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Abstract	<p>Landslide mitigation measures are used to reduce the risk affecting mountain communities. The quantitative estimation of the change or reduction in risk, after implementing mitigation measures, requires modeling of past events and the forward prediction of possible future occurrences. However, the forward-prediction of landslide hazard is subjected to uncertainties due to the lack of knowledge on some key aspects like the possible source volume that can be triggered and model parameters that determine the landslide runout. In this study, a back-analysis of a debris flow event was carried out using MassMov2D to create a set of parameter ranges for forward-predicting runouts with mitigation measures. We approached the issue of uncertainty by systematically sampling parameters from wide ranges and running hundreds of different runout scenarios. Simulations from back-analysis were compared with the forward-predicted models to determine changes in the spread and intensity of debris flows affecting elements at risk (e.g. houses and roads). This study is a first step towards a quantitative</p>	

risk assessment (QRA) being carried out within the EC FP-7 funded CHANGES network (Grant Agreement No. 263953).

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Keywords  
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Landslide runout - 2D numerical modelling - Landslide mitigation -  
Landslide hazard and risk

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# Assessing the Effect of Mitigation Measures on Landslide Hazard Using 2D Numerical Runout Modelling

Haydar Y. Hussin, Roxana Ciurean, Simone Frigerio, Paola Reichenbach, Cees van Westen, and Thomas Glade

## Abstract

Landslide mitigation measures are used to reduce the risk affecting mountain communities. The quantitative estimation of the change or reduction in risk, after implementing mitigation measures, requires modeling of past events and the forward prediction of possible future occurrences. However, the forward-prediction of landslide hazard is subjected to uncertainties due to the lack of knowledge on some key aspects like the possible source volume that can be triggered and model parameters that determine the landslide runout. In this study, a back-analysis of a debris flow event was carried out using MassMov2D to create a set of parameter ranges for forward-predicting runouts with mitigation measures. We approached the issue of uncertainty by systematically sampling parameters from wide ranges and running hundreds of different runout scenarios. Simulations from back-analysis were compared with the forward-predicted models to determine changes in the spread and intensity of debris flows affecting elements at risk (e.g. houses and roads). This study is a first step towards a quantitative risk assessment (QRA) being carried out within the EC FP-7 funded CHANGES network (Grant Agreement No. 263953).

## Keywords

Landslide runout • 2D numerical modelling • Landslide mitigation • Landslide hazard and risk

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## Introduction

Numerical 2D runout models are used to study the flow behaviour of landslide runouts and to produce hazard maps for areas at risk (e.g. alluvial and debris fans). More recently, 2D runout models are being applied to forward predict or forecast the effect of existing mitigation measures on future landslide and debris flow runouts, deposit heights and velocities (Takahashi 2009; Graf and McArdeall 2011; Liu et al. 2012). However, using model parameters from back-analyses to forward-predict future runouts can lead to uncertainties in the modelling results (Pirulli 2010), especially if parameters from “past” events are used with “new” DEMs containing mitigations measures. Therefore, it is necessary to produce multiple scenarios in forward predictive modelling of debris flows when analysing the effectiveness of mitigation measures.

We propose in this study to use parametric sampling from ranges based on back-analysis of past events and expert



**Fig. 1** (Left) The Abitato Cucco 2003 debris flow from the initiation to the deposit zone and (right) the breach of the barrier which damaged several houses



**Fig. 2** The mitigation measures constructed at the Abitato Cucco basin following the 2003 event, including the two houses that were relocated

39 knowledge to forward predict multiple debris flow runout  
 40 scenarios with recently constructed mitigation measures  
 41 using a high resolution DEM. The goal is to analyse whether  
 42 infrastructure in the study area is still at risk of being hit by  
 43 debris flows. This information can be used as a first step in  
 44 determining the quantitative change in risk and the residual  
 45 risk after implementing mitigation measures.

## Study Area and Mitigation Measures

46 The Abitato Cucco settlement in the municipality of  
 47 Malborghetto-Valbruna forms a section of the Val Canale  
 48 valley of the Fella River basin (Friuli-Venezia Giulia region,  
 49 Eastern Italian Alps). On the 29th of August 2003, a debris  
 50 flow was triggered by a severe rainfall event, mobilizing  
 51 approximately 10,000 m<sup>3</sup> of debris which breached an  
 52 existing mitigation barrier. Deposit heights exceeding 2 m  
 53 affected 13 to 14 houses (Fig. 1).

54 An estimated total of 1 million cubic meters of debris and  
 55 sediments in the Val Canale valley were mobilized  
 56 (Tropeano et al. 2004). Some of the recorded rainfall values  
 57 that triggered the event were: 88.6, 233.4 and 343.0 mm for  
 58 periods of 1, 3 and 6 h, respectively (Calligaris and Zini  
 59 2012). According to the analysis of rainfall data, the Abitato

Cucco debris flow had an estimated return period of 500  
 years.

60  
 61  
 62 After the 2003 event, the Civil Protection of the Friuli-  
 63 Venezia Giulia region started works on new mitigation  
 64 measures. Figure 2 shows the changes made at the Abitato  
 65 Cucco area. A small retention basin was constructed at the  
 66 upper part with a 10 m deep retention dam in the middle-  
 67 section, followed by a channel with a series of culverts  
 68 leading to the Fella River. Two houses were relocated due  
 69 to this adjustment.

## Numerical Runout Modelling and Back Analysis

70 The Abitato Cucco debris flow was back-analysed by  
 71 Calligaris and Zini (2012) with the commercial Flo-2D  
 72 software. They used a 5 m DEM acquired from a pre-event  
 73 laser scanning. Then an attempt was made to forward-  
 74 predict a debris flow by manually manipulating the 5 m  
 75 DEM to simulate the new mitigation measures based on  
 76 field observations from 2007. However, after the 2003  
 77 event, thousands of cubic meters of material were removed,  
 78 which completely changed the morphology of the area.  
 79 Therefore, a new 1 m DEM was acquired in June 2008 by  
 80 the Civil Protection of the Friuli-Venezia Giulia region,  
 81 which includes the completed mitigation works. Before

t.1 **Table 1** Model parameter ranges used in the 400 simulations of the 2003 debris flow event and the best performing values obtained from the back-analysis

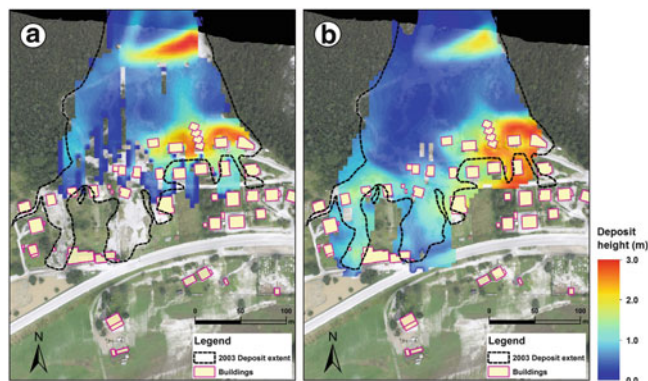
t.2	Model parameters	Ranges used	Best performing values
t.3	Release volume, $V$ ( $m^3$ )	4,000–20,000	12,000–16,000
t.4	Debris flow bulk density, $D$ ( $kg/m^3$ )	1,700–2,200	1,850–2,000
t.5	Chézy roughness coefficient, $\xi$ ( $m/s^2$ )	10–3,000	100–600
t.6	Basal friction angle, $\mu$ ( $^\circ$ )	5–50	5–15
t.7	Angle of internal friction, $\alpha$ ( $^\circ$ )	5–50	15–40

82 this DEM can be used for forward-prediction, a back-  
 83 analysis is required according to the numerical runout  
 84 model that is chosen.

85 In this study, we applied the two dimensional single-  
 86 phase MassMov2D runout model (Beguería et al. 2009)  
 87 running in the PCRaster GIS environmental modelling soft-  
 88 ware (Wesseling et al. 1996; Karszenberg et al. 2001). There  
 89 are several reasons for this choice: (1) the model runs in a  
 90 free and powerful open-source environment, (2) simulation  
 91 times are faster than other conventional runout modelling  
 92 software like Flo-2D or RAMMS, (3) different rheologies (e.  
 93 g. Voellmy, Bingham and Coulomb friction) can be applied  
 94 and compared with one another, (4) users can add their own  
 95 rheology or adjust and implement the model code to their  
 96 own needs, (5) and finally, batch-file capabilities can easily  
 97 produce hundreds or thousands of models within several  
 98 hours for model calibration, sensitivity analyses or stochas-  
 99 tic approaches. For detailed information on the description  
 100 and governing equations of MassMov2D, the reader is  
 101 referred to Beguería et al. (2009).

102 After testing different rheologies in MassMov2D, the  
 103 Voellmy rheology performed the best. The initiation volume  
 104 was represented as a block release polygon with a specific  
 105 height (m). This volume was released at the start of the  
 106 deposit zone (Fig. 1). A total of five parameters were  
 107 calibrated in the Abitato Cucco back-analysis: the debris  
 108 flow release volume ( $V$ ), the debris flow bulk density ( $D$ ),  
 109 the Chézy roughness coefficient ( $\xi$ ), the basal friction angle  
 110 ( $\mu$ ) and the angle of internal friction ( $\alpha$ ). The parameters  
 111 were systematically sampled in equal intervals and equal  
 112 probability from a very wide range to produce 400  
 113 simulations using the pre-2003 event 5 m DEM. The best  
 114 performing model parameter ranges are shown in Table 1.

115 The required debris flow initiation volume for back anal-  
 116 ysis ranged at 12,000–14,000  $m^3$ , which is slightly higher  
 117 than the original estimation of 10,000  $m^3$  made by Calligaris  
 118 and Zini (2012). According to Tropeano et al. (2004) the  
 119 bulk density ranged from 1,700 to 2,200  $kg/m^3$ , which is in  
 120 agreement with our best performing values. The Chézy  
 121 roughness coefficient was purely determined through back-  
 122 analysis results. Also, due to lack of field samples and  
 123 laboratory analysis, friction angles ( $\mu$ ,  $\alpha$ ) were approximated  
 124 from model calibrations.



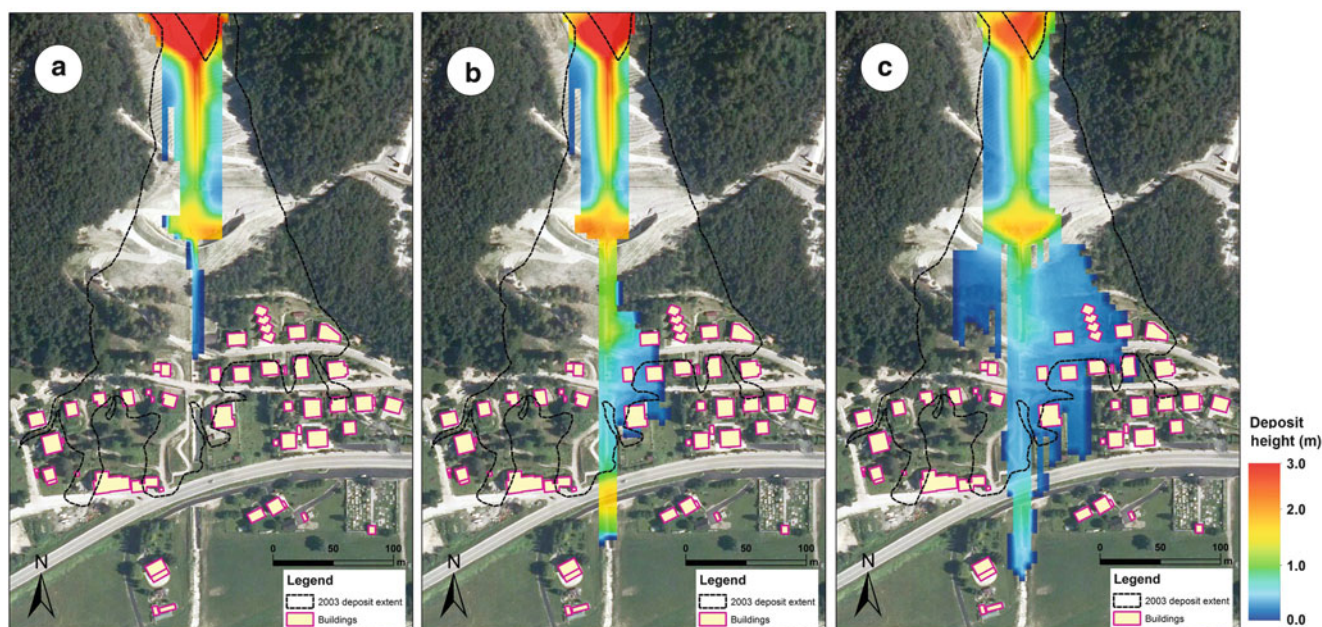
**Fig. 3** Back-analysis in 5 m resolution of the 2003 event: (a) model with the best estimation of deposit heights ( $V = 13,000 m^3$ ,  $D = 1,850 kg/m^3$ ,  $\xi = 300 m/s^2$ ,  $\mu = 10^\circ$ ,  $\alpha = 20^\circ$ ) and (b) the best performing model in terms of runout extent ( $V = 16,000 m^3$ ,  $D = 2,000 kg/m^3$ ,  $\xi = 600 m/s^2$ ,  $\mu = 12^\circ$ ,  $\alpha = 15^\circ$ )

Figure 3 shows the best two performing models in the  
 back-analysis of the 2003 debris flow. The first model does  
 well estimating the deposit height with a slight  
 underestimation of the runout distance (Fig. 3a). The second  
 model gives a more accurate runout extent but with slight  
 overestimations of deposit height at the debris flow toe, and  
 underestimates the height behind the mitigation barrier

### Forward-Prediction Modelling

Forward-prediction modelling with the latest DEM (June, 2008) was carried out first in 5 m resolution by up-scaling the 1 m DEM in order to directly compare the 2008 situation with 2003. This was followed by modelling in the original 1 m resolution in order to forward-predict the most accurate runout extent and heights. We also compared the 5 m model with the 1 m model to analyse the effect of the DEM resolution on the runout modelling.

The best performing range of parameter values in the back-analysis (Table 1) were used to carry out 100 simulations for forward-prediction scenarios using the 5 m DEM. The results of the 100 5 m resolution models can be



**Fig. 4** Examples of the three main type of forward prediction scenarios using the latest upscaled 5 m DEM (June, 2008): (a) no breaching at the retention dam ( $V = 12,000 \text{ m}^3$ ,  $D = 2,000 \text{ kg/m}^3$ ,  $\xi = 300 \text{ m/s}^2$ ,  $\mu = 10^\circ$ ,  $\alpha = 10^\circ$ ), (b) debris breaches only at the

lower channel ( $V = 12,000 \text{ m}^3$ ,  $D = 2,000 \text{ kg/m}^3$ ,  $\xi = 100 \text{ m/s}^2$ ,  $\mu = 8^\circ$ ,  $\alpha = 15^\circ$ ), and (c) breaching of the flow at the dam and lower channel areas ( $V = 12,000 \text{ m}^3$ ,  $D = 2,000 \text{ kg/m}^3$ ,  $\xi = 100 \text{ m/s}^2$ ,  $\mu = 5^\circ$ ,  $\alpha = 40^\circ$ )

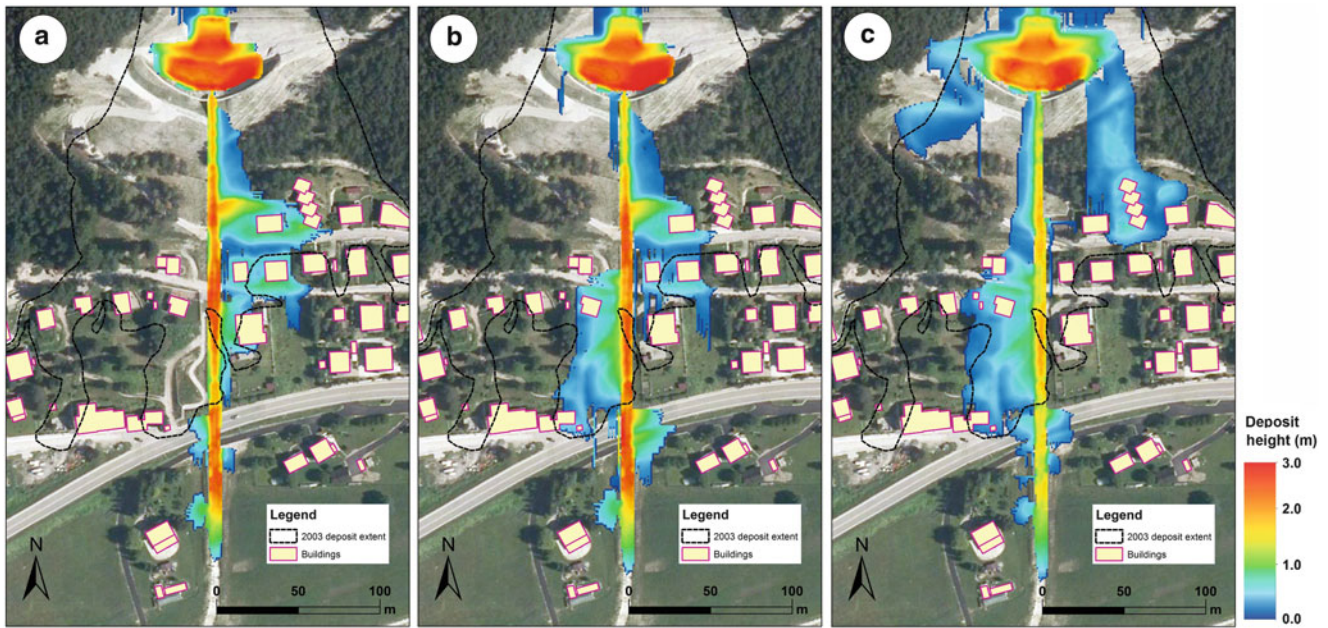
145 classified into three main scenarios: (1) no debris flow  
146 breaches, (2) breaching of the retention dam and lower  
147 channel, or (3) breaching only at the lower channel (Fig. 4).

148 All 5 m runout models show an accumulation of debris of  
149 more than 3 m at the upstream artificial basin. This indicates  
150 that the mitigation system significantly decreases the possi-  
151 bility of large debris flow heights to reach downstream. The  
152 maximum deposit height in the most extreme scenarios near  
153 the houses is no more than 0.85 m. This is a substantial  
154 decrease compared to the 2003 deposit heights of 2.0 to  
155 2.5 m. Breaching of the dam and lower channel occurs  
156 mainly towards the east side of the settlement. The western  
157 part of the settlement is almost unaffected. Scenario 1  
158 models show deposits of maximum 0.15 m on the eastern  
159 channel banks, while scenario 2 and 3 have more significant  
160 deposit heights and flow velocities. The most extreme  
161 scenarios affect approximately 8–10 houses, with scenario  
162 2 type simulations affecting a maximum of 3–4 houses.

163 A total of 50 forward-prediction simulations were pro-  
164 duced using the 1 m DEM due to time constraints of  
165 modelling in a 1 m resolution. A simulation averaged around  
166 30–40 min compared to a 3–5 min simulation time in 5 m  
167 resolution. Similar to the 5 m simulations, the 1 m models

were also categorized into scenario types. Non-breaching 168  
scenarios in 1 m resolution were less common than in 169  
the 5 m simulations. Therefore, we defined the 1 m 170  
scenarios into the following three types: (1) breaching at 171  
the east channel bank (2) breaching at both channel 172  
banks and (3) breaching at the dam and lower channel area 173  
(Fig. 5). 174

The 1 m simulations give a very different view on possi- 175  
ble scenarios due to the more accurate depiction of the dam 176  
and channel geometry. The modelled debris flows are more 177  
confined, pushing the higher deposits further downstream. 178  
The thicker deposits that stopped at the upper basin in the 179  
5 m models are now located near the retention dam in the 180  
1 m simulations. Breaches at the lower channel are much 181  
more subtle and follow better the topography, with higher 182  
deposits found near the houses next to the channel. The 183  
average outputs of both 5 m and 1 m simulations can be 184  
compared with one another in Table 2. The results show that 185  
1 m model scenarios generally affect less houses, but show 186  
higher intensity values. This is possibly due to the more 187  
confined flow in the 1 m simulations, forcing the velocity 188  
and height to slightly increase in narrower sections of the 189  
flow. 190



**Fig. 5** The three general types of forward-predicted scenarios using the original 1 m DEM (June, 2008): (a) debris flow breaching at the east channel bank ( $V = 13,000 \text{ m}^3$ ,  $D = 1,850 \text{ kg/m}^3$ ,  $\xi = 100 \text{ m/s}^2$ ,  $\mu = 10^\circ$ ,  $\alpha = 30^\circ$ ), (b) breaching at both sides of the channel ( $V = 12,000 \text{ m}^3$ ,  $D = 1,850 \text{ kg/m}^3$ ,  $\xi = 100 \text{ m/s}^2$ ,  $\mu = 8^\circ$ ,  $\alpha = 30^\circ$ ), and (c) breaching at the retention dam and lower channel ( $V = 13,000 \text{ m}^3$ ,  $D = 1,850 \text{ kg/m}^3$ ,  $\xi = 100 \text{ m/s}^2$ ,  $\mu = 8^\circ$ ,  $\alpha = 40^\circ$ )

t.1 **Table 2** Average modelled intensities and number of houses affected for all scenario types (3 scenarios in 5 m and 1 m resolution)

t.2 Forward predictions	Maximum flow height near houses	Maximum velocity near houses	Number of houses affected
t.3 Scenario 1 (5 m)	0.15 m	0 m/s	0
t.4 Scenario 2 (5 m)	0.52 m	2.2 m/s	4–5
t.5 Scenario 3 (5 m)	0.85 m	3.6 m/s	8–10
t.6 Scenario 1 (1 m)	1.05 m	3.9 m/s	2–3
t.7 Scenario 2 (1 m)	0.76 m	2.7 m/s	3–4
t.8 Scenario 3 (1 m)	0.47 m	1.8 m/s	5–6

## 191 Discussion and Conclusions

192 The limitations of forward-predicting landslide runouts  
 193 can be related to several assumptions that have been made  
 194 in this study. Forward-analysis was carried out using a  
 195 similar initiation volume as the 2003 event. However, it is  
 196 known that debris flow source areas need time to recharge  
 197 and accumulate enough sediment in order for a similar  
 198 past event to reoccur (Glade 2005). This problem can  
 199 therefore cause changes in the magnitude of a certain  
 200 return period. A thorough assessment of the source area  
 201 is required to analyse possible changes in debris recharge,  
 202 which accordingly can change the input initiation volume  
 203 for modelling.

204 Debris flow entrainment was assumed to be part of the  
 205 initiation volume. Despite the relative short distance  
 206 between source and deposit zones, entrainment can still  
 207 play a substantial role in the formation of the final deposit

heights and velocities in deposit zones (McDougall and 208  
 Hungr 2005; Hussin et al. 2012). Furthermore, the use of a 209  
 block release polygon instead of a hydrograph can have 210  
 some disadvantages. Hydrographs are able to more accu- 211  
 rately describe boundary conditions, surges and the timing 212  
 of flows reaching deposit zones (Hürlimann et al. 2003). 213

214 The DEM resolution has shown to be very significant  
 215 in modelling debris flow runouts, especially in artificially  
 216 channelized areas which are more difficult to model than  
 217 flows spreading on open slopes or debris fans. The high  
 218 resolution 1 m runout simulations show more realistic  
 219 flow scenarios, where the retention dam and channels  
 220 are more accurately defined. Differences in flow extent  
 221 and heights between the 5 m and 1 m models change the  
 222 predicted areas and houses being affected. Thus, it is  
 223 highly recommended to model debris flows in the highest  
 224 resolution possible when assessing the effectiveness of  
 225 mitigation strategies.



226 The accurate representation of different types of miti-  
 227 gation measures in a DEM can be very difficult, regard-  
 228 less of the detail or resolution of the DEM. In our work,  
 229 we assumed the culverts to be an open channel system,  
 230 simulating their inflow points by creating very small  
 231 obstacles in the channel bed. This assumption was  
 232 required due to the restriction of our chosen model.  
 233 Other models like Flo-2D are capable of modelling with  
 234 culverts, tunnels and other obstacles. Therefore, compar-  
 235 ing the two different models is planned in the near future  
 236 for our continuing research.

237 This study applied specific ranges from back-analysis  
 238 to forward-predict possible future runouts. However,  
 239 some model parameters, like the Chézy roughness coeffi-  
 240 cient, cannot be measured in laboratory or field studies .  
 241 These parameters can only be obtained by calibrating  
 242 runout models using a DEM representing the past event.  
 243 Therefore, applying back-calibrated parameters for  
 244 forward-prediction using completely different DEMs  
 245 causes a source of uncertainty in prediction outputs. We  
 246 have tried to approach this uncertainty by simulating  
 247 many runs and classifying the large amount of produced  
 248 models into several scenario types. Our approach gives  
 249 some indications of possible types of scenarios and the  
 250 number of buildings that can be affected in the future. The  
 251 application of wider parameter ranges to produce many  
 252 landslide runout simulations, results in multiple possible  
 253 scenarios. This is an indication of the importance of  
 254 acknowledging uncertainties in landslide mitigation  
 255 planning and the need to address the difficulties in  
 256 predicting residual landslide risk.

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