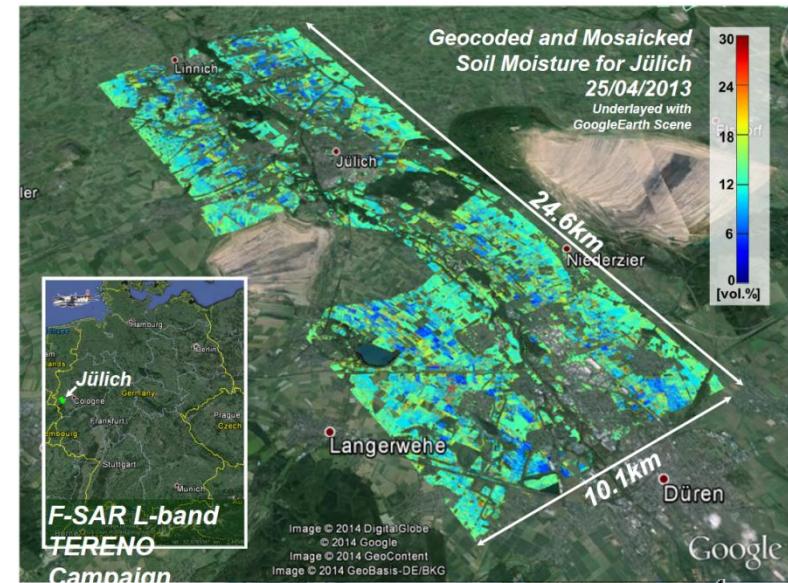
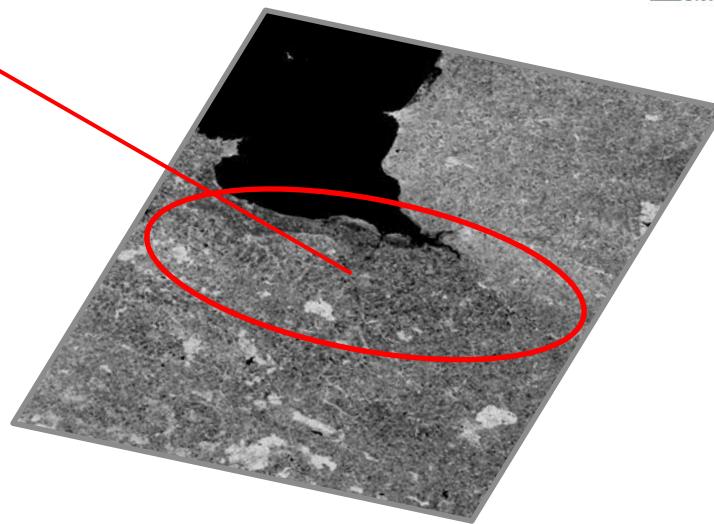
$$2A_0$$

$$B_0 + B$$

$$B_0 - B$$

PolSAR

Track₁

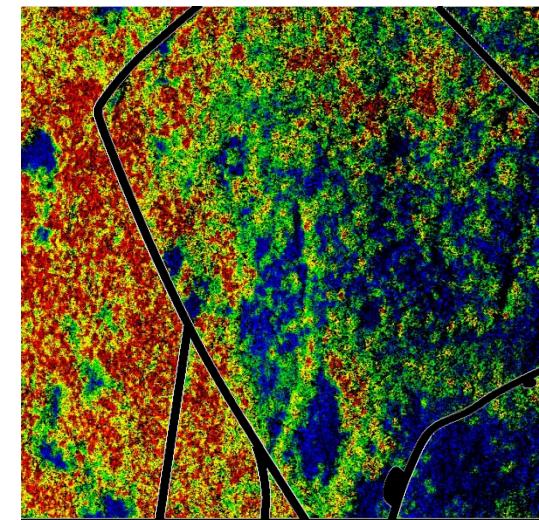
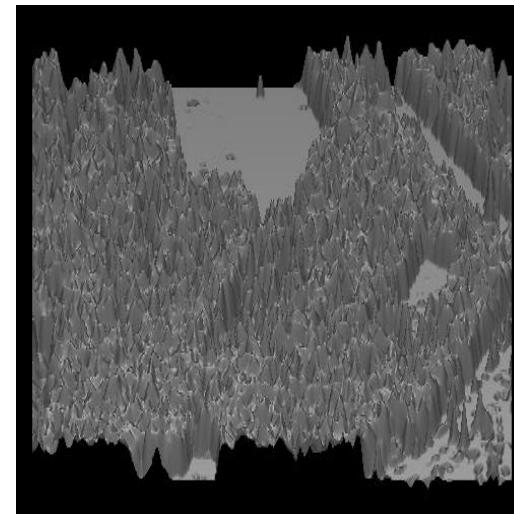
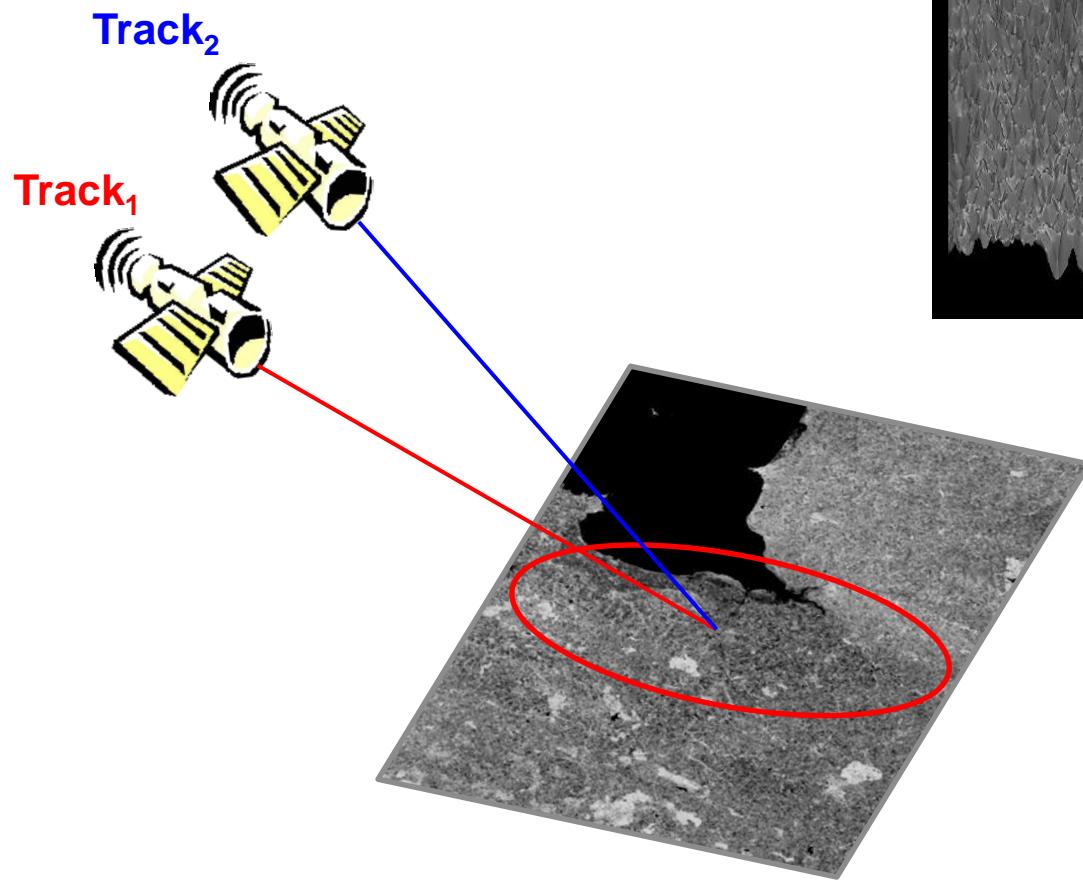


Soil moisture

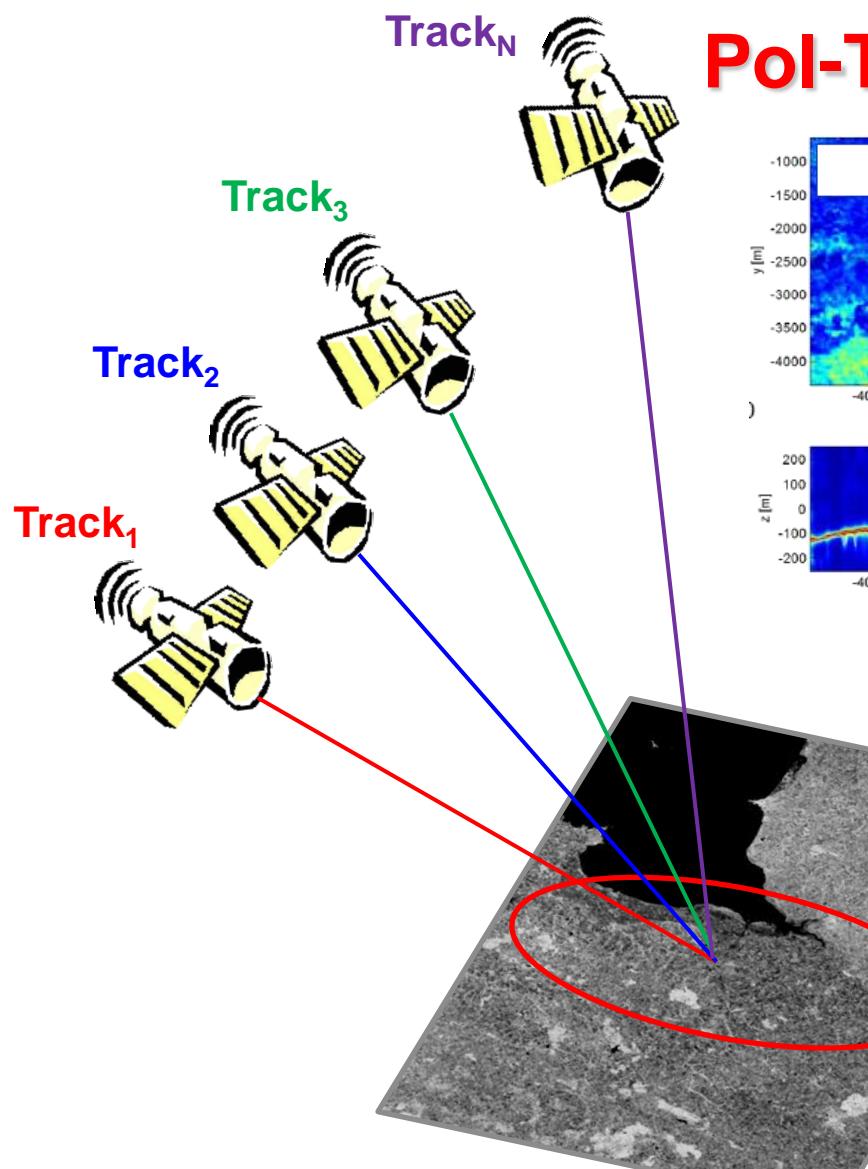


Urban monitoring

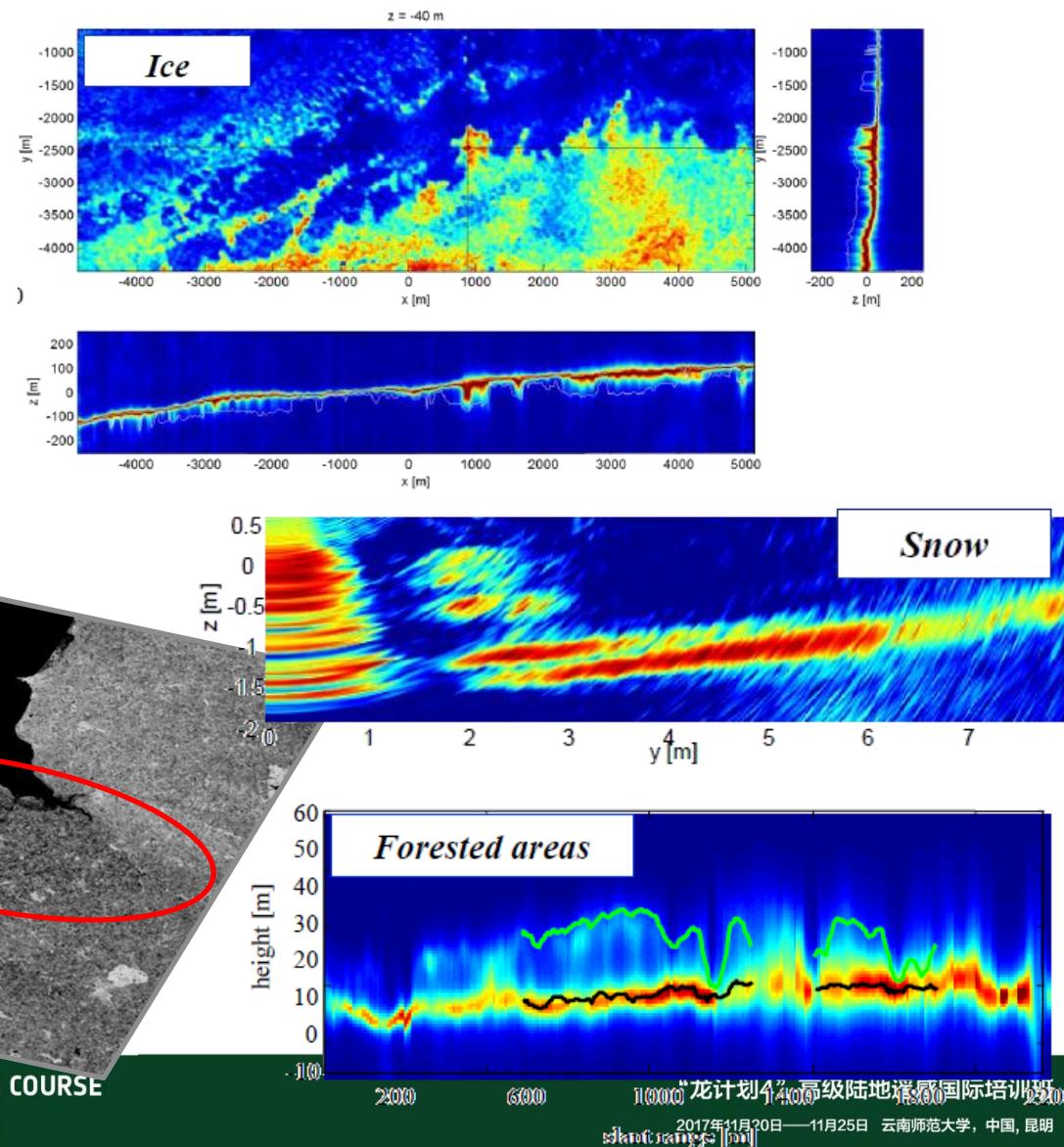
Pol-InSAR



Courtesy of Dr. K. Papathanassiou



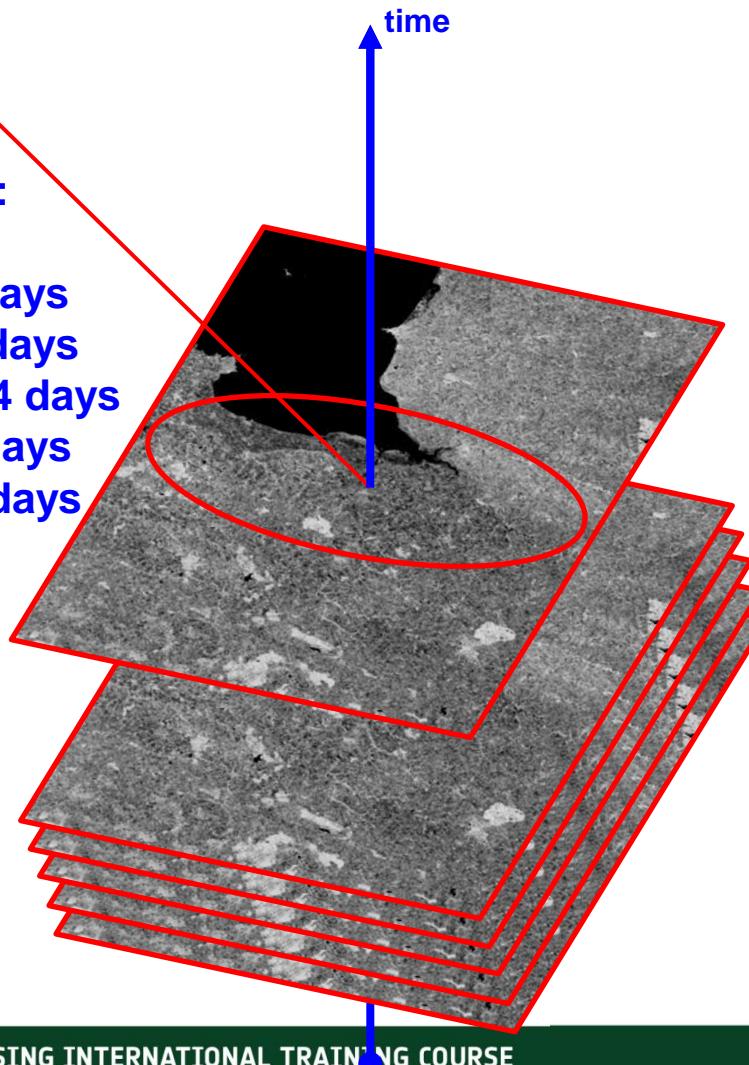
Pol-TomSAR



Track_{1..N}

Revisit time :

- ALOS-2 = 14 days
- BIOMASS = 4 days
- RADARSAT2 = 24 days
- RISAT-1 = 25 days
- Sentinel-1 = 6 days



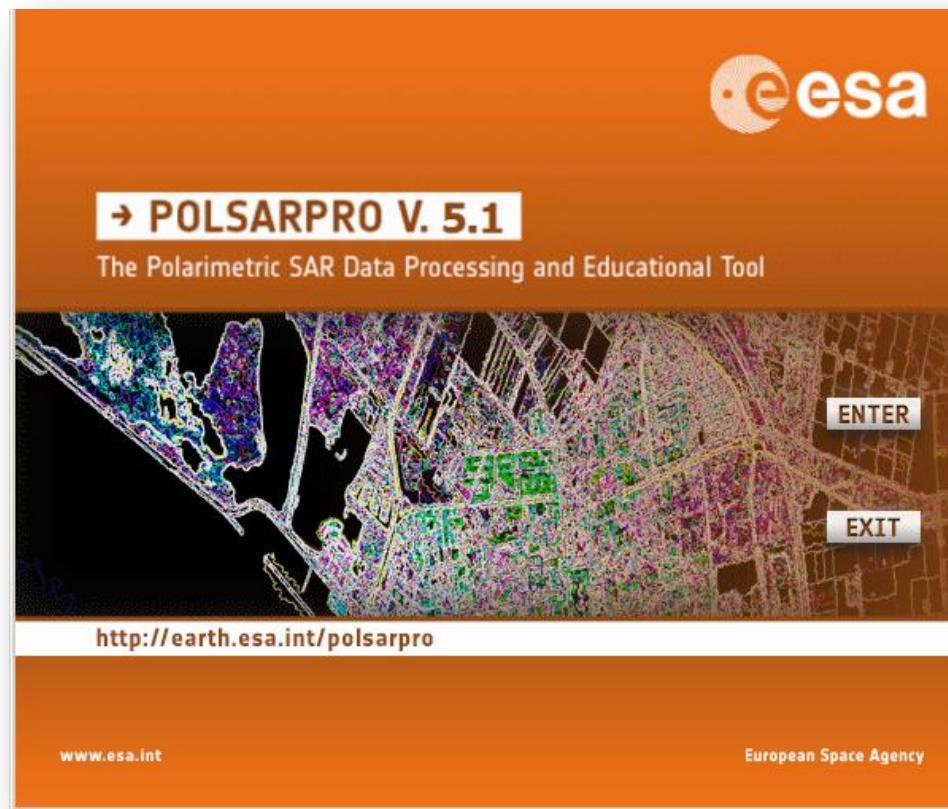
Pol-TimeSAR



Polarimetric feature
temporal evolution

Questions ?



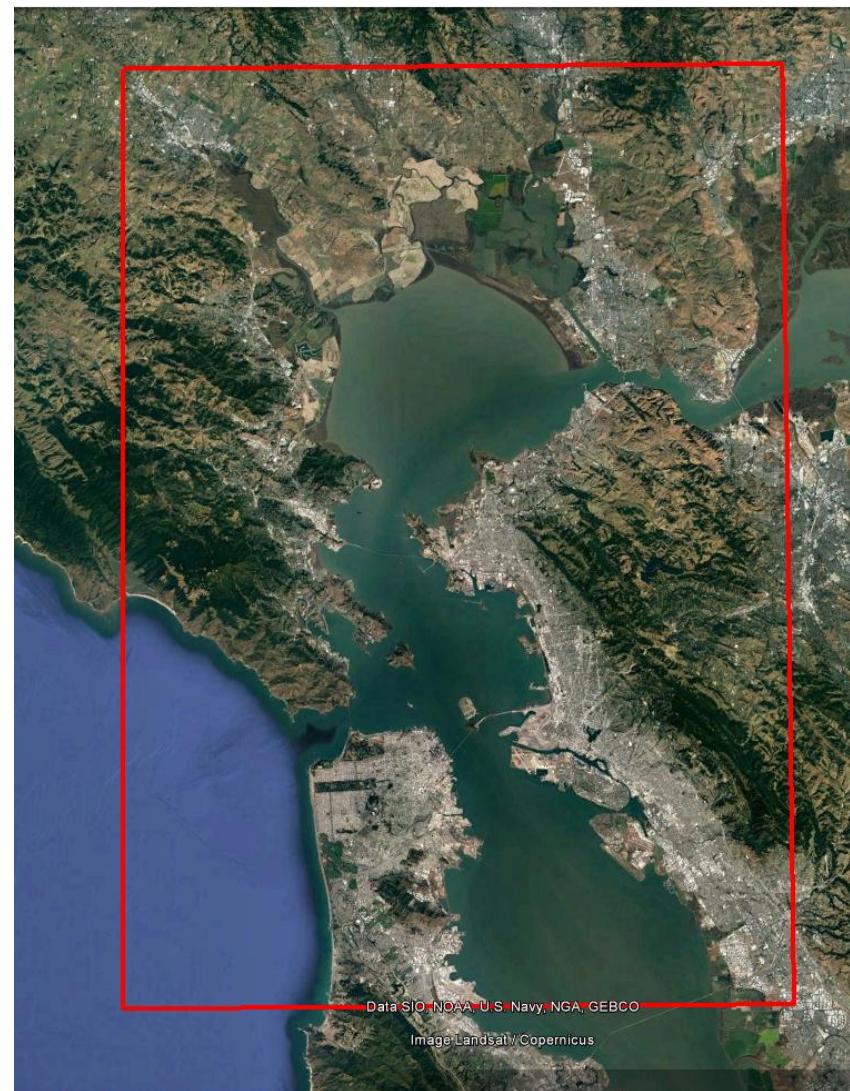
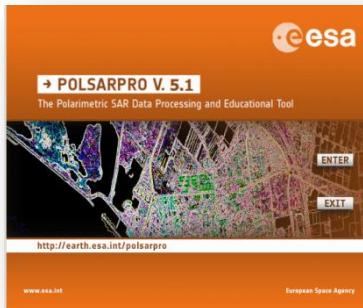


PolSARpro v5.1 Software Training Course



ALOS Advanced Land Observing Satellite **ALOS2 - PALSAR** JAXA

L-Band (Quad - 2015)



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